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AN INTRODUCTION TO THE MECHANICS OF PERFORMANCE ASSESSMENT USING EXAMPLES OF CALCULATIONS DONE FOR THE WASTE ISOLATION PILOT PLANT BETWEEN 1990 AND 1992

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ABSTRACT

This document provides an overview of the process used to assess the performance of the Waste Isolation Pilot Plant (WIPP), a proposed repository for transuranic wastes that is located in southeastern New Mexico. The quantitative metrics used in the performance-assessment (PA) process are those put forward in the Environmental Protection Agency's Environmental Standards for the Management and Disposal of Spent Nuclear Fuel, High-Level and Transuranic Radioactive Wastes (40 CFR 191). Much has been written about the individual building blocks that comprise the foundation of PA theory and practice, and that WIPP literature is well cited herein. However, the present approach is to provide an accurate, well documented overview of the process, from the perspective of the mechanical steps used to perform the actual PA calculations. Specifically, the preliminary stochastic simulations that comprise the WIPP PAs of 1990, 1991, and 1992 are summarized.
PREFACE

In broad terms, performance assessments (PAs) for the Waste Isolation Pilot Plant (WIPP) are stochastic simulations that estimate probabilistically the behavior of human-made and/or natural structures for the express purpose of comparing their performance to regulatory standards. The available literature on the WIPP's various performance assessments for the WIPP is extensive. However, relatively little has been written about the overall mechanics of the WIPP PA process itself. To help remedy that situation, the principal purpose and perspective adopted in this report have been to provide overview of the structure, form, and function of the WIPP PA process.

Purpose

The purpose of this document is to describe in overview the process used by Sandia National Laboratories since 1986 to assess the performance of the WIPP using examples of calculations from 1990 through 1992. The document also serves as a reader's guide to the tonics of more detailed information that Sandia (as scientific investigator and advisor for the Department of Energy on characterizing the WIPP) has published since 1975 on specific and related topics. Each topic treated herein is accompanied by a list of basic references on that subject. The document is also intended to serve as a primer on the performance assessment calculation process. It was the latter purpose that provided the first impetus to collect the information presented in the report. However, the former two purposes provide the motivation to set the information in writing and determined the organization and content of the report as a whole. Knowledge of the evolution of the PA calculation process and its application to the WIPP is important to fully understand the general calculational approach that will be used in the draft and final applications certifying compliance of the WIPP with regulations of the Environmental Protection Agency.

Organization

The report is divided into eight chapters. Those chapters are subdivided into sections and subsections. Most subsections consist of a single page of text that includes a reference list, and a single figure that illustrates its corresponding text. The text/figure pairs are designed to be fairly self-contained. Therefore, readers with specific interests may treat the document as a handbook or manual. Traditional readers may discover that subsections within a section provide progressively more detail about the mechanics of the process being discussed. The final subsection within each section usually describes the detailed linkage of the modularly designed computer codes used in that part of the PA process. Such information will be of interest to anyone endeavoring to understand the working details of the system, but it is probably not of interest to more casual readers.

The introductory chapter sets the stage by overviewing compliance strategy. It subdivides the various tasks of the WIPP PA process into six progressive steps and addresses the critical role of multiple iterations. The introduction also includes a brief history of the WIPP project and PA methodology. The chapters following the introduction treat the various PA tasks in the order in which they are described in the introduction, which is: Chapter 2, disposal-system characterization; Chapter 3, scenario development; Chapter 4, probability modeling; Chapter 5, consequence modeling; Chapter 6, regulatory assessment; Chapter 7, sensitivity analysis. Chapter 8, the final chapter, provides summary figures of the PA process and of the linkages among the modeling subsystems of the WIPP PA for calculations through 1992.

Using This Report

Because each subsection of the report is self-contained, the reader can easily choose the type of information to be read and the desired level of detail. A general reader seeking an overview may choose to read only the first subsection under each of the PA steps, that is, only the main headings of the report. However, a PA analyst endeavoring to learn how to contribute to or evaluate the inner workings of the PA modeling system may wish to concentrate solely on the subsections under his/her PA step of interest, with cursory forays into neighboring steps so as to understand the interfaces between his/her work and the other subsystems within the overall PA process.

Caveats

This report focuses on the calculational process used for the 1990, 1991, and 1992 WIPP PAs. The readers should not take the descriptions as an exact prescription of what will take place in future PAs. For example, changes can occur based on availability of new experimental data and improvements in the modeling process.
Preface

This report is designed for a spectrum of readers having a broad band of technical backgrounds. It is not, however, written for general nontechnical readers. General readers may find the report useful in that it provides a measure of insight into the PA process, but it also assumes some technical competency and familiarity with basic technical nomenclature. On the other hand, knowledgeable readers should not expect a definitive, step-by-step users' guide with in-depth technical bases for each of the WIPP PA codes, although the documents in which those topics are treated are referenced.

The reader should bear in mind that no single individual carried out the 1990, 1991, or 1992 annual PAs. As practiced in the United States, stochastic PAs for nuclear waste disposal system are complicated, interdisciplinary, demanding tasks that require diverse skills and a thorough understanding of myriad aspects of the physical and mathematical sciences. They start as conceptual models that must be transformed into sound theoretical, then computational, and finally applied models. To date, WIPP PAs have resulted from the well coordinated efforts by a sizable team of experienced specialists who have become experts in their specific subareas of the PA calculation.

The committed reader will want to start with the overall calculational procedure. Once that is understood, he/she should then turn to the science of the models and then endeavor to understand how all of the models interact as a system, thus endeavoring to appreciate both the microscopic and macroscopic viewpoints of the various WIPP PAs. A concise document such as this cannot promise to support that entire goal unaided. It can, however, serve as a useful introduction and guide to the inherently complex stochastic PA of nuclear waste disposal systems in the United States and to the literature that supports it.

Related Overview Documents

Readers who require additional information on the mechanics of the PA process are referred to the following overview documents:


The User's Guide to the WIPP PA Codes that is being written by W.F. Simmons and G.K. Froehlich.

The individual users' guides and corresponding technical-basis manuals for each of the modular WIPP PA codes that are under preparation.

Those seeking additional information on the results and applications of the PA process are referred to the following two sets of reports:


Note: The second of the two reports does not pertain to the WIPP Project, but it uses the same general methodology. It has the advantage of describing an entire PA calculation in one main volume (Volume 2), rather than the five or more volumes necessary to treat the WIPP.

Acknowledgments

A probabilistic PA of a disposal system like the WIPP requires many individuals having expertise covering a wide range of fields of science and technology. Without the exemplary work of this well coordinated team of dedicated researchers, the PA process could not have been brought to scientifically acceptable fruition. The summary contributions of the WIPP Project's "PA team," led by D.R. Anderson and M.G. Marietta, form the scientific basis of this document. Their work is gratefully acknowledged.
Section 1.5.1, Timeline of Events for the WIPP Project, took a great deal of effort to compile, diagram, and verify. Hugh Ho, a Sandia summer employee, Carol Crawford (13415), and Darcy Pulliam of Tech Reps, Inc., helped greatly with this task. Section 1.5.2, Timeline of Events Influencing Probabilistic Analysis of Systems, benefited greatly from interviews with M.S. Tierney, M.G. Marietta, D.R. Anderson, J.C. Helton, and J.E. Campbell; all gave graciously of their time and provided important background information on the many topics presented. Ching Wo, a Sandia summer employee, and Kathy Best of Tech Reps, Inc., also helped with this particular section.

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1.0 INTRODUCTION

In 1979, Congress authorized the U.S. Department of Energy (DOE)\* to build a research and development facility to test the safe management, storage, and disposal of wastes containing transuranic (TRU) radionuclides. The Waste Isolation Pilot Plant (WIPP) was designed and built as a full-scale pilot repository. It is mined horizontally at a depth of 655 m (2150 ft) in a thick and extensive bedded salt formation (mostly halite) 42 km (26 mi) east of Carlsbad, New Mexico. If the design proves tenable on the development facility to test the safe management, storage, and disposal of wastes containing transuranic repository. It is mined horizontally at a depth of 655 m (2150 ft) in a thick and extensive bedded salt formation (mostly halite) 42 km (26 mi) east of Carlsbad, New Mexico. If the design proves tenable on the basis of all regulatory criteria, the facility would become a permanent repository for TRU radioactive wastes produced by federal programs for the development and manufacture of nuclear weapons (transuranic refers to elements with atomic numbers greater than uranium-92). Because these wastes contain radionuclides and other hazardous constituents, such as heavy metals and volatile organic compounds (VOCs), a full suite of regulatory criteria has to be satisfied before the WIPP can be certified as an acceptable repository for federal wastes. In 1992, Congress charged the U.S. Environmental Protection Agency (EPA) to review the DOE's published findings on the WIPP and to certify whether or not overall compliance has been satisfactorily demonstrated.**

In general, the overall process of assessing whether a waste disposal system meets a set of performance criteria is known as a performance assessment (PA).\*** A PA provides important input to decisions on the safety (i.e., social acceptability of the risks) of a plan of action using a detailed procedure and scientific knowledge. For radioactive wastes, a computationally demanding set of risk-based performance criteria is specified in the EPA's Environmental Radiation Protection Standards for Management and Disposal of Spent Nuclear Fuel, High-Level and Transuranic Radioactive Wastes (40 CFR 191).\*They are specific, quantitative criteria that specify probabilistic limits that must be met for the first 10,000 years of operation of a waste repository. Clearly, it is not sufficient to develop an accurate scientific understanding of the current status of a disposal system. Rather, calculations illustrating possible behavior well into the future are required. Consequently, a PA is carried out on a suite of models that represents and illustrates the disposal system's present and future behavior, and the assessment is through computer simulation. The physical, chemical, and geological processes that determine the behavior and evolution of the site are complex and often highly nonlinear. Accordingly, the models that describe the processes are themselves complex and often technically sophisticated.

This document describes in overview the procedural steps that comprise a WIPP performance assessment. Specifically, it treats the 1990, 1991, and 1992 PAs,\* which were evolutionary in nature, each building on and extending the scope and results of the ones before. The 1990 PA highlighted the backbone of the assessment modeling system, the so-called Compliance Assessment Methodology CONtroller (CAMCON). The CAMCON system is the central information-transmission and quality-assurance system to which PA computational and utility codes connect, and through which they communicate. It served as the central utility code for the subsequent PAs in 1991 and 1992.\* With CAMCON in place, the 1991 PA featured a complete suite of computational components and highlighted the documentation. With a complete array of working models in place, the 1992 PA used improved field

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\* The U.S. Department of Energy was formed in 1977 by the Department of Energy Organization Act (Public Law 95-91, 912 Stat. 565). It replaced the Energy Research and Development Agency (ERDA). ERDA was formed by the 1974 Energy Reorganization Act (Public Law 93-438) and replaced the Atomic Energy Commission (AEC), which was formed in 1946 (Public Law 585, August 1, 1946, 60 Stat. 755).

\** The WIPP is not regulated by the Nuclear Regulatory Commission (NRC).\* (See also Section 1.5.1, Timeline of Events for the Waste Isolation Pilot Plant.)

\*** This general definition of a PA is used herein. However, the 40 CFR 191 regulation defines a performance assessment as an analysis for comparison with the Containment Requirements of 40 CFR 191: specifically, an analysis that identifies the processes and events that might affect the disposal system, examines the effects of these processes and events on the performance of the disposal system, and estimates the cumulative releases of radionuclides, considering the associated uncertainties, caused by all significant processes and events. Concerning these events, Appendix C of 40 CFR 191 states that the most severe anthropogenic event to consider is human intrusion into the repository from exploratory drilling.

\* As noted in the preface, because of changes instituted by the DOE in response to the Waste Isolation Pilot Plant Land Withdrawal Act (Public Law 102-579) and changes introduced by the Secretary of the Department of Energy to accelerate the regulatory compliance program, the information in this document may not apply to future PAs.
1.0 Introduction

data and highlighted both the conceptual and refined computational models that had been developed to
comprise the WIPP PA modeling system.\footnote{An early 1989 PA highlighted the methodology to be used in the following years.\footnote{\cite{14}} However, the modeling system used was only a prototype of the one used for the later PAs. Consequently, the PA mechanics described in this document do not apply to the 1989 PA.}

The EPA's official guidance concerning the nature of performance assessments (50 FR 38066)\footnote{\cite{3}} suggests a PA in the United States requires a stochastic simulation of the possible long-term behaviors of a real system based on computer-implemented mathematical models of that system. In that respect, WIPP PAs are similar to other, perhaps more familiar, large-scale stochastic simulations such as the Reactor Safety Study.\footnote{\cite{11,12}} These large-scale simulations have been used by federal agencies to explore policy options and to develop regulatory criteria.\footnote{\cite{13}} However, unlike those simulations, PA results are not intended merely to gain insight into the behavior of a system for purposes of rational bases for governmental policy or regulatory standards. Rather, they are used to test the compliance of a real system (i.e., the WIPP) with environmental standards. But bear in mind, PAs are not truly predictive, but rather illustrative calculations for comparison to regulatory measures. Thus, not only are the PA results themselves of critical importance, but also equally important are the uncertainty analyses that accompany them. The quantitative analysis of uncertainty in PA calculations is not just good scientific practice, it is strongly suggested as necessary by EPA regulations. Moreover, a disposal system cannot be analyzed and assessed piecemeal. By federal regulation, all results must be combined to form an "overall probability distribution" whenever practicable.

Use of a stochastic simulation to quantitatively evaluate uncertainty is only one of several constraints that complicate PAs. Modeling problems are often compounded by the inherent characteristics of the disposal system itself. The principal elements of geological waste-disposal systems are natural materials, that is, stratified layers of soils, sands, clays, rocks, salts, and other minerals that have been deformed and worked for millennia by tectonic, hydrological, and climatic forces. The distribution and physical and chemical characteristics of these natural components are not well known, usually inhomogeneous, anisotropic, and temporally variable on scales that are difficult to characterize thoroughly.

Correspondingly, the EPA has acknowledged explicitly that a performance assessment, being an indirect demonstration or illustration of possible future conditions, need not provide complete assurance that performance requirements will be met. Quoting from 40 CFR 191, "Because of the long time period involved and the nature of the events and processes of interest, there will inevitably be substantial uncertainties in projecting disposal-system performance. Proof of the future performance of a disposal system is not to be had in the ordinary sense of the word in situations that deal with much shorter time frames. Instead, what is required is a reasonable expectation, on the basis of the record before the implementing agency, that compliance with 191.13(a) (Containment Requirements, see Sections 6.1.2 and 6.1.3) will be achieved."

This document presents a condensed overview of the overall calculation procedure for assessing the performance of the WIPP for 10,000 yr. It endeavors to present the system at several levels of technical sophistication so as to be useful to readers with a broad spectrum of technical backgrounds. To make that possible, the physics, chemistry, and mathematics of the WIPP PA models have been described only functionally. The nuances of the various natural phenomena treated in the WIPP's scientific models have been intentionally omitted so as to save the overview reader from inevitable and considerable technical encumbrances. These nuances are treated extensively in the referenced documents. Technical manuals describing each of the WIPP codes are presently in preparation. They are scheduled to appear some time during 1995 and 1996. Readers should regard them as additions to this document's list of references.

In addition to providing a general overview of the PA process, this document may be used as a guide to the extensive and more detailed WIPP scientific literature. Each subsection of the body of the report includes an abbreviated reference list that gives the principal scientific references related to the topic treated in that subsection. In addition, readers having access to the WIPP codes, the required computational hardware, and the desire to run them are referred to the Users' Guide to the WIPP PA Codes that is currently being written and may be regarded as a companion volume to this document for serious technical readers.

The remaining sections of this introduction describe (a) Sandia's overall strategy for evaluating the WIPP in terms of the various environmental regulations and the multiple-iteration technique used to improve the quality of the PA (Section 1.1), (b) the general steps that comprise Sandia's PA process (Section 1.2), (c) the types of uncertainty that arise in a PA (Section 1.3), (d) the terminology pertinent to a
The organization of the remainder of the report follows the steps of a performance assessment as they are described in Section 1.2. Each section of a chapter explains one aspect of that chapter, and each subsection of that section offers increasing detail on the PA process being discussed. Thus, the final subsection of each section usually describes the detailed linkage of codes used for that portion of the PA process code linkages that are clearly of interest to readers endeavoring to master the operational details of the process. However, they are probably not of interest to the casual reader. Thus, a reasonable strategy for approaching this document is to obtain a general overview of the PA process by skimming the text of the main chapter headings (denoted 1.0, 1.2, ..., 2.1, 2.2, ..., 3.1, ...) and then studying the text and figures of the subsections (denoted 1.1.1, 1.1.2, 1.2.1, 1.2.2, 1.3.1, ...).

References


1.0 Introduction

1.1 40 CFR 191 - Based Compliance Strategy

The Environmental Protection Agency (EPA) standard, "Environmental Radiation Protection Standards for Management and Disposal of Spent Nuclear Fuel, High-Level and Transuranic Radioactive Wastes" (40 CFR 191), requires extensive computations of a probabilistic nature to illustrate the performance of the disposal system of the Waste Isolation Pilot Plant (WIPP). Thus, it provides the incentive for the development of the modeling methodology and associated analysis tools devised and compiled by Sandia National Laboratories to evaluate the long-term behavior of the WIPP disposal system. That methodology, with modifications, also serves to assess compliance with other environmental regulations and laws concerned with long-term release of nonradioactive contaminants, such as the regulations of the Resource Conservation and Recovery Act of 1976 (see Chapter 6.0, Long-Term Regulatory Assessment).

Essentially, the EPA standard 40 CFR 191 specifies the required safety of a geologic disposal system, that is, the risk from the WIPP that is acceptable in the United States. In turn, risk is the potential that some unwanted loss may occur. Although 40 CFR 191 does not directly use that risk to human health as a criterion, its requirements are related to health risk. Specifically, the individual protection requirements set limits on radionuclide doses to humans, and the containment requirements set limits on (a) radionuclide releases and (b) on the probability that such releases will occur. Because 40 CFR 191 explicitly recognizes the uncertainty of scientific explanations, uncertainties associated with the WIPP modeling process must also be quantified to the extent possible (see Chapter 6.0, Long-Term Regulatory Assessment).

Sandia's overall assessment approach was developed simultaneously with early drafts of 40 CFR 191, so as to evaluate early options for regulating deep, geologic repositories. Sandia's approach to assessment modeling benefited further from its scientific participation in earlier studies of the feasibility of subseabed disposal of radioactive wastes in deep-ocean sediments. Those studies were conducted under the auspices of the Nuclear Energy Agency of the International Organisation for Economic Co-Operation and Development. Sandia used information from these exploratory analyses to guide the development of performance assessment techniques for the WIPP.

Attention is called to two important aspects of the compliance strategy of the WIPP, namely: (1) the use of a detailed modeling style, and (2) multiple iterations performed to improve assessment quality. These aspects are described further in the two subsections that follow.

References


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Note: An alternative compliance strategy might have been to start by implementing the RCRA regulations because they include well-defined legal steps (e.g., applications, hearings, etc.). However, the RCRA regulations are less demanding of the models. Furthermore, these regulations were the last to be applied to the WIPP and so their influence is not as strong (see Section 1.5.1, Timeline of Events for the WIPP Project).

** To arrive at a quantifiable risk (or a risk-related measure) requires describing what may happen, quantifying the probability of some unwanted loss happening, and quantifying the loss (see Section 1.2.2, Performance Assessment as an Ordered Triplet). Although not done here, authors frequently define risk as the product of the loss (consequence) and the probability of the loss. Herein the loss and the probability loss for various happenings (scenarios) are paired to form the complementary cumulative distribution function (CCDF) (see Section 1.3 and Chapter 6).
1.0 Introduction

1.1.1 The Modeling Style of the PA for the WIPP

The general definition of performance assessment (PA)—a process of assessing whether a system meets a set of performance criteria—is easy to understand. Even the six general steps of a performance assessment for a waste disposal system described in Section 1.2 are easy to comprehend because, in general, the steps are tied to the process of building scientific models. It is the approaches within these six steps that were used for analyzing the Waste Isolation Pilot Plant (WIPP) from 1990 through 1992 that this report seeks to illuminate.* In this report, the guiding philosophy used to construct models is termed "modeling style." Examples of modeling style include the following: the type of natural and anthropogenic phenomena considered, assumptions of symmetry and dimensionality of the conceptual model, and density of spatially varying data. The modeling style, in turn, is dependent upon the type of system, the performance criteria, and the available assessment technology. Different modelers approach and frame modeling problems differently. For the geologic disposal systems in general, and the WIPP in particular, modeling style was determined by Sandia scientists and engineers. Important influences on this style were congressional policies set forth in laws (e.g., NEPA1 and the WIPP Land Withdrawal Act2) and regulations of the Environmental Protection Agency (EPA) implementing these laws (e.g., 40 CFR 191). Future influences will be determined by the EPA as they review the WIPP compliance application (e.g., 40 CFR 194). For example, 40 CFR 191 specifies performance criteria for 10,000 yr, therefore, the system is necessarily a mathematical model. Furthermore, 40 CFR 191 uses a probabilistic performance criterion for assessing compliance and requests an applicant display the results of the analysis as a "complementary cumulative distribution function" (CCDF).

The modeling style adopted must be adequate to provide the EPA with "... a reasonable expectation ... that compliance will be achieved." In the calculations through 1992 for assessing the safety of the WIPP, Sandia adopted a detailed* modeling style (i.e., a style that included phenomenological details and often multiple dimensions in the model, and avoided simplified or conservative models and/or parameters unless required data or knowledge was not available***). Certainly, an important reason for using a detailed modeling style was the general acceptance in the United States of using detailed probabilistic risk assessments (PRAs) for nuclear regulatory matters; PRAs were used because of the pioneering work in 1975 in the Reactor Safety Study5 that was the backdrop for the development of 40 CFR 191 in the late 1970s and early 1980s. Similarly, Sandia also used detailed models in the major update of the Reactor Safety Study6 and in the process of examining deep seabed disposal of nuclear waste.7 Also, a detailed modeling style has been proposed as policy by the Nuclear Regulatory Commission.8 Furthermore, early comment received from the EPA9 and the WIPP Panel of the National Academy of Science encouraged Sandia to continue using a detailed modeling style (at least for preliminary assessments when determining general understanding of the disposal system).

The principal advantage of the detailed modeling style is that it provides a sufficient level of realism (1) to provide general scientific understanding of the WIPP disposal system over 10,000 yr, (2) to explore many potential sources of uncertainty, and (3) be able to tie any lack of understanding or sources of uncertainty directly to measurable quantities, should they be important to study further in other modeling iterations. The major self-imposed constraint on the amount of detail and what type of phenomena to include was Sandia's desire to perform an entire performance assessment each year to obtain the benefits of performance assessment iterations (see Section 1.1.2, Multiple Iterations: a Performance Assessment Strategy).

* Should the myriad details presented throughout the remainder of the report become confusing, recall that the structure of the report is such that much can be gleaned about the modeling style by reading the major sections rather than the many subsections.

** A frequently used term is "realistic," but even realistic models are models nonetheless, and only mimic nature; thus, the term is avoided in this report.

*** Although not adopted for preliminary assessments of the WIPP, the use of simple and often conservative models and/or parameters to give conservative results can be a convincing approach to use in a compliance application; thus, this is one aspect that can change from the preliminary assessments discussed in this report and future compliance applications.

† Science is a consensual human endeavor, but consensus on scientific issues can take many years to form; thus, scientific consensus that all potentially important knowledge that could be obtained about the site had indeed occurred was certainly desired but was not a goal.
References


1.1.2 Multiple Iterations: a Performance Assessment Strategy

The strategy of conducting sequential performance assessment (PA) iterations (see Figure 1.1-2) is beneficial because each iteration provides enhanced information about the disposal system in precisely those areas where it is required. Initially, available data and supplementary information are used to develop preliminary scenarios. These are analyzed with simple models and produce preliminary results, which may be but simple bounding values. If these initial results are either indefensible or indecisive, better data, more complete conceptual models, and more realistic computational models are sought and used in subsequent calculations. By repeating this process iteratively, engineers and scientists can replace weak links in the simulation chain and, eventually, devise defensible, definitive calculations on which intelligent decisions about radioactive waste disposal at the Waste Isolation Pilot Plant (WIPP) can be made.*

In addition to assuring the overall goal of producing defensible calculations, multiple PA iterations achieve six other goals, as follows:

- The analysis team focuses on the expectations to both the customer (purchasers of PA, i.e., the Department of Energy [DOE]), regulators (e.g., Environmental Protection Agency), and the stakeholders (agencies and individuals with internal and possible desire to impact PA). Moreover, the customers, regulators, and stakeholders can become involved in the PA process. These iterative interactions facilitate decisions that must be made by more than one person or agency over long periods of time, e.g., nuclear waste disposal decisions.
- Because different performance hypotheses can be tested, analysts develop insight as to the behavior of the disposal system.
- Through periodic peer reviews, analysts receive invaluable scientific feedback that can provide new approaches, and insights, as well as new interactions for multidisciplinary teams.
- In instances where critical questions can be posed, early analyses can sometimes be partially validated in later iterations based on more advanced models or newly collected data.
- Through sensitivity analyses on the results of simplified preliminary systems, project managers and the participants can decide intelligently how best to allocate resources for supplementary data collection and whether models should be elaborated or simplified.
- The WIPP PA, which is a large, long-term project, can be divided into several smaller parts, each with more easily agreed upon constraints and schedules. The PA becomes a series of smaller projects repeated and refined several times—a useful technique, providing a quality product.

References


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* Sandia's PA Department performed annual iterative PAs of the WIPP from 1989 through 1992. Along with the iterative PAs, the DOE intended to perform in situ experiments on actual waste at the WIPP. However, circumstances associated with the in situ experiments caused the DOE to decide in October 1993 to (1) eliminate in situ experiments at the WIPP, (2) perform any necessary experiments with waste above ground away from the WIPP, and (3) implement an accelerated regulatory compliance program that included preparing a draft application for certifying compliance of the WIPP as a means to begin discussions with the Environmental Protection Agency (EPA) (see Section 1.5.1, Timeline of Events for the WIPP Project). The latter decision required the curtailment of the annual PAs performed by Sandia.
Figure 1.1-2. Multiple performance assessment iterations. In addition to clarifying general issues to groups outside Sandia, multiple iterations of performance assessments can help develop scientific consensus on issues important to the performance assessment. Feedback to investigators performing disposal-system characterization is shown as an example. (Rechard et al., 1992a, Figure 1-2).
1.0 Introduction
1.2 The Six Principal Steps of Performance Assessment

In this report, performance assessments (PAs) are subdivided into six principal steps, as follows:

1. **Disposal-system and regional characterization** entails data collection on waste properties, facility design, regional geology, and regional hydrology.

2. **Scenario development** identifies and selects features, events, and processes that collectively comprise the scenarios, \( S(x) \), through which contaminants might be released to the "accessible environment" as defined by the Environmental Protection Agency. It provides guidance for subsequent model development.

3. **Probability estimation** models likelihoods that the various scenarios will occur, \( P(x,S(x)) \).

4. **Consequence analysis including uncertainty propagation** calculates the potential amounts of contaminants that might be released for a given scenario, \( C(x,S(x)) \), and includes the quantitative evaluation of uncertainties associated with those predictions.

5. **Long-term regulatory compliance assessment** involves the construction of CCDFs and other performance and uncertainty metrics and their comparisons with the relevant long-term environmental regulations.

6. **Sensitivity analysis** determines the individual parameters and model forms that most influence performance metrics and thereby provides guidance to WIPP project managers on where to direct resources to further evaluate uncertainty of the parameters.

The first two performance assessment steps (see Chapters 2.0 and 3.0) are referred to collectively as "model conceptualization" in this report. The third step, probability estimation, evaluates the probability of occurrence of the various scenarios and includes the uncertainty in some of the system parameters (e.g., exploratory drilling for resources [human intrusion]) (see Chapter 4.0, Probability Estimation).

The fourth step, consequence analysis, consists of simulating the relevant physical, chemical, biological, geological, and climatological processes that could influence repository performance (see Chapter 5.0, Consequence Analysis). It is important to understand that it would take too long and cost too much to build and run a single, three-dimensional, system model that would represent the Waste Isolation Pilot Plant (WIPP) in sufficient detail to simulate all the events and processes that affect its performance. Consequently, a suite of interconnecting submodels is used as the system model. Each submodel simulates one of the WIPP's principal physical components. A "consequence model" is, thus, not a single model, but a suite of many submodels that interface through CAMCON. This so-called "modular" approach to consequence modeling is well suited to model development and refinement. To treat parameter uncertainty, system parameters are sampled probabilistically, and the model is exercised many times over to yield a suite of realizations illustrating the possible performance of the system.

The fifth step involves calculation of performance metrics such as cumulative release over 10,000 yr, or individual dose. Metrics are evaluated and compared to established regulatory performance criteria (see Chapter 6.0, Long-Term Regulatory Assessment).

In the final step, sensitivity analysis, the quantitative systemic effect of externally imposed variations in selected individual parameters \( x_n \) is assessed in terms of predicted consequences or the probabilities of their occurrence (see Chapter 7.0, Sensitivity/Uncertainty Analysis).

The following subsections describe the general component of the six steps and then introduce several underlying concepts of PAs.

References


1.2.1 Components of the Six Performance Assessment Steps

Figure 1.2-1 displays the various components (shown as boxes) of the six performance assessment (PA) steps and the flow of information through these components. The information flow is normally sequential and usually follows the general order shown. However, in part because of the modular nature of the PA system and in part because of its exercise through multiple iterations, system characterization and the development of scenarios, probability models, and consequence models can occur concurrently with consequence modeling. The system is modular and dynamic, and development is an ongoing process. One component of the probability modeling step, estimates of probability, is normally postponed and calculated concurrently with the construction of performance metrics (complementary cumulative distribution function) during the regulatory assessment step.

Although the location and flow of information is generally as depicted in Figure 1.2-1, it is important to realize that discrete boxes were selected more for illustrative purposes than for their absolute accuracy in representing PA organizational subdivisions and the flow of information. In fact, the boundaries between many of the subdivisions are fuzzy, and subareas can overlap to a great extent. For example, gathering new input data might be categorized equally well as site characterization or model parameter compilation. Moreover, the distribution of tasks among the depicted components is not unique, in part because the process of performing the specific tasks is more continuous than discrete. Despite its inherent deficiencies, the figure remains a useful tool in describing the complex operational nature of the PA process.

Note that the bottom-most box of Figure 1.2-1 is connected via an upward-pointing arrow to the top-most boxes, suggesting the iterative nature of the PA process. Iterative refinement is not confined to the entire PA (once per year between 1989 and 1992), but it may occur more frequently over many of the subprocesses. For example, inner iterations frequently occur during disposal system characterizations. A particularly important “inner” iteration is the appropriate assignment of parameters and uncertainties to fit the scale and detail of the models chosen for the PA analysis, given the facility design and knowledge of the character of the site (see Chapter 3.0, Scenario Development).

The individual components shown in Figure 1.2-1 are discussed in greater detail in subsections of this report. The figure is repeated at the beginning of each chapter and the components treated in that chapter are highlighted in boldface.

Reference

1.2 The Six Principal Steps of Performance Assessment

**Figure 1.2-1.** Components of the six general steps of a performance assessment.

- **Inner Iterations**
  - Character of Site
  - Properties of Waste
  - Design of Facility
  - Detailed Modeling of Phenomena*
  - Selection of Features, Events, and Processes
  - Modeling System Selection
  - Assignment of Parameter Uncertainty
  - Estimates of Probability
  - Compilation of Model Parameters
  - Modeling of Groundwater Flow
  - Modeling of Groundwater Transport
  - Modeling of Biosphere Transport
  - Modeling of Facility*
  - Modeling of Repository

**Iterations through PA**

- **Disposal System and Regional Characterization**
  - Scenario Development S(x)
  - Risk Triplet
  - Consequence Analysis Including Uncertainty Propagation C[x,S(x)]
  - Long-term Regulatory Assessment
  - Sensitivity/Uncertainty Analysis

**Comparison with**

- 40 CFR 191.73
- 40 CFR 191.24

**Calculation of System Parameters**

- National Environmental Policy Act (NEPA)
- Evaluation of Statistical Correlations

* Examples not included in this report
1.0 Introduction

1.2.2 Performance Assessment as an Ordered Triplet

A revealing description of the performance assessment (PA) task (see Figure 1.1-2) arises if the risk-based performance criteria of the Containment Requirements in 40 CFR 191 (see Section 6.1.3, Containment Requirements) are viewed as a set of ordered triplets, each triplet consisting of answers to the following three questions:\(^1\)\(^2\)

- What can happen? [hereafter called scenarios, \(S_j(x)\), where \(j = 1, 2, \ldots, n_S\)].
- How likely are these things to happen? (probabilities of scenarios, \(P[x, S_j(x)]\)).
- What are the outcomes of these happenings? (consequences of scenarios, \(C[x, S_j(x)]\)), where \(x\) represents all the numerical parameters required to quantify the applied model, and \(n_S\) is the number of scenarios to be included.

The first question is answered via the scenario development process (see Chapter 3.0). Part of scenario development consists of selecting features, events, and processes from a general list to create a set of plausible occurrences that specify what might happen to the disposal system in the future. These are denoted \(S_j(x)\), where \(j = 1, 2, \ldots, n_S\). The second question requires a modeling system capable of estimating the probability \(P[x, S_j(x)]\) that the \(j\)th scenario will occur. The third question requires several modeling systems capable of estimating the consequences of each of the \(n_S\) scenarios, \(C[x, S_j(x)]\) \(^3\) (see Chapter 5.0, Consequence Analysis). For a given scenario, a complementary cumulative distribution function (CCDF) displays as a single curve the second and third elements, that is, the consequence and the probability of that consequence occurring (see Section 6.1, Environmental Protection Agency 40 CFR 191 Simulations, and Section 1.3.1, Propagating Uncertain Parameters (Epistemic Uncertainty) through Consequence Models). For \(n_S\) scenarios, there will be \(n_S\) CCDF curves. Uncertainty in the calculation of the CCDF can arise from uncertainty in any of the three elements of the triplet (scenario selection, probability model form, consequence model form) or in the underlying numerical parameters characterizing the system (\(x = x_1, \ldots, x_{n^p}\), where \(n^p\) is the total number of parameters required).\(^4\) Evaluations of predictive uncertainty that cannot be derived quantitatively may be derived qualitatively by expert judgment (see Section 4.1, Assigning Parameter Uncertainties).

References


\(^1\) In evaluating compliance, a suite of \(n_S\) consequences, \(C[x, S_j(x)]\), where \(j = 1, 2, \ldots, n_S\), is produced, one for each scenario. These may then be combined into a single performance metric, denoted \(R\) (see Section 6.1, Environmental Protection Agency 40 CFR 191 Simulations and Figure 1.1-2).

\(^2\) The transition from three parts of stochastic simulation to the three components of the PA triplet is discussed in Section 1.2.3. See also Section 8.1, Concise Review of the Six-Step Performance Assessment Process.
1.2 The Six Principal Steps of Performance Assessment

Risk Triplet

\[
\left\{ S_i(x), P(x, S_i(x)), C(x, S_i(x)) \right\}_{j = 1, \ldots, nS}
\]

- Scenarios (Chapter 3)
- Probability of Scenarios (Chapter 4)
- Consequences of Scenarios (Chapter 5)

These two terms plotted as:
1) Probability density function (PDF)
2) Cumulative distribution function (CDF)
3) Complementary cumulative distribution function (CCDF) (Chapter 6)

Figure 1.2-2. The ordered triplet of a performance assessment.
1.0 Introduction

1.2.3 Stochastic Simulations

Three elements are required to evaluate the statistical properties of the outcomes of a model (a stochastic simulation). They are (1) a parameter space, $D_n$, for a model composed of $n$ parameters, (2) a joint probability distribution for the uncertain parameters, $F(x)$, and a complete system model, $C$ (see Section 1.2.4, Model Development). For parameters that are statistically independent, the joint probability distribution is equivalent to the product of the probability distributions of the individual parameters $F(x) = F_1(x_1) \cdot F_2(x_2) \cdot \ldots \cdot F_n(x_n)$ (Figure 1.2-3).

Usually for the practical application of stochastic simulation for a large structured probabilistic analysis, several steps are made to arrive at a risk triplet (as described in Section 1.1.2). First, the parameter space, $D_n$, is divided into disjoint sets that form scenarios—i.e., a scenario space (see Chapter 3.0). The partition of the parameter space, $D_n$, into scenarios is somewhat arbitrary and depends on the purposes of the analysis. Ideally, those parameters whose variability can be classified epistemic (related to precision of knowledge) and thus describable by a distribution remain in the parameter space. Those parameters that are aleatoric (related to chance) describe chance features or events, such as an inadvertent human intrusion, and can be used to define individual scenarios. For the partition of the parameter space to be practical, the probability of each disjoint occurring set must be calculable by a probability model, $P$, which is devised in the second step. The description of the distributions of the parameters remaining in the parameter space is also part of the second step. (The description of the distribution is usually through a subjective probability model, see Section 4.1). The third step is to evaluate the distribution of the results, $C[k, S_i(x)]$, from the complete system model, $C$. The most common way is through random sampling (see Section 1.3). This information is then displayed as a complementary cumulative distribution function (CCDF) (see Section 1.3.1).

Although identical in theory, any structured probabilistic analysis can differ in the emphasis and assumptions made in the three simplifying steps described above. A probabilistic risk assessment (PRA) for a nuclear power plant and a performance assessment (PA) for a nuclear waste repository demonstrate the different emphasis possible. To elaborate, in a PRA many events can be postulated from numerous phenomena that are threaded together in event tree that forms scenarios. The probability of the phenomena is often evaluated through a large fault tree that because the failure phenomena are short-term events (i.e., the duration of the phenomena in relation to the regulatory period of 40 yr is very short), and measured failure rates of components are often available. Consequences of the most probable events are then modeled, often using extensive empirical data that can substitute for mechanistic models. In a PA, the event tree is simpler. The event tree defining the few scenarios is often related to unknown human or geologic behavior far in the future, thus, their probability of occurrence is evaluated with simple analytic functions. Fault trees are usually not used because the phenomena of most interest, possible change of the initially stable environment of the repository, occur over geologic time scales of the same relative duration as the regulatory period (10,000 yr or longer). The consequences of the various phenomena are evaluated directly in a large system mechanism that involves wide uncertainty because direct observation of the phenomena of interest cannot be obtained over the time scales of interest.

References


* The reader should realize that although the differences between these two categories can be subtle and that the classification of some model parameters may be somewhat nebulous, the distinction has been recognized and used in the scientific community for many years (e.g., see Chernoff and Moses, 1959, p 1).²

** Herein, a PRA refers to a system composed solely of human-engineered components and performance criteria that include risk to health over a short time (e.g., human lifetime) relative to geologic time. Whereas, a PA refers to a system composed of both natural and engineered components that include performance measures such as dose to individuals or cumulative releases over geologic time.
Stochastic simulation consists of three components.

1. Parameter space of model, \( D_{nv} \)
   (see Chapter 3).

2. Joint probability density function, \( F(x) \)
   where
   \[ F(x) = F_1(x_1) \cdot F_2(x_2) \cdots \cdot F_n(x_n) \]
   (see Chapter 4).

3. Model of complete system, \( C \)
   (see Chapter 5).

For PA or PRA, three steps are made to arrive at risk triplet \( \{ S_i(x), P_i(x, S_i(x)), C_i(x, S_i(x)) \} \)
(see §1.2.2).

1. Divide parameter space into subsets (scenarios)
   (see §3.2).

2a Assuming the components of \( F(x) \) are independent, take random samples of each individual distribution e.g., \( F_n(x_n) \) (see §4.1).

2b Develop and evaluate probability models of scenarios
   (see §4.3).

3. Run complete system model using parameters for scenarios \( S_1, S_2, \ldots \)
   (subsets of \( D_{nv} \))
   (see §1.3.1 and Chapter 5).

For PA, usually
1. Not many scenarios, \( S_i \)
2. Probability model, \( P \), composed of simple analytic functions
3. Model, \( C \), incorporates many physical phenomena of gradual change of system.

For PRA, for nuclear reactor study, often
1. Many scenarios, \( S_i \)
2. Probability model, \( P \), can be evaluated by fault trees
3. Model, \( C \), incorporates much empirical evidence from operation of facility (e.g., pump failure rates)

Figure 1.2-3. Three components of a stochastic simulation and their translation into the ordered triplet of a WIPP performance assessment, with comparison to a probabilistic risk assessment of a nuclear reactor.
1.2.4 Model Development

As previously stated, performance assessments (PAs) are designed to determine whether a system meets a set of performance criteria. Because the Waste Isolation Pilot Plant's (WIPP's) performance criteria must be applied over a 10,000-yr period, it is necessary to apply them to a model of the system, not the system itself. Hence, the process of performing a PA is intimately tied to the process of building models. Obviously, that model must be capable of representing the "real-world" disposal system in those aspects that pertain vitally to waste-disposal performance. Model development normally occurs in several steps (see Figure 1.2-2), and uncertainties are generated at each step. For example, there is scientific uncertainty associated with model selection and degree of simplification. Four principal model types are recognized, as follows.

A conceptual model is the set of hypotheses and assumptions about the physical characteristics of a system (e.g., aquifer structure, boundaries, or boundary types) and the phenomena that ensue there (e.g., single-porosity darcy flow) that describe, in terms of scientific postulates, the behavior of pertinent aspects of that system. A diagram that represents the geology of a region as simplified stratigraphy or a paragraph of text that describes a phenomenon are examples of conceptual models. For WIPP PAs, conceptual models provide the foundation for subsequent model-development steps.

A mathematical model is the mathematical description of the conceptual model. It might include algebraic, ordinary differential, partial differential, or integral equations characterizing accepted conservation laws (e.g., conservation of mass, energy, or momentum) as well as appropriate constitutive equations that describe material behavior in the domain of the conceptual model. These equations are augmented by boundary and initial conditions of the dependent variables.

A computational model is the solution and implementation of the mathematical model. The solution be analytical, numerical, or empirical. Analytical solutions are, in principle, possible, but in the WIPP, they are rare. Empirical models use data directly by means of lookup tables or statistical relationships and are normally used to propagate information into data-sparse regions between discrete points where observational data are available. In the WIPP, solutions are almost universally implemented via numerical techniques on computers and consequently the computational models are often called computer or numerical models.

An applied model is the analyst's application of a computational model to a particular system using appropriate values. Computational models are generic by nature. They cannot be used until all parameter values, boundary values, initial values, and discretizations of time and space have been specified. The solutions they provide apply only to particular values used. For the WIPP, the system in question is the WIPP waste disposal site, and the applied models are sometimes referred to as site-specific models.

References


Alternatives in model form may exist at each stage of model development. Alternatives at the first stage of model development (alternative conceptual models) are often of greatest concern. Specifically, alternative conceptual models are multiple working sets of hypotheses and assumptions of a system that are all scientifically acceptable (i.e., consistent with the purpose of the model, with one another, and in agreement with existing facts and observations).

Verification of a (computational) model is the process of assuring that model appropriately solves and implements the mathematical model. In other words, model verification is the process of illustrating that the mathematical model is being solved appropriately.

The assumptions underlying the model system should also be validated using system-specific data (see "applied model" above). The validation of an applied model is the ongoing process of assuring that corresponding conceptual, mathematical, computational, and applied models describe the given "real-world" system with sufficient validity and soundness, consistent with the purposes of the model.
1.2 The Six Principal Steps of Performance Assessment

Actual Environment
(briefly introduced in § 2.0)

Conceptual Model(s)
(Set of Hypotheses about System)
(briefly introduced in § 3.2)

Mathematical Model
(Mathematical Representation of
Conceptual Model
briefly introduced in § 5.0)

Computational Model
(Typically Mathematical Model
Solved Numerically and
Implemented on the
Computer)
(not discussed in this report)

Applied Model
(Application of Computational Model)
(briefly introduced in § 5.0)

Equations and Boundary Conditions
\[
\begin{align*}
\frac{\partial h}{\partial t} &= V \cdot (K \cdot \nabla h) - W \\
\frac{\partial h}{\partial n} &= 0 \text{ on the boundary}
\end{align*}
\]

CAMCON Codes
(Fortran Lines of Code)

Mesh & Boundary Conditions

Velocity Field

Figure 1.2-4. Hierarchy of model development selection of features, events, and processes to include and corresponding methods of modeling (i.e., selection of form of model[s]) (after Rechard et al., 1992a, Figure 1-6).
1.3 Types of Uncertainty in Performance Assessments

Three major sources of uncertainty arise in performance assessments (PAs) of geologic disposal systems. They are (1) parameter uncertainty, that is, uncertainty in the parameters of an applied model (where a "parameter" is an underlying fundamental entity (e.g., number) required by an applied model, whereas "data" are the information collected in the field or elsewhere, organized, and used in preparing parameter values); (2) scenario uncertainty, that is, uncertainty as to the most appropriate features, events, and processes to include in scenarios and the most appropriate way to group the features, events, and processes for modeling; and (3) model form uncertainty, that is, uncertainty about the hypotheses and the appropriate model forms and, of course, uncertainty regarding the adequacy of model verification and validation (where developing alternative conceptual models is an effective way to acknowledge and quantify model form uncertainty).

These three sources of uncertainty are related. Occasionally, data are used directly as model parameters. However, in most situations, data must be transformed so as to convey necessary meaning (e.g., "data reduction"), which, in turn, requires a model. Conversely, model uncertainty can result from sparse data or dearth of information to corroborate or refute alternative models. Hence, model uncertainty can affect parameter uncertainty and vice versa.

Parameter uncertainty and scenario uncertainty are also closely related because, as noted in Section 1.1.2, Multiple Iterations: a Performance Assessment Strategy, scenarios may be thought of as partitions of the set of all model parameters. Finally, scenario uncertainty and model uncertainty are related through uncertainty that all impartial contributions to behavior of a system have been included. This "completeness uncertainty" cannot be quantified but only acknowledged and evaluated through expert judgment and peer review.

The following are techniques for controlling and/or evaluating the influence of uncertainty:

<table>
<thead>
<tr>
<th>Type of Uncertainty</th>
<th>Technique for Controlling or Evaluating</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameter values and variability</td>
<td>Data collection programs; parameter selection guidelines; sensitivity/uncertainty analysis</td>
</tr>
<tr>
<td>Scenarios (completeness, logic, and</td>
<td>Expert judgment and peer review</td>
</tr>
<tr>
<td>probabilities)</td>
<td></td>
</tr>
<tr>
<td>Model form</td>
<td>Expert judgment and peer review, sensitivity/uncertainty analysis, verification and validation</td>
</tr>
</tbody>
</table>

Model-form uncertainty was introduced in Section 1.2.4, Model Development. Sections 1.3.1 and 1.3.2 introduce methods for evaluating the influence of uncertainty from parameter and scenario variability on a modeling system. Section 1.3.3 discusses the quality assurance procedures developed for the preliminary PA calculations. Because uncertainty is pervasive throughout the PA process, only a few facets of uncertainty can be discussed in these three subsections. Other facets of uncertainty will be discussed elsewhere (see Chapters 3.0 and 4.0).

References


* Ideally, initial uncertainty is largest and subsequent examination "reduces" it, but knowledge does not always progress in that fashion.
** Quality Assurance procedures undergo continual modifications. These reports represent the set of procedures developed in conjunction with the 1990, 1991, and 1992 PA calculations.
1.0 Introduction

1.3.1 Propagating Uncertain Parameters (Epistemic Uncertainty) through Consequence Models

Once highly or moderately uncertain parameters, \( x_n \), have been selected and their uncertainties characterized as probability distributions (see Section 4.1.1, Characterizing Parameter Uncertainty), they must be propagated through the consequence models to determine the uncertainty they produce in the results. This process is termed uncertainty propagation. The Waste Isolation Pilot Plant (WIPP) Performance Assessment Department propagates uncertainty from underlying parameters (or uncertainties from scenarios, probability models, or consequence models that can be expressed as parameter uncertainties) through its deterministic computational models using a Monte Carlo technique\(^1\),\(^2\) (see Figure 1.3-1). A Monte Carlo technique was selected for the following six reasons\(^3\): (1) it easily propagates uncertainty through a sequence of linked models; (2) it produces a mapping of input to output that can be studied by a variety of standard statistical techniques (e.g., scatterplots, regression analysis); (3) it does not require an intermediate model that might smooth and obscure discontinuities or other transitions between regimes of behavior; (4) it does not require that deterministic computer models be modified; (5) it can include parameters with empirical or subjective distributions having wide ranges and discontinuities; and (6) it allows the uncertain parameters to be correlated.

Monte Carlo techniques are used as follows. First, a sample is generated from the specified distributions and correlations between uncertain parameters that vary \( x_k = (x_{1k}, x_{2k}, \ldots, x_{nk}) \), where \( nK \) is the size of the sample and \( nV \) is the number of uncertain parameters. Then, the model calculation is performed \( nK \) times using each sample element \( x_k \), which yields a sequence of \( nK \) results of the form \( C(x_1), C(x_2), \ldots, C(x_{nK}) \). These results can be plotted as one of several types of distribution function, namely a PDF,\(^*\) a CDF,\(^**\) or a CCDF.\(^***\) The latter two functions are more commonly used. In practice, Latin hypercube sampling\(^4\),\(^5\) (see Sections 4.2.3 and 4.2.4) is used to minimize the number of sample elements needed to capture parameter variability adequately.

References


\(^*\) A probability density function (PDF) is analogous to a mass density function in physics. Whereas a mass density function is integrated over volume to obtain the mass between the limits of integration, a probability density function is integrated over outcome to obtain the probability of an outcome between the limits of integration.

\(^**\) A cumulative distribution function (CDF) is the sum (or integral, as appropriate) of the probability density over those values of a random variable that are less than or equal to a specified value, \( C \), and represents the probability that an outcome of \( C \) or less will occur.

\(^***\) A complementary cumulative distribution function (CCDF) is one minus the cumulative distribution function. It represents the probability of exceeding a consequence value of \( C \). For the containment requirements in 40 CFR 191, the consequence value is the sum of all releases (normalized by the Environmental Protection Agency release limits) accumulated over 10,000 yr.
1.3 Types of Uncertainty in Performance Assessments

Uncertain parameters (see § 4.1, Assigning Parameter Uncertainties)

Fixed parameters (vast majority of parameters)

\[ \begin{align*}
\text{kth sample value for parameter } x_i \\
\text{CDF} \quad \text{(or CCDF) represents uncertainty in consequence value resulting from uncertainty in input parameters.}
\end{align*} \]

Figure 1.3-1. Monte Carlo analysis is used to propagate parameter uncertainty, that is, numerous sample sets of all the uncertain parameters are run through the deterministic consequence model, \( C \), to define the distribution of the result. The \( k \)th sample set, \( x_k \), of the parameters and the deterministic result are shown as an example.
1.0 Introduction

1.3.2 Propagating Aleatoric Uncertainty through Performance Assessment

How uncertainty is propagated through an entire performance assessment (PA) depends on the source of the uncertainty: (1) scenarios and form of consequence and probability models underlying the model and (2) parameters (refer to Section 1.3, Types of Uncertainty in Performance Assessments). Uncertainty in consequences arising from different scenarios is represented by differences in the complementary cumulative distribution functions resulting from each scenario (see Section 1.1.2, Multiple Iterations: a Performance Assessment Strategy, and Section 6.1, Environmental Protection Agency 40 CFR 191 Simulations). Uncertainty in parameters used by computational models is discussed in Section 1.3. If these two types of uncertainty are described mathematically (and a Monte Carlo approach is assumed to propagate uncertainty), the following mathematical statement results and is depicted in Figure 1.3-2:

\[
\text{Risk}(x_k) = \{S_j(x_k), C[x_k, S_j(x_k)], P[x_k, S_j(x_k)] \} \quad j = 1, \ldots, nS, \quad k = 1, \ldots, nK
\]

Uncertainty concerning completeness of physical processes included in the consequence model (e.g., inclusion of all significant process parameters) or the completeness of events and features (e.g., inclusion of all significant model parameters representing features) can be controlled only through a specially defined procedure or peer review; it cannot be "propagated." Uncertainty associated with the formation of the scenarios and the development of the form of models in the PA can be quantitatively evaluated through the use of alternatives (e.g., alternative conceptual or mathematical models of fluid flow and transport through fractures) (see Section 1.2.4, Model Development). Realistically, however, the number of alternatives examined in preliminary performance assessments is strongly dependent upon the number of model parameters declared as uncertain and hence requiring propagation through the models. Furthermore, examining alternatives associated with model form will be useful primarily during preliminary PAs. The final PA used for determining compliance will likely use only one model form thought to best capture the behavior of the disposal system.

References


---

* Although important to discuss in the introductory chapter, this topic is easier to discuss after the overall PA process is somewhat understood. Section 8.1, Concise Review of the Six-Step Performance Assessment Process, provides a good starting point from which to observe (1) the propagation of uncertainty in a PA from parameters used to describe scenarios and thus represented by individual CCDFs and (2) the propagation of uncertainty in a PA from parameters in the computational models.

** Although this general division of uncertainty is somewhat nebulous, it has been recognized and accepted by the scientific community for many years (e.g., see Chernoff and Moses, 1959, p. 1).** See also Section 4.1, Assigning Parameter Uncertainties.
1.3 Types of Uncertainty in Performance Assessments

CCDF from 1st Monte Carlo sample

1st Scenario
$C(S_1(x_1), x_1), P(S_1(x_1), x_1)$

nS Scenario
$C(S_{ns}(x_{ns}), x_{ns}), P(S_{ns}(x_{ns}), x_{ns})$

Each step is a consequence, probability pair for one scenario.

Consequences from same scenario (nS for example) can be plotted to give CCDF (as in §1.3.1), but this CCDF is conditional on scenario nS occurring.

CCDF from nKth Monte Carlo sample

1st Scenario
$C(S_1(x_{nk}), x_{nk}), P(S_1(x_{nk}), x_{nk})$

nS Scenario
$C(S_{ns}(x_{ns}), x_{ns}), P(S_{ns}(x_{ns}), x_{ns})$

Note: To increase the feasibility of the calculations not all consequences may be calculated; for example, the results of five intrusions into the repository could be bounded by five times the consequence of one intrusion.

Plotting all CCDFs simultaneously shows quantifiable uncertainty from scenarios and parameters (model form uncertainty requires the same approach but simulations with an alternative model form, $C'$ or $P'$).

Figure 1.3-2. Propagating aleatoric uncertainty through performance assessment.
1.3.3 Quality Assurance Procedures for 1990-1992 Calculations

Given the emphasis of this report on the mechanics of the performance assessment (PA) process, it is important to mention the concepts behind the procedures developed to provide a reasonable degree of assurance that the results from the PA process at that time presented a scientifically reliable view of the Waste Isolation Pilot Plant (WIPP) performance based on current knowledge and the explicitly identified sources of uncertainty. What follows is a description of the quality assurance (QA) procedures developed concurrently with the 1990-1992 PA calculations. The QA procedures provided assurance by specifying requirements in three primary areas of the analysis process: Parameter Selection, Software, and Analysis. These primary areas were distinct processes and usually involved different participants. The procedures also ensured quality in two other areas—Report Review and Expert Judgment Panels (Figure 3.3-3). These two subareas were not necessarily distinct from the primary areas because, for example, all three primary QA areas required reports followed by review. In addition, some personnel participating in the Parameter, Software, and Analysis QA areas were able to participate in documentation and/or Expert Judgment Panels. A brief introduction to the procedures is described below.

The Parameter QA procedures sought to provide the PA analyst with consistent computational model parameters. The fundamental requirement was the development of a secondary data base managed by a Secondary Data Base Task Leader who was responsible for selecting appropriate data in consultation with site Investigators and PA Analysts. Transferring data from experimental groups to the secondary data base was an important means by which the PA Analysts interacted with other groups within the WIPP Project. The Software QA procedures were designed to ensure that the software performed to meet the expectations of the PA Analyst. The fundamental requirement was the development of a Software Management System (the CAMCON Modeling System; see Section 3.3.4) directed by Software Sponsors who enter an assigned code into the system and serve as a point of contact for PA Analysts. The Analysis QA procedures established a framework for the analysis so that the results presented a scientifically acceptable view of the WIPP performance based on current knowledge. The fundamental requirement was the division of the PA analysis into small tasks followed by peer review. The Expert Judgment Panel QA procedures were intended to ensure that as much observation data as possible supported the judgment and that as much rigor as possible went into the judgment-making process. The fundamental requirement was the composition of an issue statement for the expert panel. The Report Review QA procedures were intended to provide the decision makers and all participants in the WIPP Project with assurance that the final products contained the necessary information on Parameter, Software, Analysis, and Expert Judgment Panels and were adequately reviewed. The fundamental requirement was a two-level approach to quality in that all documents underwent a standard review, but selected documents were also more rigorously reviewed by a PA Peer Review Panel of peers selected from outside the Sandia WIPP Project.

The QA procedures for Parameter, Software, and Analysis were formally structured around the five steps of an analysis: define, investigate and implement, verify, review, and document. An exception is that neither Software nor Parameter QA included the first step, define, because these steps were defined within the project. As an example, the Software QA procedures addressed analysis investigation, verification, review, and documentation in the following ways: (1) investigation through traceability (by requiring version IDs based on a three-level classification of code, developer names, and dates on output) and retrievability (by requiring the CAMCON system); (2) verification through performing test cases; (3) review by means of a Software Review Committee; and (4) documentation through on-line, computerized documentation ("help files"), general abstracts, records on changes and verification, internal comments, and user and theory manual formal reports. The other procedures have comparable controls in the five steps of an analysis.

The areas covered by the QA procedures roughly corresponded to the basic steps for performing a PA analysis (see Section 1.2). To elaborate, Parameter Selection QA procedures set requirements to address parameter uncertainty and compilation/interpretation of data for disposal system characterization/conceptual model development; Software QA procedures set requirements for software development of consequence and probability computational models; Analysis QA procedures set requirements for use of software tools to address scenario and model form uncertainty and perform consequence and sensitivity/uncertainty analysis; Expert Judgment and Document Review QA set procedures for all tasks including scenario uncertainty and regulatory performance evaluation.
Three primary areas—software, parameters, and analysis—and two subareas—report review and expert panels—controlled by the quality assurance procedures for the 1990-1992 performance assessment calculations. Implicit in these quality assurance procedures was the understanding that the PA process would be repeated several times.
1.3.3 Quality Assurance Procedures for 1990-1992 Calculations (Cont'd)

The QA procedures implicitly assumed the PA process would be repeated several times (See Section 1.1.2, Multiple Iterations: a Performance Assessment Strategy); thus, the PA task within the WIPP Project was treated as an ongoing process or operation and not a project. To elaborate, the QA procedures were concerned primarily with the analysis product and PA process quality rather than the WIPP Project management quality and, hence, the procedures (e.g., Software QA) did not address the project life cycle, project triple constraints (cost, schedule, performance), project planning, human resource allocation, or project change control.

References


1.4 Terminology of a Mined Geologic Disposal System

As with many fields of study, once the meaning of the specialized terminology is understood, the reader can understand related concepts more readily. Nuclear waste disposal is no exception. The following two sections define (1) terminology used in Environmental Protection Agency regulation 40CFR 191, and (2) terminology used to describe common features of a geologic repository for the disposal of nuclear waste.
1.4.1 Terminology Used in 40 CFR 191

As defined in 40 CFR 191, Subpart B, the disposal system is the combination of the engineered barriers of the repository system and the natural barriers of the disposal site that isolate the radioactive wastes from the accessible environment, where "barrier," as given in §191.12[a], "means any material or structure that prevents or substantially delays movement of water or radionuclides toward the accessible environment." Accessible environment is defined below and in Figure 1.4-1. Engineered barriers are designed by humans and include backfill in the emplacement facilities or plugs in boreholes. Natural barriers are the subsurface geologic and hydrologic features within the "controlled area" that inhibit release and migration of hazardous materials. "Controlled area" is defined below and in Figure 1.4-1. Barriers are not limited to the examples given in the regulator's documentation, nor are those examples mandatory. Furthermore, the Environmental Protection Agency (EPA) states in Appendix B of 40CFR 191, "...reasonable projections for the protection expected from all of the engineered and natural barriers...will be considered."

According to §191.12 of 40 CFR 191, the "controlled area" mentioned above is "(1) a surface location, to be identified by passive institutional controls, that encompasses no more than 100 square kilometers and extends horizontally no more than five kilometers in any direction from the outer boundary of the original location of the radioactive wastes in a disposal system; and (2) the subsurface underlying such a surface location." Furthermore, paragraph [k] of that same section defines the "accessible environment" as "... (1) the atmosphere, (2) land surfaces, (3) surface water, (4) oceans, and (5) all of the lithosphere that is beyond the controlled area." For assessment purposes, the overall performance of the disposal system is normally calculated at the boundary between these two regions.

As used herein, the "site" is the general location of the controlled area (the disposal system, including the land surface directly above it), but includes any important features surrounding the controlled area. Except for the latter addition, this report's definition of site is most similar to the regulatory definition in 10 CFR 60.2: "the location of the controlled area."

References
1.4 Terminology of a Mined Geologic Disposal System

The "Controlled Area" is the Disposal System plus the Land Surface Directly Above it.

"Disposal System" includes Engineered and Geologic Barriers Bounded by Accessible Environment; Maximum size is ≤ 5 km from Waste and ≤ 100 km² Area.

WIPP Disposal System (16 mi² of Land Withdrawn for use by WIPP) 𝑆

Engineered Barriers Include:
- Waste Parcel
  - Waste Form
  - Internal Backfill
  - Containers
- Repository
  - Backfill around Waste Parcel and in Drift
  - Facility Layout
  - Waste Distribution
  - Backfill in Shafts

Accessible Environment for 40 CFR 191. 1,2 (Rest of World)

Probable Disposal Unit for 40 CFR 268. 5

*Disposal System Barriers are any Material or Structure that Delays Movement of Radionuclides toward the Accessible Environment; in this Report they are Categorized as either Geologic or Engineered

Figure 1.4-1. Artist's concept of a mined geologic disposal system portraying terminology used in this report. 6
1.0 Introduction

1.4.2 Description of the Waste Containment System

In this report, a radioactive-waste containment system includes three principal subsystems: institutional controls, engineered barriers, and geologic barriers, and their major components (shown symbolically in Figure 1.4-2).

The first subsystem—institutional controls—consists of components such as U.S. Government ownership of the land and resources, fencing and signs around the property, permanent markers, public records and archives, and other methods of preserving knowledge about the disposal system.\(^1\)\(^2\)

The physical features of the repository (e.g., design of the repository, waste form, waste parcel, and backfill) are components of the second subsystem, engineered barriers. For purposes of discussion, the components of the engineered barrier system are further grouped into two subdivisions—the waste parcel and the repository. In this report, the waste parcel is defined as the waste form, waste containers, and any internal backfill. The repository is the portion of the disposal facility that includes the waste panels, access drift, and access shafts. Although the Waste Isolation Pilot Plant is not regulated by the Nuclear Regulatory Commission, a few terms from their 10 CFR 60\(^3\) are included in Figure 1.4-2 to demonstrate the slight differences in terminology that can occur. For example, the 10 CFR 60 "engineered barrier" definition, which omits shafts, boreholes, and their seals, is narrower than the definition used in this report. Also, the term "waste emplacement package" signifies the waste parcel and any backfill-buffer placed between the waste parcel and the host rock.

The third subsystem—geologic barriers—includes the lithosphere that extends from the engineered barrier up to the ground surface no more than 5 km (3 mi) from the outer boundary of waste-emplacement rooms and drifts. In other words, it extends to the accessible environment.

The disposal system is defined as the combination of engineered and natural barriers that isolate spent nuclear fuel or radioactive waste after disposal (40 CFR 191.12[a]).\(^4\) As part of the performance assessment, analysts must investigate how the disposal system behaves. Specific situations are assumed (i.e., various combinations of features, events, and processes) that represent possible future conditions at the repository. Depending on the situation, different parts of the engineered and geologic barrier subsystems are assembled into a conceptual model that is then described mathematically.

References


1.4 Terminology of a Mined Geologic Disposal System

Disposal System

Engineered Barrier Subsystem
10 CFR 60 omits shaft and borehole backfill and waste management from engineered barrier system.

Institutional Control Subsystem
40 CFR 191 does not allow the DOE to depend upon the enforcement of active institutional controls after 100 yr, for performance assessments.

Geologic Barrier Subsystem
(Maximum 5 km Distance Around Waste Disposal Area)
The requirement in 40 CFR 191 to consider human intrusion implies that parts or all of the geologic barrier can be effectively by-passed.

Various groupings of the engineered barrier -- "waste parcel" and "repository" are primarily used in this report.

Figure 1.4-2. Subsystems and components of a radioactive waste containment system. The disposal system, as defined in 40 CFR 191, comprises the geologic and engineered subsystems of the waste containment system (Rechard, ed., 1993b, p. 1-9).
1.0 Introduction
1.5 Regulatory Influences on the Waste Isolation Pilot Plant Project

At present, the Waste Isolation Pilot Plant (WIPP) Project is about 20 years old, and more years lie ahead before the regulatory process for the disposal facility is completed. National policy issues, regulatory influences, negotiated agreements, and court settlements over the first half of the project have had a strong influence on the amount and type of scientific data collected. In the second half of the project, federal compliance policy and actual regulations were set more firmly. The WIPP will have to comply with these if it is to operate as a repository.

Prior to the WIPP Project, the precursor to the Department of Energy (DOE), the Atomic Energy Commission (AEC), spent the period from 1955 through the late 1960s formulating a Commission policy on nuclear waste disposal.\(^1\) As soon as it appeared, Congress established its own broad national policy requiring environmental impact statements (EISs) on large federally funded projects (83 Stat. 852, 42 U.S.C. 4332).\(^2\) The EIS process exerted its influence during the 1970s as the AEC, then the Energy Research and Development Agency, and finally the DOE, searched for and located a bedded salt deposit satisfactory for use as a repository. That site was to become the present WIPP site, near Carlsbad, New Mexico. Just as the WIPP EIS was nearing completion in 1979, Congress established anew the purpose of the WIPP Project and granted self-regulation to the DOE.\(^3\) \([\text{Although regulations by the Nuclear Regulatory Commission (NRC)}^{*}\text{ would have been possible, NRC had been established to regulate primarily commercial nuclear reactors and waste}.\]

Negotiated settlements with the State of New Mexico in the early 1980s, and early drafts of the Environmental Protection Agency (EPA) nuclear waste disposal standard, 40 CFR 191, focused on hydrologic data collection near the site. National advisory groups, particularly the WIPP Panel of the Board of Radioactive Waste Management (BRWM) of the National Academy of Sciences and independent state-selected evaluation groups, such as the New Mexico Environmental Evaluation Group, were set up on the initiative of the DOE to monitor its self-regulation. The promulgation of 40 CFR 191 in 1985 established the primary regulation with which the WIPP would have to comply. However, the definition of radioactive waste as hazardous in 1986 and 1987 (42 U.S.C. 6901 et seq.) established another set of regulations, those for chemical waste with which WIPP must also comply. Then, in 1992, the Congress established a specific compliance process and designated the EPA (rather than the DOE) as the regulator of the WIPP.\(^4\)

WIPP-Project history is not essential to acquire an understanding of the performance assessment (PA) process. However, it clarifies the evolution and emphasizes how only recently, in relation to the age of the project, stochastic simulations were introduced as a tool for the assessment of WIPP performance. Assessment activities before the late 1980s were undertaken primarily (1) to satisfy needs for environmental impact statements, (2) to satisfy negotiated agreements with the State of New Mexico, or (3) to develop general understanding of selected natural phenomena associated with nuclear waste disposal, as deemed prudent by Sandia scientists (working with peers in waste management) and/or as suggested by scientists on the WIPP Panel of the BRWM of the National Academy of Sciences. Thus, many activities performed throughout the history of the WIPP Project cannot be neatly categorized in terms of fulfilling the specific needs of the PA process. The following section and figure present a timeline of regulation and other events that influenced the formation, maintenance, and current status of the WIPP Project.

References

* The Nuclear Regulatory Commission was formed by the 1974 Energy Reorganization Act.\(^5\) It was formerly part of the Atomic Energy Commission.
1.5.1 Timeline of Events for the WIPP Project

Systematic studies of disposal options for radioactive waste began in the United States in 1955 when the Atomic Energy Commission (AEC), which later became the Department of Energy (DOE), asked the National Academy of Sciences (NAS) to examine the issue in detail (see Table 1.5-1). In 1957, the NAS reported that while various options and disposal sites were feasible, disposal in salt beds was the most promising method. From that point through the early 1970s, Oak Ridge National Laboratory conducted radioactive-waste experiments, most notably Project Salt Vault in an abandoned salt mine near Lyons, Kansas. Although the AEC considered using the mine as a repository, the discovery of boreholes in the nearby area prompted the AEC to search for more suitable sites.

At the invitation of New Mexico's governor, the AEC investigated the Delaware Basin in the Carlsbad area of New Mexico. After an initial examination, a potential site was identified in the 1970s. The site was named the Waste Isolation Pilot Plant (WIPP) in January 1976. During the site-characterization phase, two technical oversight groups were formed: the WIPP Panel of the Board of Radioactive Waste Management of the NAS, and the New Mexico Environmental Evaluation Group. The regional site-characterization phase of this potential waste disposal site ended with the preparation of a draft Environmental Impact Statement (EIS) in 1979, as required by the National Environmental Policy Act of 1969 (NEPA). In response to that EIS, the DOE decided to proceed with a preliminary design phase at this site.

During the 1970s, the original mission of the WIPP, and thus the design, oscillated between including and not including defense high-level waste (HLW) in addition to transuranic (TRU) wastes. However, with passage of the National Security and Military Applications of Nuclear Energy Authorization Act of 1980, Congress defined the WIPP as a research and development facility for storage and disposal of TRU wastes only, and exempted the WIPP from regulation by the Nuclear Regulatory Commission.

In 1981, the "Stipulated Agreement" and "Consultation and Cooperation Agreement" defined the WIPP's relationship with the State of New Mexico and stipulated specific geotechnical experiments required by the state. After much planning, which included a site and preliminary design phase, full construction of the WIPP facility began in 1983. Experiments to characterize the local disposal system followed. The report by Lynch et al. provides an overview of technical aspects relevant to that work. In preparation for the WIPP's opening, a Supplemental EIS was published. It identified gas generation—the gas being generated through normal corrosion of waste containers in time—as an important issue. This issue became the primary purpose of proposed tests using actual TRU waste within the repository during a carefully monitored test phase.

In the Waste Isolation Pilot Plant Land Withdrawal Act of 1992, Congress defined the process by which WIPP compliance would have to be evaluated and transferred ownership of the WIPP site to the DOE. This act officially marked the transition from the construction and disposal-system-characterization phase to the compliance and testing phases, although those phases had begun unofficially in 1985 when the U.S. Environmental Protection Agency (EPA) issued 40 CFR 191 and in 1989 when Sandia first began to assess performance using the EPA standard.

References for Section 1.5.1 Text


* Because the WIPP Project spans more than 20 years, more events have occurred than can easily be covered in a few pages; thus, the timeline is selective, with more emphasis placed on the role of overall national policy and its influence on the WIPP Project than the numerous milestones and scientific studies conducted at the site.
1.5 Regulatory Influences on the Waste Isolation Pilot Plant Project


Table 1.5-1. Milestones for Disposal of Radioactive Waste in the United States.

<table>
<thead>
<tr>
<th>New Mexico Administration and Regional Issues</th>
<th>Federal Legislative and Court Policy on Nuclear Waste Disposal</th>
<th>U.S. President and DOE Directives and Regulatory Decisions</th>
<th>Technical Milestones Related to the WIPP</th>
<th>Time Line</th>
<th>Events</th>
</tr>
</thead>
<tbody>
<tr>
<td>Miles Administration</td>
<td></td>
<td>* 1942 - Manhattan Engineering District</td>
<td>Reopened Administration</td>
<td>1942</td>
<td></td>
</tr>
<tr>
<td>Deming</td>
<td></td>
<td>Corps of Engineers selects site for Los Alamos Laboratory to develop nuclear weapons.</td>
<td></td>
<td>43</td>
<td></td>
</tr>
<tr>
<td>Military Administration</td>
<td></td>
<td>* 1946 - AEC Chairman: Lilienthal</td>
<td>Truman Administration</td>
<td>45</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>(Director of Tennessee Valley Authority)</td>
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<td>46</td>
<td></td>
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<tr>
<td></td>
<td></td>
<td>* In 1940's, AEC's earliest decision on managing waste: store high-level waste (HLW) as liquids in tanks and bury other waste in trenches.*</td>
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<td>47</td>
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<tr>
<td></td>
<td></td>
<td>* 1953 - AEC Chairman: Strauss (Rear Admiral)</td>
<td></td>
<td>48</td>
<td></td>
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<tr>
<td></td>
<td></td>
<td>* 1955 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>49</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>* 1958 - AEC Chairman: McCone (Businessman). Plowshare program started to look at peaceful uses of nuclear explosives.</td>
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<td>50</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>* 1957 - NAS recommends radionuclide waste disposal in salt as most promising method. Oak Ridge National Laboratory (ORNL) begins research in salt (1957-61).</td>
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<td>51</td>
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<tr>
<td></td>
<td></td>
<td>* 1959 - NAS commission on oceanography reports on coastal disposal of low-level radioactive waste.</td>
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<td>52</td>
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<tr>
<td></td>
<td></td>
<td>* 1960 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>53</td>
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</tr>
<tr>
<td></td>
<td></td>
<td>* 1962 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<tr>
<td></td>
<td></td>
<td>* 1963 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>55</td>
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<tr>
<td></td>
<td></td>
<td>* 1964 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>56</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>* 1965 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>57</td>
<td></td>
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<tr>
<td></td>
<td></td>
<td>* 1966 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>58</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>* 1967 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>59</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>* 1968 - AEC asks National Academy of Sciences (NAS) to examine issue of permanent disposal of radioactive wastes.</td>
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<td>60</td>
<td></td>
</tr>
</tbody>
</table>
### New Mexico Administration and Regional Issues

<table>
<thead>
<tr>
<th>Year</th>
<th>Event</th>
</tr>
</thead>
<tbody>
<tr>
<td>1976</td>
<td>DOE contracts with NM to establish Environmental Evaluation Group (EEG) to provide a full-time, independent assessment of WIPP and oversee environmental &amp; public health &amp; safety. Although DOE funded, EEG is initially made a part of Environmental Improvement Division of NM Health &amp; Environment. The general understanding is neither DOE nor NM would attempt to bias or interfere in EEG's technical conclusions. EEG becomes 1st of 2 permanent outside oversight groups set up by DOE (other was NAS WIPP Panel of BERWM). NM House of Reps passes ballot proposal for constitutional amendment to keep nuclear waste from NM.</td>
</tr>
<tr>
<td>1979</td>
<td>AG: Bingaman legislation establishes (1) Gov's Radioactive Waste Consultation Task Force to negotiate with DOE &amp; (2) legislative Radiactive &amp; Hazardous Waste Committee to review task force.</td>
</tr>
<tr>
<td>1980</td>
<td>NM &amp; DOE begin negotiations on &quot;Consultation &amp; Cooperation (CAC) Agreement to define procedures &amp; process of cooperation.&quot;</td>
</tr>
<tr>
<td>1989</td>
<td>May: House Armed Services Committee cuts WIPP's FY funding in response to DOE's expansion of the project to a reactor for commercial use &amp; thus requiring NRC licensing. Dec: Congress defines mission of WIPP.</td>
</tr>
<tr>
<td>1990</td>
<td>Apr: DOE defines project as a combination military/ commercial-uranium disposal in Draft EIS. Oct: DOE decides to begin preliminary design of WIPP.</td>
</tr>
</tbody>
</table>

### Federal Legislative and Court Policy on Nuclear Waste Disposal

<table>
<thead>
<tr>
<th>Year</th>
<th>Event</th>
</tr>
</thead>
<tbody>
<tr>
<td>1977</td>
<td>DOE Organization Act creates Cabinet-level Department of Energy (DOE) from ERDA.</td>
</tr>
<tr>
<td>1977</td>
<td>DOE Sec: Schlesinger. DOE tells NRC it plans to seek license to build &amp; operate WIPP (WIPP back in commercial waste repository program). In response to Ford directive, EPA conducts 1st public workshop to educate public on WIPP &amp; technical issues of waste disposal.</td>
</tr>
<tr>
<td>1978</td>
<td>Schlesinger promises NM Congressional delegation &quot;if NM did not wish to have the WIPP, then it could veto the plan.&quot; Both Comptroller - Gen &amp; DOE Gen. Council state Schlesinger powerless to grant &quot;state veto.&quot; DOE conducts local hearings on proposed WIPP. Deahth (MIT chem. prof.) report written for DOE recommends (1) disposing TRU waste at WIPP without planning for retrieval, &amp; (2) demonstrating spent nuclear fuel (SNF), HLW &amp; TRU disposal at WIPP. DOE Denies Sec. J. O'Leary presses on with 2nd recommendation until 1979 enabling law for WIPP.</td>
</tr>
<tr>
<td>1979</td>
<td>Apr: DOE defines project as a combination military/commercial-uranium disposal in Draft EIS. Oct: DOE decides to begin preliminary design of WIPP.</td>
</tr>
</tbody>
</table>

### U.S. President and DOE Directives and Regulatory Decisions

<table>
<thead>
<tr>
<th>Year</th>
<th>Event</th>
</tr>
</thead>
<tbody>
<tr>
<td>1977</td>
<td>DOE Sec: Schlesinger. DOE tells NRC it plans to seek license to build &amp; operate WIPP (WIPP back in commercial waste repository program). In response to Ford directive, EPA conducts 1st public workshop to educate public on WIPP &amp; technical issues of waste disposal.</td>
</tr>
<tr>
<td>1978</td>
<td>Schlesinger promises NM Congressional delegation &quot;if NM did not wish to have the WIPP, then it could veto the plan.&quot; Both Comptroller - Gen &amp; DOE Gen. Council state Schlesinger powerless to grant &quot;state veto.&quot; DOE conducts local hearings on proposed WIPP. Deahth (MIT chem. prof.) report written for DOE recommends (1) disposing TRU waste at WIPP without planning for retrieval, &amp; (2) demonstrating spent nuclear fuel (SNF), HLW &amp; TRU disposal at WIPP. DOE Denies Sec. J. O'Leary presses on with 2nd recommendation until 1979 enabling law for WIPP.</td>
</tr>
</tbody>
</table>

### Technical Milestones Related to the WIPP

<table>
<thead>
<tr>
<th>Year</th>
<th>Event</th>
</tr>
</thead>
<tbody>
<tr>
<td>1979</td>
<td>SNL begins studies for direct geologic structurally affects in nearby potash mine &amp; Louisa dome. For 1st time, permeability measurement of Salado FM salt from AEC test well. (values 1000 times larger than when measured in laboratory). NSB identified 2 potential horizons for WIPP.</td>
</tr>
<tr>
<td>1981</td>
<td>May: DOE begins investigating 1st shaft beneath which it is planned in the SDDP phase of WIPP. Jul: drilling on 1st shaft begins. May: project strikes pressured brine reservoir while deepening WIPP; 12 more of the repository (part of Stabilization Agreement (SA)). Following evaluation, repository moved ~ 1000 ft below ground. Dec: drilling of 2nd shaft begins.</td>
</tr>
</tbody>
</table>
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1982 - Dec: Supplemental SA signed
(1) committing DOE to seek funds for
upgrading highways 1n NM (2) committing DOE to more geotechnical
studies, and (3) making DOE liable
for WI PP-related accidents
1983 - AG: Bardacke. May: after reviewing results from SPDV program,
EEG concludes that " ... the Los Medanos site has been characterized in

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in the validation of the site for permanent
emplacement of approximately 6 million ft'
(1 75 x 10 5 m 3 ) of defense TAU waste,
" but also recommends additional studies
to resolve outstanding geotechnical issues
such as evaluation of potential for brine
reservoirs. 46 Aug: EEG issues report
"Potential Problems from Shipments of
High-Curie Content Contact Handled TAU
• Waste to WIPP." 47 Aug·. Anaya states
concern about potentially explosive
hydrogen gas in TRUPACT-1. Sep: CARD
& Sierra Club allege that DOE & EEG are
collaborating to deceive NM about safety
of WIPP. Also insists on NRC licensing
[ ofWIPP
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1985 - EEG notifies DOE that the
single-shelled, vented rectangular
~
transportation container for TR U
03
waste, TRUPACT-1. is unaccept
able. 48 Feb: Natural Resources
~
Defense Council (NRDC) sues DOE to
bring about compliance with NWPA of
1982 (see 1981).

"'

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1982 - Nuclear Waste Policy Act
(NWPA) 49 :
- sets up trust fund, funded by utilities,
to pay for SNF & HLW repository
- requires NRC licensing of repository
- sets acceptable risk of 1000 deaths/
10,000 yr
- states SNF & HLW from DOE facilities
will go to repository unless Reagan
objects
suggests DOE build Monitored Retrievable Storage (MRS)
Courts decline to relieve DOE from responding to numerous SWRIC interrogatories.

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L 1983 - Congress allocates $5.8 M for
road improvement in NM

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1984- 1st modification to C&C Agree- "'
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menr 11mmng remote naflaiea lHH)
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TAU waste amount to 5.2 x 106 Ci.
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1984 - Hazardous & Solid Waste Amendment Act (HSWA) 50 bans hazardous
waste disposal in land fills without accepted pretreatment unless disposal
site has petitioned successfully for a
"no-migration" variance. LEAF v. Hodel 51
requires DOE to apply both the technical
and procedural requirements of RCRA to
DOE facilities even though AEA exempted
DOE from many environment and human
health laws.

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1982- DOI approves applicat1on 55 submitted 2 yr earlier by DOE 56 for administrative
withdrawal of 36 x 106 m 2 (8960 ac) for
conducting SPDV experiments for 8 yr.
Dec: EPA publishes working draft 20
as proposed 40 CFR 191 rule. 57

1985 - DOE Sec: Herrington (lawyer).
Reagan approves the 3 repository
candidates as recommended bv DOE
for SNF & HLW. Reagan conc~rs with
DOE recommendation that defense
SNF & HLW be disposed of in commercial repository. Sep: EPA promulgates 40 CFR 191 for disposal of SNF
HLW, & TAU in a geologic repository, 31
uses 1000 deaths/10,000-yr criterion
from NWPA of 1982; promulgation
begins the transition of the WIPP to
compliance phase.

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1985 - Office of Technology Assessment
(OTA), an agency of Congress, concludes
no insurmountable technical obstacles
for geologic reposrtories. 52

1986 - NRDC sues EPA over 40 CFR 191. *

1986 - EPA states radioactivity waste
co-contaminated with hazard chemicals
(mixed waste) approx. 60% of WIPP
waste subject to RCRA.

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1982 - 2nd shaft completed (-80m [270ft]
fluid left in the shaft). Nov: project flips repository 180° (TAU disposal area moved
further south). Dec: SNL completes interim report on dissolution of evaporites in &
around the Delaware Basin" (part of SA).

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1985 - GA disassembles TRUPACT-1 and
~85
cuts in half; half with door rebuilt; while
~rebuilding, puncture damage replicated
to match damage in original TRUPACT-1.
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With the definition of a 5-km boundary to
the disposal system in 40 CFR 191, project begins to focus more on near-field
hydrologic modeling rather than regional
model'1ng.
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1986- Feb: half TRUPACT-1 passes fire
test at SNL. 67 ·68 Aug: SNL accepts task
2
of assessing performance of WI PP
Sl
c;·
against 40 CFR 191 criteria (Performance ::J
Assessment [PA)).
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1983 - Mar: SNL, USGS, & contractors
co'llplete most reports required by SA.
Apr: WIPP Panel NAS tours WIPP underLi... ground to examine SPDV tests. 63 May:
IJl'C repository level selected. Jun: Army Corp
of Engineers assumes responsibility for
all phases of construction management.
Jun: excavations connect the two existing
shafts. Oct: USGS completes Breccia
pipe report (part of SA) and drilling of
pilot hole for 3rd shaft begins.
1984 - SNL begins implementing many
thermal/structural & waste package (e.g.,
LI... defense HLW) field tests defined in 1982,
I~ ushering in the system characterizat"1on
phase of project. 64 ·65 ·66 GA completes
one TRUPACT-1 container; SNL sends
to ORNL test facility because container
exceeded weight limitation at the time
:IJ
for structural testing (e.g., 30 ft drop on
unyielding target, puncture test, etc.)
required in 10 CFR 191; container passes
::o

1983 - DOE Sec: Hodel (lawyer). Mar:
DOE gives SPDV reports to NM & allows
60 day comment period. 58 Jun: DOI
approves withdrawal of 36 x 106 m' land
for 8-yr full construction. 59 Jun: NRC
promulgates technical criteria for waste
disposal in geologic repositories and
includes by reference the yet to be
promulgated EPA standard on waste
disposal. 34 •35 ·36 Jul: DOE announces
decision to proceed with construction. 60
Sep: DOE sets Oct 1988 as WIPP
opening date.
1984 - Mar: Manager of Albuquerque
Operations Office (AL) moves WIPP
Project Office (WPO) to Carlsbad.

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between radioactive & hazardous waste
regulations, NM legislature exempts
WIPP from hazardous waste regulations.
2nd modification to C&C Agreement
0
commrtting DOE to comply with all
)> "'
applicable laws & regulatrons and
c.
3
discourage WIPP compliance by
?" ~
way of grandfathering, variance,
en
exemption, or waiver; & use
40 CFR 191 as 1st issued for
evaluating WIPP compliance until
reissued by EPA; NRC & DOT regs apply
to WIPP transport.

s.

1987 - Jul: Court of Appeals for 1st
District, vacates & remands to EPA
one portion of 40 CFR 191 added in
response to comments but not commented on again and one portion with
discrepancy with Clean Water Act. 53
Dec: Nuclear Waste Policy Admendments
Act (NWPAA) 54 selects Yucca Mt, NV to
undergo site characterization for potential
SNF and HLW disposal; because bedded
salt not being considered SNF and HLW
tests at WIPP unnecessary .

e

1987 - DOE redefines "byproduct material" *1987- SNL finds possibility of a pressurized brine reservoir below the TAU disto exclude everything except radionuclides, and thereby TAU waste is subject
posal area cannot be ruled out. 63 ·69 Lack
of double containment in TRUPACT-1
to RCRA (& HSWA). 106 Oct: DOE selects
Nuclear Packaging conceptual design for
becomes ma1or issue. 70 71 Oct: Nuclear
TRUPACT-11. Jul: Agreement between
Packaging becomes NE for TRUPACT-11;
SNL again becomes DOE technical
Department of Labor (DOL) and DOE
advisor.
on mine inspections. 61

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<table>
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<tr>
<th>New Mexico Administration and Regional Issues</th>
<th>Federal Legislative and Court Policy on Nuclear Waste Disposal</th>
<th>U.S. President and DOE Directives and Regulatory Decisions</th>
<th>Technical Milestones Related to the WIPP</th>
<th>Time Line Events</th>
</tr>
</thead>
<tbody>
<tr>
<td>• 1988 - Jan: EEG issues report on potential brine reservoirs under WIPP. Oct: (ID Gov. Andrus bars shipments of radioactive waste into state because WIPP not open. Dec: (ID Gov. Andrus, CO Gov. dome, and NM Gov. Carruthers meet in Salt Lake City to discuss WIPP and options to assert shutdown of DOE Rocky Flats Plant from lack of authorized storage imposed by CO. and inability to ship to ID because of imposed ban by Gov. Andrus, DOE agrees to vigorously pursue administrative and legislative land withdrawal for WIPP.</td>
<td>• 1988 - With continued technical problems (e.g., TRUPACT-II had not yet been licensed.) NM Congressmen urge Congress to reassess EEG to the New Mexico Institute of Mining &amp; Technology in Socorro in Sep., because of conflicts between NM state government and EEG.</td>
<td>• 1988 - Sep: DOE announces that WIPP won't open as scheduled in Oct.</td>
<td>• 1988 - WIPP SNF &amp; LW experiments cancelled because of NWPA. May: WIPP begins drilling 4th shaft after reevaluating 1981 decision to eliminate it. SNL reports on in-situ permeability (10X times lower than 1979) and small potential brine inflow. NAS group formed to study brine inflow, 1st prototype of TRUPACT-II passes structural tests, but fails engulfing fire test at seals.</td>
<td>1988</td>
</tr>
<tr>
<td>• 1989 - Jan: EEG issues report on potential brine reservoirs under WIPP. Oct: (ID Gov. Andrus bars shipments of radioactive waste into state because WIPP not open. Dec: (ID Gov. Andrus, CO Gov. dome, and NM Gov. Carruthers meet in Salt Lake City to discuss WIPP and options to assert shutdown of DOE Rocky Flats Plant from lack of authorized storage imposed by CO. and inability to ship to ID because of imposed ban by Gov. Andrus, DOE agrees to vigorously pursue administrative and legislative land withdrawal for WIPP.</td>
<td>• 1991 - Mar: House Select Committee on Energy and Commerce approves DOE modified brine withdrawal ordinance allowed under Federal Land Policy &amp; Management Act (FLPMA). Aug: 9th Circuit Court of Appeals rules state ban on radioactive waste shipments imposed by Gov. Andrus of Idaho illegal.</td>
<td>• 1990 - Jan: DOE issues Final Supplemental EA (SFEP) at WIPP. Aug: DOE reissues Record of Decision on WIPP Final Supplemental EIS stating testing phase (Stage V) should proceed. Then another Supplemental EIS should be prepared before going to full operation.</td>
<td>• 1989 - Jun-Aug: DOE issues Final Supplemental EA (SFEP) at WIPP. DOE evaluates potential risks due to brine disposal at WIPP and determines that the potential risks are acceptable.</td>
<td>1989</td>
</tr>
<tr>
<td>• 1992 - Environmental Defense Fund (EDF) and NRDC join the NM lawsuit and seek to make RCRA issues more important (e.g., interim status of WIPP).</td>
<td>• 1992 - WIPP Land Withdrawal Act establishes EPA as regulator for WIPP (removing self regulation by DOE).</td>
<td>• 1992 - DOE reissues 40 CFR 191 for WIPP.</td>
<td>• 1992 - DOE completes No-Migration Test Phase.</td>
<td>1992</td>
</tr>
<tr>
<td>• 1993 - Mayor of Carlsbad demands more economic benefits accrue to city of Carlsbad from WIPP.</td>
<td>• 1993 - Oct: DOE announces intent to promulgate 40 CFR 194 to specify requirements for implementing 40 CFR 191 at WIPP.</td>
<td>• 1994 - Jan: DOE announces intent to promulgate 40 CFR 194 to specify requirements for implementing 40 CFR 191 at WIPP.</td>
<td>• 1994 - SNL &amp; Westinghouse complete test phase requiring 95% of WIPP capacity of gas generation experiments.</td>
<td>1994</td>
</tr>
</tbody>
</table>

Table 1.5-1. Milestones for Disposal of Radioactive Waste in the United States.
Table 1.5-1 References

1.0 Introduction


1.5 Regulatory Influences on the Waste Isolation Pilot Plant Project


44 McVey, D.F. 1981. Analysis of Data from Line Source Thermal Conductivity Measurements Taken In Situ in Domed Salt at the Avery Island Mine. SAND81-1232. Albuquerque, NM: Sandia National Laboratories.


1.0 Introduction


1.0 Introduction


1.5 Regulatory Influences on the Waste Isolation Pilot Plant Project
1.0 Introduction

1.5.2 Timeline of Events Influencing Performance Assessment Process

The progress in integrating many disciplines and developing corresponding computational tools for a performance assessment (PA) is directly tied to the major projects that have been funded to this specific type of policy analysis. However, the events influencing the PA process are more than just a long list of major projects each making an evolutionary improvement. In this section and tabulated in Table 1.5-2, aspects of the history of the performance assessment process are grouped into four main subject categories: (1) events directly associated with nuclear reactor risk assessments in the United States, (2) events associated with performance assessments of nuclear waste repositories in the United States and abroad, (3) events associated with risk assessments with transporting nuclear waste and in disciplines other than nuclear facilities, and (4) outside influences affecting the performance assessment process in general. In the following discussion, a temporal categorization is also used. The first temporal category is the foundation phase (1947-1975) where most aspects of the underlying theory were developed for the PA process and limited applications of that theory were made. The second is the large-scale, interdisciplinary phase (1975-1985) where probabilistic risk assessments (PRA) and probabilistic performance assessments (PA) were done for the first time in the United States for large, complex nuclear facilities that require the integration of many scientific disciplines. The third is the diverse application phase (~1985 onward) where many applications to different physical systems have been made.

Besides the mathematical fields of probability and statistics, the foundations of the performance assessment process discussed in this report have evolved largely out of the U. S. nuclear weapons programs. The most important foundation technique was the development of the Monte Carlo method (see Section 1.3.1) by the Manhattan Project to evaluate the physics of weapons, specifically nuclear diffusion of neutrons through fissile material. Also drawn upon was the reservoir of techniques that were developed for the analysis of the reliability of delivery systems for nuclear weapons in the 1950s and early 1960s. One such example is the fault tree technique developed by Bell Laboratories and applied by Boeing to evaluate the Minuteman Missile. Another important foundational development for PAs in the United States was the development of the Latin Hypercube sampling technique in the summer of 1975 (see Section 4.2.2, Latin Hypercube Sampling).

The National Environmental Policy Act of 1969 (NEPA) (see Section 6.2) created a need to predict risks of large federally funded actions—especially technological actions. NEPA also provided an avenue through the public comment period on the Environmental Impact Statement (EIS) for special interest groups to call for more stringent analysis of the associated hazards of technological actions and resulted in a shift to detailed modeling to predict the consequences of these outcomes. An important technology to be significantly affected by NEPA was nuclear power. Although not directly tied to a formal EIS, the justly famous Reactor Safety Study requested by the Atomic Energy Commission Chairman, James Schlesinger, to evaluate hazards from severe accidents at commercial nuclear reactors was one of the earliest analyses to meet the general needs of detailed analysis required in the new atmosphere created by the NEPA. The critiques of the Reactor Safety Study also published in 1975 (e.g., Lewis Report) recognized its significant contribution as the first detailed, comprehensive, quantitative look at a large, complex nuclear facility. However, the critiques also noted that uncertainty associated with estimates for parameter values needed to be included besides uncertainty in behavior of the system, which had been evaluated through event trees and fault trees (see Section 1.3, Types of Uncertainty in Performance Assessments).

Demands for permanent solutions to nuclear waste provided an impetus for President Ford to call for more vigorous pursuit of applicable standards in 1977 for proposed waste repositories that culminated in the first probabilistic standard (see Section 6.1). It was during this period that the term performance assessment was adopted for assessments of waste disposal systems. Analysts at Sandia adopted a thorough and rigorous probabilistic approach, similar to the pioneering work in the Reactor Safety Study probabilistic risk assessment. Although the underlying theory of the PRA and the PA are the same, not all the analysis tools developed for assessing nuclear reactors could be used for assessing a geological disposal system. Both the engineered and geologic components of a waste disposal system are subject to natural processes over geologic time; hence, fault trees to calculate probabilities are not used and simple event trees usually omit temporal effects. Furthermore, computational tools differed because more phenomenological models were needed in order to include geologic processes. Although Sandia developed codes to be loosely connected in a PA in the late 1970s and early 1980s, the Canadians developed the first integrated system, SYVAC, in 1981. This was followed by other systems, including the CAMCON system, developed primarily between 1988
and 1990. The capabilities implemented in CAMCON greatly determined the approaches used and described in this report on the WIPP PA (see Section 3.3, Modeling System Selection).

During the late 1970s and early 1980s, exchange of ideas and concepts about rational nuclear waste disposal occurred through the International Atomic Energy Agency (IAEA) located in Vienna and the Nuclear Energy Agency (NEA) located in Paris (e.g., the international subseabed disposal system program and the Probabilistic Systems Assessment Code [PSAC] user group[1]). Also during the 1980s and 1990s, many diverse applications of PRA and PA occurred beyond those done initially for nuclear facilities. Several accidents and one disaster helped prompt the more frequent use of risk assessment. The first was the accident in one unit of the Three-Mile Island nuclear power plant in 1979. Another important accident was the Challenger space shuttle explosion in 1986. Both accidents helped give more credence to risk assessment. In 1984, the disaster at the chemical plant in Bhopal, India, where safety responsibilities had been turned over to local authorities who did not appreciate the gravity of ignoring safety procedures, helped encourage more extensive risk assessments within the chemical industry. Surprisingly, the risk culture that developed for nuclear facilities and the risk culture that developed for other disciplines, specifically environmental hazards from chemicals (summarized by the National Academy of Sciences in 1983[12]), have not frequently learned from each other—as evidenced, for example, by the different terms used for describing types of uncertainty. Some cross over has occurred,13 but until very recently the occurrences have generally remained isolated instances of what could be called probabilistic system assessments.

References for Section 1.5.2 Text

Table 1.5-2. Timeline of Events Influencing Probabilistic Analysis of Systems

<table>
<thead>
<tr>
<th>Risk Assessments for Other Technology (Chemical, Biological, Electrical, etc.) in U.S.</th>
<th>Performance Assessments for Nuclear Waste Repositories throughout World</th>
<th>Probabilistic Risk and Safety Assessments (PRA and PSA) for Nuclear Reactors in U.S.</th>
<th>General Events throughout the World Influencing Risk Assessments in U.S.</th>
<th>Time Line</th>
</tr>
</thead>
<tbody>
<tr>
<td>1945 - Some monitoring of radioactive fallout occurs at Trinity test at Alamogordo, Manhattan engineering district asks University of Washington to start experiments on radioactive effects on Columbia River fish near Hanford.</td>
<td>1955 - Simulation of war (i.e., war games) uses Monte Carlo methods to teach consequences of decisions.</td>
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<td>1960 - National Cancer Institute begins testing of common chemicals for carcinogenicity</td>
<td>1962 - Gnome project (part of Plowshare Program for peaceable use of nuclear explosives) creates need to predict (stochastically) diffusion of radionuclides through salt.</td>
<td></td>
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<tr>
<td>1964 - Risk assessment is done for capital investments of a business.</td>
<td>1966 - Oak Ridge studies radiological hazards from nuclear explosives, used for new canal in Panama (part of Plowshare Program).</td>
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<tr>
<td>1966 - Apollo Program at National Aeronautical and Space Administration (NASA) abandons fault-tree analysis and thereby risk analysis because of bad experience with estimates of failure being both too high and too low; instead resorts to rigorous testing of components and qualitative Failure Mode/Effects Analysis.</td>
<td>1967 - Fault trees applied to various components of nuclear reactors.</td>
<td>1968 - Event trees applied to siting of nuclear reactors.</td>
<td>1945 - Systematic development of Monte Carlo Methods to solve neutron diffusion in atomic bombs (important modeling technique for uncertainty propagation).</td>
<td></td>
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<tr>
<td>1954 - First Atoms for Peace conference overview's hazards of radionuclides.</td>
<td>1954 - Fallout from atmospheric tests contaminates Marshall Islands and Lucky Dragon Japanese fishermen – creates need for assessments and outcry to stop tests.</td>
<td>1955 - Systematic development of Monte Carlo Methods to diverse problems in 1950s.</td>
<td>1956 - Hanford reports on semiautomatic, deterministic risk assessment using expert opinion, is done to determine indemnification of nuclear industry (study similar to typical safety analysis).</td>
<td></td>
</tr>
<tr>
<td>1956 - Hanford reports on semiautomatic, deterministic risk assessment using expert opinion, is done to determine indemnification of nuclear industry.</td>
<td>1957 - Brookhaven worse case, deterministic risk assessment using expert opinion, is done to determine indemnification of nuclear industry.</td>
<td>1957 - Windscale graphite reactor fire in United Kingdom (UK) releases 21T milk contamination curtailed.</td>
<td>1958 - Congress passes Food Additive Amendment containing 'Doleroy Clause' prohibiting additives that induce cancer in animals or humans.</td>
<td></td>
</tr>
<tr>
<td>1958 - Congress passes Food Additive Amendment containing 'Doleroy Clause' prohibiting additives that induce cancer in animals or humans.</td>
<td>1962 - Bell Laboratories develops fault tree methodology.</td>
<td>1963 - Event trees applied to siting of nuclear reactors.</td>
<td>1966 - Event trees applied to siting of nuclear reactors.</td>
<td></td>
</tr>
</tbody>
</table>
1970 - Disposition study for Gnome site is conducted for Atomic Energy Commission (AEC).26

1970 - Deactivation study for Gnome site is conducted for Atomic Energy Commission (AEC).26

1973 - Food and Drug Administration (FDA) proposes 1 change in 100 million as de minimis for cancer risk. In 1977 changes to 1 in 1 million and uses linear dose model (no threshold).

1974 - First scenario development and deterministic consequence analysis is conducted for Waste Isolation Pilot Plant (WIPP).22

1975 - National Academy of Sciences (NAS) studies impact of Super Sonic Transport (SST) on stratospheric ozone.26


1977 - Geohydrology is an important aspect of geologic disposal. Hence, mathematical modeling of groundwater flow is required.22 President Ford orders EPA to develop generally applicable standards for permanent disposal of nuclear waste.22 International Atomic Energy Agency (IAEA) recommends site selection criteria for geologic disposal sites.26

1977 - Congress forms Environmental Protection Agency (EPA) and transfers to it responsibilities of research, monitoring, standard setting, and enforcement activities related to environment.27 Congress amends Clean Air Act.27

1977 - Appeals court requires AEC to look at all impacts in EIS on Calvert Cliffs reactor.29

1978 - Anti-nuclear groups claim renewable surface storage facility (RSSF) proposed by AEC defacto permanent disposal.

1975 - Arab oil embargo causes energy crisis in U.S.; encouraged by NM political leaders, AEC recommends SE NM for nuclear waste repository in US.

1974 - Congress splits AEC into Nuclear Regulatory Commission (NRC) and Energy Research and Development Agency (ERDA).10

1976 - DOE's Environmental Protection Agency (EPA) and transfers to it responsibilities of research, monitoring, standard setting, and enforcement activities related to environment.27 Congress amends Clean Air Act.27 Congress amends Clean Air Act requiring health risk assessment for existing National Ambient Air Quality Standards for common air pollutants.

1977 - DOE's Environmental Protection Agency (EPA) and transfers to it responsibilities of research, monitoring, standard setting, and enforcement activities related to environment.27 Congress amends Clean Air Act.27 Congress amends Clean Air Act requiring health risk assessment for existing National Ambient Air Quality Standards for common air pollutants.
1.0 Introduction


2.0 DISPOSAL SYSTEM AND REGIONAL CHARACTERIZATION

To model the Waste Isolation Pilot Plant (WIPP) disposal system* for a performance assessment requires gathering available information about the wastes it will contain, the proposed design of the repository, the geology and hydrology of the surrounding site, and the physical processes that operate there.** Gathering this information is termed system characterization. It is a vital step in any model development program (see Section 3.2, Grouping Features, Events, and Processes into Scenarios) and the first step of a performance assessment (PA). Model development and system characterization can drive one another as PA methodology evolves. System characterization determines the kinds of models that must be designed. The data requirements of the resultant models determine the kinds of additional measurements that must be carried out. These, in turn, can redefine the models in various ways, which, in turn, can redefine the data needs. Thus, each activity can steer the development of the other.

This chapter describes (1) the geologic character of the site and natural barrier system and (2) waste inventory and repository design of engineered barrier systems used in the 1990-1992 PA calculations (see Figure 2.0).

---

* A disposal system is any combination of engineered and natural barriers that isolate transuranic spent nuclear fuel, or radioactive waste after disposal [40 CFR 191.12(a)]. The natural barriers extend to the accessible environment.

** The general environment as used in 46 CFR 191. Subpart A is described as the "total terrestrial, atmospheric, and aquatic environments outside sites within which any activity, operation, or process associated with the management and storage of ... radioactive waste is conducted" (Section 191.02).
2.0 Disposal System and Regional Characterization
2.1 Character of the WIPP Site

The Waste Isolation Pilot Plant (WIPP) is located in semiarid rangeland in southeastern New Mexico. Population density close to the WIPP is very low. Fewer than 30 permanent residents live within a 16-km (10-mi) radius of the repository. Very little of the well water within 16 km (10 mi) of the WIPP is used for human consumption, largely because the water contains significant concentrations of dissolved salts. The surrounding area is used primarily for grazing, potash mining, and hydrocarbon production.

The WIPP repository is located in a bedded salt deposit known as the Salado Formation, roughly 655 m (2150 ft) below the land surface. Subsurface bedded salt is commonly selected for examination as waste repositories. France (NEA, 1991, p. 20), Germany (NEA, 1991, p. 20), the Netherlands (Cornelissen, 1991), Spain (NEA, 1993, p. 27) have all investigated the suitability of bedded salt or domal salt formations in their respective countries for deep disposal of radioactive wastes and Germany has ongoing investigations. Salt repositories have also been examined as part of the Commission of the European Communities (CEC) Performance Assessment of Geological Isolation Systems (PAGIS) project. Other CEC studies have considered disposal of alpha-contaminated wastes and intermediate-level wastes in salt domes located in Germany.

Salt beds possess both advantages and disadvantages for the disposal of radioactive waste. The principal advantages of salt are that it (1) entombs the waste, (2) readily consolidates and regains physical properties close to those of the original host rock properties, e.g., permeability, density, porosity, (3) can be found in regions of tectonic stability, (4) can be found relatively near the surface in many parts of the continental United States, (5) is easy to mine, (6) has extremely small groundwater fluxes, (7) is relatively homogeneous, and (8) provides good heat conduction, thus preventing excessively high temperatures in the waste and at the waste parcel/salt interfaces.

Disadvantages include the following: (1) the wastes would be difficult to retrieve safely with current mining techniques after disposal, (2) keeping a repository open would require extensive, costly maintenance, (3) drilling for natural resources, such as hydrocarbons, has often occurred in bedded salt areas; that is, the potential for co-location with economically valuable minerals exists in salt beds (see Appendix C of 40 CFR 191).

The advantageous natural features of the WIPP site include the following: (1) a lack of pre-existing boreholes (through the evaporites) within 1.6 km (1 mi) of site, (2) salt of high purity, (3) a relatively thick layer of halite, nominally from 300-m (984-ft) to 900-m (2952-ft) depth, (4) lack of extensive dissolution, (5) lack of deformation (extensive horizontal bedding), (6) tectonic stability, and (7) a relative lack of valuable resources (i.e., no known oil or gas resource at the site), and the resources that do exist can be found readily elsewhere. Advantageous social and economic characteristics at the site include (1) strong public support in the region, (2) absence of land use and strong resource conflicts, and (3) a very low population density in the area because the land surface is primarily used for grazing.

Characterization of the natural barriers of the WIPP disposal system is a lengthy task that has been ongoing since site characterization efforts began in 1973 (see Section 1.5.1, Timeline of Events for the WIPP Project). Information from site characterization activities and other sources are described in detail in many reports including those by Hiss (1975), Cheeseman (1978), Williamson (1978), Hills (1984), Ward et al. (1986), Harms and Williamson (1988), Holt and Powers (1988, 1990), Brinster (1991), Powers et al. (1978), Bechtel (1986), Lappin et al. (1989), the WIPP Final Environmental Impact Statement (FEIS) (U.S. DOE, 1980b), the WIPP Final Safety Analysis Report (FSAR) (U.S. DOE, 1990b), the WIPP Final Supplemental Environmental Impact Statement (FSEIS) (U.S. DOE, 1990c), and Volumes 2 and 3 of 1992 Preliminary Performance Assessment report for the WIPP (Sandia WIPP Project, 1992b).

The following subsections provide only a sampling of the vast amount of information available on the character of the site. They introduce the physical setting (Section 2.1.1), stratigraphy (Section 2.1.2), regional geology (Section 2.1.3), regional cross-sections (Section 2.1.4), hydrological characterization of

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* Although fairly homogeneous relative to other rock types, it is the possible heterogeneities that are of concern in any performance assessment.

** Although a scarcity of boreholes was considered an important criterion in the early 1970s, the EPA standard promulgated in 1985 and 1993 has since made the point less critical. The EPA regulation specifies that human intrusion by means of an exploratory borehole must be examined regardless of the absence of previous boreholes. Only the rate of drilling is now an issue.
2.0 Disposal System and Regional Characterization

the Culebra (Section 2.1.5), and climate variability (Section 2.1.6). The latter is not really a characteristic of the disposal system. It is an agent that acts on the disposal system, but it is convenient to discuss it here.

References


2.1 Character of the WIPP Site


2.0 Disposal System and Regional Characterization

2.1.1 Physical Setting, including Natural Resources

Physical Setting of the WIPP

The Waste Isolation Pilot Plant (WIPP) is located in southeastern New Mexico, 42 km (26 mi) east of the city of Carlsbad, 20 km (12 mi) northeast of the Pecos River, and 45 km (28 mi) west of the high plains of west Texas. The region is known locally as Los Medaños ("the Dunes"). Most sand dunes in the area are stabilized by vegetation. There is relatively little local topographic relief. Major geographical features in the region include Nash Draw, Laguna Grande de la Sal, and the Pecos River (Figure 2.1-1).

The land surface within Los Medaños slopes gradually upward to the northeast from Livingston Ridge on the eastern boundary of Nash Draw to a low ridge called "The Divide." Nash Draw, 8 km (5 mi) west of the WIPP, is a broad, shallow topographic depression with no external surface drainage. Nash Draw extends northeast about 35 km (22 mi) from the Pecos River east of Loving, New Mexico, to the Maroon Cliffs area. This feature is bounded on the east by Livingston Ridge and on the west by Qualahoa Ridge.

Laguna Grande de la Sal, about 9.5 km (6 mi) west-southwest of the WIPP, is a large playa about 3.2 km (2 mi) wide and 4.8 km (3 mi) long, formed by coalesced collapse sinks that were created by dissolution of evaporite deposits. In the geologic past, a relatively permanent, saline lake occupied the playa. In recent history, however, the lake has undergone numerous cycles of filling and evaporation in response to wet and dry seasons. Effluent from the potash, oil, and gas industries has enlarged the lake.

The Pecos River, the principal surface-water feature in southeastern New Mexico, flows southeastward, draining into the Rio Grande in western Texas. Surface drainage from the WIPP does not reach the river or its ephemeral tributaries.

Natural Resources

Potash, oil, and gas are the only known, commercially important, mineral resources in the vicinity of the WIPP. Estimates of the volumes and locations of these resources are reported by U.S. Department of Energy. Numerous productive oil and gas wells are near the WIPP. The wells generally tap Pennsylvanian strata, about 4,200 m (14,000 ft) deep. Interest in oil exploration near the WIPP Project has increased in the last few years and could be an important aspect to address regarding permanent markers for the site (Assurance Requirements of 40 CFR 191; see Section 6.1.1). Three potash mines and two associated chemical-processing plants are located between 8 and 16 km (5 and 10 mi) from the WIPP. Potash-enriched beds are found stratigraphically above the repository horizon. Neither mining of potash nor exploratory drilling for potash reserves reaches the repository horizon.

Other Salt Deposits

Salt deposits can originate in a variety of settings. Under proper conditions, thick sequences of gypsum and halite can accumulate. For an evaporite deposit to be preserved, it must be protected from subsequent dissolution by undersaturated water as has occurred at the WIPP site for 255 million years (0.004% of the regulatory period of 10,000 yr). Evaporitic sequences, protected by thicknesses of overburden sufficient to inhibit dissolution of the soluble evaporites, exist all around the world. In the United States, salt deposits are located in about half the states and cover a wide span of geologic time, ranging in age from the Silurian to the Pliocene.

References


* In this report, salt refers to evaporite deposits that are predominantly sodium chloride (NaCl). Mineralogic names such as halite (NaCl), sylvite (KCl), gypsum (CaSO₄•2H₂O), and anhydrite (CaSO₄) are used when referring to specific evaporite minerals. The term evaporite includes all of the above minerals. Evaporites are formed by the evaporation of a solution that contains dissolved solids; in this case, the solution was ancient sea water.
Figure 2.1-1. Physical setting of the WIPP (location of salt basins after Pierce and Rich, 1962).
2.1.2 Stratigraphy

The repository level of the Waste Isolation Pilot Plant (WIPP) is located within the Salado Formation (Figure 2.1-2), which consists primarily of nearly horizontal (<1 degree dip), 600-m (1968-ft) thick halite (NaCl) with occasional interbeds of minerals such as clay and anhydrites (CaSO₄) of the Late Permian Period (approximately 255 million yr old). One such anhydrite interbed, known as Marker Bed 139 (MB139), is located about 1 m (3 ft) below the repository interval and forms a potential lateral-transport pathway away from the repository. It is about 1-m (3-ft) thick and is one of about 45 interbed units within the Salado Formation.¹

Most of the strata above the Salado are more variable in elevation. They are also well known to be permeable, being host to numerous wells throughout the basin. The Rustler Formation contains the most permeable units above the repository and is therefore the most likely pathway for lateral transport of radionuclides. Below the repository reside the Castile Formation, the Bell Canyon Formation, and deeper units. Their elevations are known at relatively few points, the remainder being inferred. Because the geologic structure in the center of the Delaware Basin is uncomplicated in relation to many other sedimentary basins or metamorphic rocks, the uncertainty of inferred elevations is likely small on a regional geologic scale. The upper layer of the Castile Formation contains irregularly spaced brine reservoirs in some parts of the basin.² Current data suggest they are hydraulically isolated pockets of pressurized fluids.

References


¹ The Salado formation is the fourth principal formation below the surface. It is composed primarily of halite and is the host medium for the WIPP repository. The Salado unit is about 600-m (1968-ft) thick and consists of three informal members. The lower member is about 340-m (1115-ft) thick and is mostly halite with lesser amounts of anhydrite (CaSO₄) and polyhalite, a hard, poorly soluble, evaporite mineral (K₂MgCa₂(SO₄)₂H₂O). Anhydrite is anhydrous calcium sulfate—that is, gypsum without water or crystallization. It is denser and harder than gypsum. The WIPP repository is located in this unit about 180 m (590 ft) above the lower contact with the Castile Formation. The middle member of the Salado is the McNutt Potash Zone. It is about 110-m (360-ft) thick and consists of reddish-orange and brown halite interbedded with sylvite and langbeinite. These minerals yield potassium salts (potash) and are mined in the nearby region. The McNutt Potash Zone is separated from the lower member by a thin silty sandstone and from the upper unit by a thin anhydrite. The upper unit is 150 m (492 ft) of halite interbedded with polyhalite, anhydrite, and sandstone.

² The Rustler Formation conformally overlies the Salado Formation and is the youngest unit of the evaporite series. The formation is a cyclical series of deposits consisting of 10% carbonates (dolomite), 30% sulfates (gypsum and anhydrite), 40% salts (halite and some polyhalite), and 20% clastic rocks (mudstone and shale). In the surrounding region, the Rustler Formation rises close to the surface. There, the anhydrite component has been hydrated and converted to gypsum. The formation has an average thickness of 110 m (360 ft), but actual thicknesses range from 8 to 216 m (26 to 709 ft). The Culebra Dolomite Member of the Rustler Formation (lower dolomite), ranging in thickness from 3 to 14 m (10 to 46 ft), is a unit with brine that could provide a pathway for lateral transport of radionuclides to the accessible environment. It is composed of a microcrystalline dolomite and dolomitic limestone with solution cavities containing gypsum and anhydrite filling. Close to the repository, the dolomite has an average thickness of 7.5 m (25 ft).

³ The 500-m (1640-ft) thick Castile Formation underlies the Salado. It is the lowest and the oldest formation considered in most WIPP conceptual models. The Castile Formation consists of five principal lithologic units under the WIPP site—three anhydrite members interbedded with two halite members. Pressurized brine reservoirs have been intersected occasionally in three wells around the site and, using accepted geophysical methods, cannot be ruled out conclusively beneath the site. Brine at pressures greater than hydrostatic occurs west of the site in the Anhydrite III layer (fractured part) of the Castile Formation. The possible existence of a brine pocket beneath the repository is important. If one were present and if an exploratory borehole breached both it and the repository above, the resultant vertical brine flow could influence the release of repository materials to the brine aquifer in the Culebra. For modeling purposes, pressurized brine reservoirs are assumed to exist (without reduction in pressures) beneath the repository for the next 10,000 yr (see Section 3.2.4, Human Intrusion Summary Scenarios).
Figure 2.1-2. Stratigraphy above and below the WIPP repository (after WIPP PA Division, 1991, Vol. 3, Figure 2.2-1).
2.0 Disposal System and Regional Characterization

2.1.3 Regional Geology

The Waste Isolation Pilot Plant (WIPP) is located near the northern end of the Delaware Basin, a portion of the Permian Basin that is a structural depression. It was formed during the Late Pennsylvanian and Permian Periods, (approximately 320 to 245 million yr ago; see Figure 2.1-3). Sedimentation within the subsiding basin resulted in the deposition of up to 4,000 m (13,000 ft) of marine strata. Biological activity at the basin margins produced massive carbonate reefs that separated deep-water sediments from the shallow-water shelf sediments deposited shoreward.

During the Permian Period, subsidence in the Delaware Basin was initially rapid, resulting in deposition of the deep-water shales, sandstones, and limestones of the Delaware Mountain Group. The Bell Canyon Formation is the topmost formation of this group. Intermittent connection with the open ocean and a decrease in clastic sediment supply, possibly in response to regional tectonic adjustments, led to the deposition of the thick evaporite sequence of the Castile and Salado Formations. Anhydrites and halites of the Castile Formation are limited to the deeper portion of the basin, which is enclosed partially by rocks of the Capitan Reef Limestone. Subsidence within the basin slowed in Late Permian time. The halites of the Salado Formation (which include the host strata for the WIPP) extend outward from the basin center over the Capitan Reef and the shallow-water shelf facies. Latest Permian-age evaporites, carbonates, and clastic rocks of the Rustler Formation and the Dewey Lake Red Beds record the end of regional subsidence and include the last marine rocks deposited in southeastern New Mexico during the Paleozoic. The overlying sandstones of the Triassic-age Dockum Group reflect continental deposition and mark the onset of a period of regional tectonic stability that lasted approximately 240 million yr, until late in the Tertiary Period.

Reference

Figure 2.1-3. Regional geology. Generalized geology of the Delaware Basin (~33,000 km² [12,750 mi²]), showing the location of the Capitan Reef and the erosional limits of the bedded salt formations (after Lappin, 1988, Figure 1-4).
2.1.4 Regional Cross-Sections

Permian-age strata of the Delaware Basin now dip gently (generally less than 1 degree) to the east, and erosion has exposed progressively older units toward the western edge of the basin (Figure 2.1-4a). This tilting reflects an uplifting of the Capitan Reef that occurred during the Late Pliocene and early Pleistocene (approximately 3.5 million to 1 million yr ago) and resulted in the formation of the Guadalupe Mountains about 60 km (37 miles) west of the Waste Isolation Pilot Plant (WIPP) site. Field evidence suggests additional uplifting may have occurred during the late Pleistocene and Holocene, and some faults of the Guadalupe Mountains may have been active within the last 1,000 yr. North and east of the WIPP, the Capitan Reef has not been uplifted and remains covered (Figure 2.1-4b).

The present landscape of the Delaware Basin has been influenced by near-surface dissolution of the evaporites. Karst features created by dissolution include sinkholes, subsidence valleys, and breccia pipes. Most of these features formed during the wetter climates of the Pleistocene, although active dissolution is still occurring wherever evaporites are exposed at the surface. Some dissolution may also be occurring in the subsurface where circulating fresh groundwater comes in contact with evaporites.

References
2.1 Character of the WIPP Site

Figure 2.1-4. Regional cross-sections. Approximate locations of cross sections shown on Figure 2.1-3.
2.1.5 Hydrological Characterization of the Culebra

The Culebra Dolomite Member is a thin dolomite stratum within the Rustler Formation. At several locations, it contains various clays (argillaceous) and sands (arenaceous) with vugular spaces (small solution cavities). Near the Waste Isolation Pilot Plant (WIPP) site, it varies in thickness from about 7 m (23 ft) (at DGE-1) to about 14 m (46 ft) (at H-7). During initial WIPP siting investigations, the Culebra was considered the most important potential groundwater-transport pathway for radionuclides to the biosphere and was used in evaluating doses to humans in the 1980 Environmental Impact Statement. Subsequent agreements between the DOE and the State of New Mexico (see Section 1.5.1, Timeline of Events for the WIPP Project) called for continued characterization of the Culebra. Accordingly, the WIPP Project scientists devoted much attention to determining the hydrogeologic properties of the Culebra. It has been hydrologically sampled at 41 locations in the vicinity of the WIPP (Figure 2.1-5). Results of these tests and interpretations of measurements have been reported in detail by, for example, Beauheim, and Avis and Saulnier (see Sections 5.2.6 and 5.2.7 for use of these data).

In December 1982, when the proposed draft of 40 CFR 191 appeared, attention shifted somewhat to the controlled area, which is defined to be a vertical surface and area below the Land Withdrawal boundary. At its closest point it is .4 km (1.5 mi) from the waste disposal area (see Section 1.4.1). Because halite and interbeds transmit water poorly, lateral radionuclide transport is unlikely during the 10,000-yr regulatory period (see, for example, Rechard et al. and the discussion of the 1992 PA). Accordingly, models assume radionuclide pathways to the accessible environment through the Culebra. However, hazardous gaseous chemicals, thought to exist in potential WIPP wastes, could conceivably move that distance at depth via fractured anhydrite marker beds. Consequently, their behavior has been modeled in other calculations (Helton et al.) (see Section 3.2.1).

References


Figure 2.1-5. Location of wells used to define hydrologic parameters for Culebra Dolomite Member of Rustler Formation (WIPP PA Division, 1991, Vol. 3, Figure 2.6-3).
2.0 Disposal System and Regional Characterization

2.1.6 Climatic Variability

Climate variability is well known to be a large-scale process that could potentially affect the disposal system. The primary concern is precipitation and, ultimately, recharge of the strata above the Salado Formation, especially the Culebra Dolomite Member, which is the principal brine-bearing member of the Rustler Formation. The Culebra Dolomite is generally thought to be the most important potential groundwater-transport pathway for radionuclides to the accessible environment, assuming human intrusion provides a pathway from the repository to the Culebra (see Section 2.1.5, Hydrological Characterization of the Culebra).

Present Climate

The climate of southeastern New Mexico is arid to semiarid. Annual precipitation occurs mainly during the late summer monsoon. Winters are cool and generally dry. At present, mean annual precipitation at the Waste Isolation Pilot Plant (WIPP) site measures between 28 and 34 cm/yr (10.9 and 13.5 in/yr).  

Paleoclimates and Climatic Variability

Based on our knowledge of past climates, it is reasonable to assume climate at the WIPP will change somewhat during the next 10,000 yr. Consequently, performance-assessment hydrologic models have examined climatic variability. At present, long-term climate models are incapable of spatial resolution on the scales required for numerical predictions of future climates at the WIPP. Moreover, simulations using these models are of limited value beyond a few hundred years into the future. Direct modeling of climate variability during the next 10,000 yr has not been attempted for WIPP performance assessments. Instead, performance-assessment modeling uses past climates to set limits for future variability (see Figure 2.1-6). The illustrated function is not a predictive function for future precipitation. Rather, it is a simplistic function that illustrates the sorts of variabilities that might occur. The magnitude of climatic variabilities caused by human-induced changes in the CO₂ composition of the Earth’s atmosphere is uncertain. Presently available models of climatic response to an enhanced greenhouse effect predict changes no greater in magnitude than those of the Pleistocene, although predicted rates of change are greater. Thus, the use of a Pleistocene analog for future climatic extremes remains appropriate.

References


2.1 Character of the WIPP Site

\[ \frac{r_f}{r_p} = \left( \frac{3A_m + 1}{4} \right) \left( \frac{A_m - 1}{2} \right) \left( \cos \theta t + \frac{1}{2} \cos(\phi t) - \sin \phi t \right) \]

where

- \( r_f \) = future mean annual precipitation
- \( r_p \) = present mean annual precipitation
- \( A_m \) = amplitude scaling factor (i.e., past precipitation maximum was \( A_m \) times the present)
- \( \theta \) = frequency parameter for Pleistocene glaciations = \( 3.3 \times 10^{-12} \) rad/s (60,000 yr period)
- \( \phi \) = frequency parameter for Holocene-type climatic fluctuations = \( 1.15 \times 10^{-11} \) rad/s (2750 yr period)
- \( t \) = time(s)

![Graph showing modeled average annual precipitation fluctuations in next 10,000 yr and comparison with surmised paleoprecipitation for past 30,000 yr (after Swift, 1993).](image)

Figure 2.1-6. Modeled average annual precipitation fluctuations in next 10,000 yr and comparison with surmised paleoprecipitation for past 30,000 yr (after Swift, 1993).
2.0 Disposal System and Regional Characterization
2.2 Properties of the Waste

Waste Isolation Pilot Plant (WIPP) wastes consist of laboratory and production materials such as glassware, metal pipes, spent solvents that are sorbed or solidified, disposable laboratory clothing, cleaning rags, and solidified sludges (see Figure 2.2). These wastes are contaminated by alpha-emitting transuranic (TRU) elements. Any waste that is contaminated with alpha (α)-emitting transuranic radionuclides having half-lives greater than 20 yr and has activities greater than 100 nCi/g, is considered TRU waste in the United States.* Normally, the waste is any material (e.g., smocks, used tools, scrap metal, rags, etc.) that has been in contact with TRU radionuclides. TRU waste is also known as Alpha-Bearing Waste in some countries. Approximately 60 percent of the wastes may be co-contaminated with other hazardous constituents such as those defined under the Resource Conservation and Recovery Act of 1976 (Public Law 94-580 and subsequent amendments). The following subsections of Section 2.2 describe various aspects of the radionuclide inventory.

Figure 2.2. Simulated waste drums containing contact-handled TRU waste (see Section 2.2.1 for definition of contact handled).

* Other types of radioactive waste and material include high-level waste (HLW), spent nuclear fuel (SNF), and low-level waste (LLW): HLW is "... the highly radioactive material (fission products and some actinides, atomic number 89-103) resulting from the reprocessing of spent nuclear fuel, including liquid waste produced directly in reprocessing any solid material derived from such liquid waste that contains fission products in sufficient concentrations ..." (Nuclear Waste Policy Act of 1982, Public Law 97-425). SNF is "... fuel that has been withdrawn from a nuclear reactor following irradiation, the constituent elements of which have not been separated by reprocessing" (Nuclear Waste Policy Act of 1982, Public Law 97-425). Although spent nuclear fuel contains fissionable 235U, it contains too many radionuclides (primarily short-lived) that adsorb neutrons from the fission process for it to be usefully left in the reactor. Occasionally, general articles regarding radioactive waste use the term high-level waste to imply any combination of spent nuclear fuel and HLW (and sometimes transuranic waste) that requires disposal in a deep, geologic repository. The Nuclear Regulatory Commission (NRC) includes spent nuclear fuel in its definition of high-level waste. LLW is all radioactive waste other than spent nuclear fuel, high-level waste, transuranic waste, and mill tailings. In the United States, LLW is divided into three categories: A, B, and C. Category A has the lowest activity, and Category C has the highest. Some countries create a category called "Intermediate-Level Waste (ILW)" by grouping together transuranic waste and the U.S.'s Category C LLW, which requires shielding during handling.
2.2.1 Contact-Handled and Remotely Handled TRU

The transuranic (TRU) waste for which the Waste Isolation Pilot Plant (WIPP) is designed has been generated at 10 facilities that have supported the nuclear weapons complex. The waste consists of laboratory and production waste such as glassware, metal pipes, solvents that are sorbed or solidified, disposable laboratory clothing, cleaning rags, and solidified sludges. Current plans specify that most of the TRU waste generated since 1970 will be placed in the WIPP repository, with the remaining waste to be disposed of elsewhere.

As of 1992, the 10 TRU waste generator and/or storage sites that are scheduled to ship waste to the WIPP are (1) Argonne National Laboratory-East (Argonne), Illinois; (2) Hanford Reservation (Hanford), Washington; (3) Idaho National Engineering Laboratory (Idaho Lab), Idaho; (4) Los Alamos National Laboratory (Los Alamos), New Mexico; (5) Lawrence Livermore National Laboratory (Livermore), California; (6) Mound Laboratory (Mound), Ohio; (7) Nevada Test Site (Nevada Site), Nevada; (8) Oak Ridge National Laboratory (Oak Ridge), Tennessee; (9) Rocky Flats Plant (Rocky Flats), Colorado; and (10) Savannah River Site (Savannah River), South Carolina.

TRU waste is waste contaminated by alpha-emitting elements having atomic numbers greater than uranium (i.e., >92), half-lives greater than 20 yr, and an activity greater than 100 nCi/g. Other contaminants include uranium and several radionuclides with half-lives less than 20 yr. Approximately 60 percent of the waste may be co-contaminated with materials considered hazardous under the Resource Conservation and Recovery Act of 1976, e.g., lead.

Contact-Handled Waste

Radioactive waste that emits alpha radiation, although dangerous if inhaled or ingested, is not hazardous if contact is external and if the external dose rate is $5.6 \times 10^{-3}$ Sv/s (200 mrem/h) or less. Most of the WIPP waste falls in this category. It can, therefore, be contact-handled (CH), which means people can handle waste drums and boxes without wearing special shielding. All 10 waste generator and/or storage sites are scheduled to send CH-TRU waste to the WIPP. The estimated CH waste contributions used in 1991 PA calculations, from each of these 10 producer sites, expressed in curies, is shown in the upper portion of Figure 2.2-1.

Remotely Handled Waste

Because some surface dose rates exceed $5.6 \times 10^{-2}$ Sv/s (200 mrem/h), a portion of the TRU waste must be transported and handled in shielded casks. These wastes are known as remotely handled (RH) wastes. No surface dose rates of RH-TRU canisters can exceed $2.8 \times 10^{-3}$ Sv/s (1000 mrem/h). No more than 5 percent of the canisters can exceed $2.8 \times 10^{-4}$ Sv/s (100 rem/h). The volume of RH TRU wastes must be less than 250,000 ft$^3$ (7080 m$^3$), and the total curie content of TRU radionuclides must be less than $5.1 \times 10^{6}$ Ci ($1.89 \times 10^{17}$ Bq) according to legal agreements between the Department of Energy and the State of New Mexico. Only 5 of the 10 waste generator and/or storage sites are scheduled to send RH-TRU waste to the WIPP. The projected RH waste contributions from each of these five sites expressed in curies, as used for the 1991 performance assessment calculations, is shown in the lower portion of Figure 2.2-1.

References

Figure 2.2-1. Anticipated contributions to radionuclide inventory for contact-handled and remotely handled waste assumed in 1991 performance assessment (WIPP PA Division, 1991, Vol. 3, Figure 3.3-4). Not all radionuclides are transuranic and so totals of activity do not reflect totals of activity of transuranic radionuclides [radionuclides with atomic numbers greater than uranium (92)].
2.0 Disposal System and Regional Characterization

2.2.2 Radioactive Decay

Subpart B of 40 CFR 191 sets release limits in curies for isotopes of americium, carbon, cesium, iodine, neptunium, plutonium, radium, strontium, technetium, thorium, tin, and uranium, as well as for certain other radionuclides (see Section 6.1.2, Environmental Protection Agency Release Limits). Although the initial Waste Isolation Pilot Plant inventory contains little or none of some of the listed nuclides, they may be produced as a result of radioactive decay (by either alpha or beta emission*) and must be accounted for in the compliance evaluation. Moreover, radionuclides not listed in Subpart B must be accounted for if they would contribute to human doses used in Environmental Impact Statements required by the National Environmental Policy Act of 1969 (e.g., $^{210}$Pb).

Four decay chains for the initial radionuclides in the contact-handled (CH) transuranic (TRU) inventory are shown in the accompanying Figure 2.2-2. Note that many of the daughter radionuclides have extremely short half-lives.**

The remotely handled (RH) inventory decay chains include the chains in the CH inventory plus three other chains originating from cesium-137, promethium-147, and strontium-90.

In the 1992 performance assessment (PA) calculations, 23 of the 70 CH radionuclides shown in Figure 2.2-2, were considered to be major contributors to the inventory. They were used to calculate the radionuclide release from drilling into the repository, bringing cuttings to the surface, and calculating concentration within the repository prior to transport to the Culebra. Nine radionuclides of the 23 were considered in the 1992 PA calculations for the much longer-term transport through the overlying Culebra. These nine radionuclides comprise 99% of the normalized activity, and omitting radium-226, comprise 98% of the normalized activity (see Section 2.2.3).

References


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* An alpha (α) particle is a helium nucleus (2 protons and 2 neutrons, where a neutron is a basic atomic particle that is electronically neutral and has nearly the same weight as the positively-charged proton). A beta (β) particle is a high-energy electron, or positron. Both constitute types of radiation.

** Half-life is defined as the time required for half the atoms of a radioactive substance to decay.
Figure 2.2-2. Radioactive decay chains of contact-handled transuranic waste (WIPP PA Division, 1991, Vol. 3, Figure 3.3-5).
2.2.3 Changes in Radionuclide Activity

Figure 2.2-3 shows the temporal changes in radionuclide activity in a panel of the Waste Isolation Pilot Plant (WIPP) repository that occurs as a result of radioactive decay for the eight most important radionuclides. Activities are normalized using limits set in the Environmental Protection Agency's (EPA's) long-term disposal regulations (40 CFR 191). The activity plotted for each of the eight radionuclides is the total curies in the inventory normalized by the EPA release limits (see Section 6.1.2, Environmental Protection Agency Release Limits). Some radionuclides in the decay chains are not considered in performance assessment calculations. At 10,000 yr, the total normalized activity in a panel for all omitted radionuclides is less than 2 percent of the EPA limit. (Inclusion of radium-226 drops the total normalized activity to one percent.)

References


Figure 2.2-3. Changes in radionuclide activity of waste in (based on the inventory used in 1991 performance assessment calculations) a) activity unnormalized, b) and the one WIPP panel normalized by number of panels in the WIPP (9.49), waste unit factor 4.225 (million curies in 1992), and the EPA release limits (usually 1000) (see Section 6.1.2) (see WIPP PA Department, 1993, App. D, for a similar plot of the time-dependent inventory).²
2.0 Disposal System and Regional Characterization
2.3 Design of the Repository (Engineered Barrier)

As defined in 40 CFR 191 (Section 191.12), a barrier "means any material or structure that prevents or substantially delays movement of water or radionuclides toward the accessible environment." An engineered barrier is any human-designed barrier of the waste-disposal system. As used herein, the engineered barrier includes shafts, boreholes, and their seals. Note that the definition in the Nuclear Regulatory Commission 10 CFR 60 is narrower and omits shafts, boreholes, and their seals in its definition.

When the Waste Isolation Pilot Plant repository is completed, the disposal area is expected to consist of eight panels of seven rooms each and two equivalent panels in the central drifts. Because the WIPP is a research and development facility, an extensive experimental area has already been excavated and is in use north of the waste-disposal area. As each panel of the disposal area is filled with wastes, the next panel will be mined. As modeled in the 1990-1992 PA calculations, each panel was assumed to have backfilled and sealed, and access ways will be sealed off from the shafts.

The following three subsections describe the repository layout, emplacement of waste, and general sealing strategy.

References


2.3.1 Repository Layout

The Waste Isolation Pilot Plant (WIPP) repository (Figure 2.3-1) is a single-level, $15 \times 10^4$ m$^2$ (38-acre), underground disposal facility constructed within a single, nearly level, stratigraphic interval (it dips to the south $< 1$ degree). As Figure 2.3-1 shows, the repository level consists of an experimental region at the northern end, an operations region with shafts to the surface in the center for waste-handling and repository equipment maintenance, and a disposal region at the southern end. The disposal region will ultimately contain access drifts and eight waste-emplacement panels. Drifts will eventually be used for waste emplacement, thereby providing the equivalent of an additional two panels for waste emplacement. At present, only the first panel has been excavated.

All underground horizontal openings are rectangular in cross section. The emplacement area drifts are 4.0-m (13-ft) high by 7.6-m (25-ft) wide. Disposal rooms are 4.0-m (13-ft) high, 10.1-m (33-ft) wide, and 91.4 m (300-ft) long. Pillars between rooms are 30.5-m (100-ft) wide. The eight waste-emplacement panels will each have an initial volume of $46,000$ m$^3$ ($1.6 \times 10^6$ ft$^3$). The northern and southern drift emplacement areas will have initial volumes of $35,000$ m$^3$ ($1.2 \times 10^6$ ft$^3$) and $32,000$ m$^3$ ($1.1 \times 10^6$ ft$^3$), respectively ($\sim 3,000$ m$^3$ difference). Thus, the overall, initial, waste-emplacement volume will be about $435,000$ m$^3$ ($1.5 \times 10^7$ ft$^3$). The design waste-disposal volume is $1.756 \times 10^6$ m$^3$ ($6.2 \times 10^6$ ft$^3$) or about 40 percent of the excavated volume. The remaining volume was assumed to be partially filled with backfill (e.g., crushed salt) (see Section 2.3.3, Sealing) in the 1989-1992 performance assessment (PA) calculations.

The four vertical access shafts in the operations area include the Air Intake Shaft, the Exhaust Shaft, the Salt Handling Shaft, and the Waste Shaft. They are cylindrical in shape and range from 6.2 m (20 ft) to 3.6 m (12 ft) in diameter. All the shafts in the units above the Salado Formation are lined to prevent groundwater inflow and thereby enhance stability. All four shafts were assumed sealed and filled upon decommissioning of the WIPP in the 1989-1992 PA calculations (see Section 2.3.3, Sealing).

References


* Repository is the portion of a waste disposal facility that includes the waste panels, access drifts, and access shafts. The repository does not include the undisturbed host rock.

** Shaft is an approximately vertically or steeply inclined passageway from the ground surface to the underground level of the disposal region.

*** Drift or access drift is an approximately horizontally excavated underground passageway from the shaft(s) to the mined panels and room(s).

† Panel is a grouping of pillars and rooms; in the WIPP there are seven rooms per panel.

‡ Room is an excavated cavity for disposal of waste. It is part of a panel.

§ Pillar is a block of rock left intact to support the overlying strata of the excavations.

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Figure 2.3-1. Planned dimensions, in meters, of the WIPP repository (dimensions originally specified in units of feet) (WIPP PA Division, 1991, Vol. 3, Figure 3.1-2).
2.0 Disposal System and Regional Characterization

2.3.2 Emplacement of Waste

Contact-Handled Transuranic Waste

Current plans for transporting contact-handled (CH) transuranic (TRU) waste to the Waste Isolation Pilot Plant (WIPP) call for shipping it in 55-gal steel drums [0.892-m (2.93-ft) high, 0.602-m (1.98-ft) diameter] or in metallic standard waste boxes that are approximately 0.94-m high x 1.3-m wide x 1.8-m long (3-ft high x 4.3-ft wide x 6-ft long). Waste currently stored in containers other than 55-gal drums and standard waste boxes will be repackaged in standard waste boxes. TRUPACT (Transuranic Package Transporter) II, the transportation container designed for trucking TRU waste to the WIPP (see Figure 2.3-2a), has space for two seven-pack units of drums or two standard waste boxes.

At the WIPP, the seven-pack units will be removed from the low bay trailer, and then transported to the waste disposal rooms where they were assumed to be and stacked three high and six wide across the room (see Figure 2.3-2b). In the ideal packing configuration, a total of 6,804 drums (972 seven-pack units) can be placed in one room. The ideal packing configuration for the standard waste boxes is three high and six across the room for a total of 900. Seven-packs and standard waste boxes may be intermixed, as practical.

Remotely Handled Transuranic Waste

The reference canister design for the remotely handled (RH) TRU waste is a right-circular cylinder of outside diameter 0.65-m (26-in.) and length 3 m (10 ft). It is made of 6.35 mm (0.25-in.) carbon steel plate. In the reference design, both end caps are welded, as is the handling point. Inside, the waste occupies about 0.89 m³ (30 ft³). Currently, RH-TRU waste is shipped in commercially available casks. The Department of Energy has plans for developing a new cask (NuPack 72B) specifically for RH canisters.

The 1989-1992 PA calculations emplaced one RH-TRU canister horizontally every 2.4 m (8 ft) into the drift and room walls of the WIPP Repository (see Section 2.3.1). Based on this technique, the capacity in each panel for RH-TRU canisters along drifts and rooms 10-m wide is 874 canisters or about 6,000 m³ (214,300 ft³). The intended capacity of the repository for RH-TRU waste is 7,080 m³ (250,000 ft³); hence, additional methods may be explored to find additional space.

References

Figure 2.3-2a. Transportation of contact-handled transuranic (CH-TRU) waste.
Figure 2.3-2b. Ideal packing of waste drums in rooms and 10-m-wide (33-ft-wide) access drifts envisioned for 1990-1992 performance assessment calculations (WIPP PA Division, 1991, Vol. 3, Figure 3.1-3).
2.3.3 Sealing


As envisioned in the 1990-1992 performance assessment calculations (see Figure 2.3-3), the entire underground facility and shafts (see Sections 1.4.1 and 2.3.1 for definitions) would be backfilled, primarily with crushed salt to limit the creation of a preferred pathway for contaminant migration. Portions of the backfill” emplaced at several locations within the shafts and various drifts would be specially prepared from preconsolidated salt with concrete plugs. It would serve to protect the ordinary backfill from fluids (gases or liquids). Inhibiting fluid flow likely hastens backfill consolidation and thus increases the likelihood that the salt backfill would rapidly (< 100 yr) assume properties near to those of the surrounding host rock. Within the Waste Isolation Pilot Plant (WIPP) Project, prepared backfill plugs are termed “seals.”

The strategy for sealing combines both short- and long-term components. Preconsolidated crushed salt is the principal long-term component in the Salado Formation. Bentonite clay, a swelling clay material shown to be stable and to have low permeability to brines, is the principal long-term component in the overlying Rustler Formation. Bentonite is a common term applied to clay containing montmorillonite as the predominate mineral. Concrete is the principal short-term component at both locations.

Short-term seals provide the initial sealing functions necessary until the long-term seal components and remaining backfill become adequately reconsolidated. Preconsolidated crushed-salt and clay components are assumed to become fully functional for sealing within 100 yr after emplacement. At that time, the long-term seals and backfill are assumed to take over all sealing functions.

Seal Locations

In the reference design, multicomponent seals between 30- and 40-m (100- and 130-ft) long were used in each of the entrances to the waste-disposal panels and in selected access drifts. Furthermore, the entire length of all shafts between the Rustler Formation and the repository level were "seals." Seals near the Rustler Formation (upper shaft and water-bearing zone seals) serve to limit vertical brine flow from water-bearing zones down to the crushed-salt backfill. Seals within the drifts were thought to reduce horizontal fluid flow (gas and brine) within the underground facility during operations.

References


* Backfill is the material used to fill the shafts, access drifts, and other excavated openings. Special types of backfill include concrete and bentonite clay plugs (seals) and optionally a mixture of bentonite clay and salt around the waste parcel (backfill-buffer).

** In 10 CFR 60, Section 60.134, the term "seals" is used only in reference to material backfilling the shafts. In the WIPP, the term is also applied to specially prepared backfill with concrete components in the drift as well as the shafts.

*** The purpose of the reference seal design, which Sandia has developed for sealing the WIPP repository, was to provide a common basis for model calculations. The reference design is a starting point for developing experiments and analysis from which a determined design will evolve. More recent options for backfill and seal design differ from those used here and are described by Van Sambeek et al. ^2, a report describing the more current options is in preparation.

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2.3 Design of the Repository (Engineered Barrier)

Figure 2.3-3. Diagram of typical sealed shaft envisioned for 1990-1992 performance assessment calculations (WIPP PA Division, 1991, Vol. 3, Figure 3.2-1).
2.0 Disposal System and Regional Characterization
3.0 SCENARIO DEVELOPMENT

Scenario development encompasses the processes of deciding (a) what may happen to the disposal system in the future and (b) how to model what may happen for effective consequence analysis. It is the second phase of conceptual-model development, the first phase being disposal system and regional characterization (see Section 2.0). System characterization and scenario development together establish how scientific reality will be represented in a conceptual model(s). Mathematically, a "scenario" is the subset of all features, events, and processes characterizing a disposal system incorporated into a conceptual model of that system. In common terminology it is "an outline of a hypothetical chain of events."(See also Section 1.1.2, Multiple Iterations: a Performance Assessment Strategy. There, scenarios are the first elements in a set of ordered triplets. They reply to the question, "What can happen?"

Although much scientific modeling is not done with scenario development as a formal step, it is useful and one aspect of a performance assessment (or probabilistic risk assessment) that sets it apart from small-scale, scientific modeling.

The scenario-development process entails selecting features (e.g., a brine reservoir under the repository), events (e.g., humans drilling into the repository), and processes (e.g., generation of gas in the repository after disposal of the wastes) relevant to the functioning of the repository. In part, scenario development is a heuristic process and for the 1990-1992 calculations consisted of the following steps:

1. Identify and list the full scope of features, events, and processes relevant to the functioning of the disposal system. This list is known as "the universe" (of discourse).

2. Select for consideration those features, events, and/or processes that might reasonably contribute to contaminant releases to a regulatory endpoint such as the accessible environment.

3. Group these features, events, and processes into summary scenarios,\[\textsuperscript{††}\] omitting elements having (a) exceedingly low probabilities of occurrence, (b) exceedingly low consequences, or (c) no role in accepted definitions of the calculation (normally based on guidance from Appendix C of 40 CFR 191). Upon completion of this step, a set of comprehensive, mutually exclusive summary scenarios for consequence analysis usually exists.

4. Create conceptual models based on (a) established disposal-system characteristics and (b) the selected and grouped features, events, and processes.

5. Design performance-assessment calculations based on these conceptual models. If desirable, subdivide the summary scenarios into computational scenarios.

The first two steps are discussed in Section 3.1, the third step in Section 3.2, and parts of the last two steps in Section 3.3. The majority of the last two steps is more conveniently described in conjunction with the probability and consequence modeling treated in Chapters 4 and 5, respectively.\[\textsuperscript{±}\]

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\[\textsuperscript{*}\] A feature is an aspect or condition of the disposal system that influences the release and/or transport of contaminants.

\[\textsuperscript{**}\] An event is a natural or anthropogenic phenomenon that occurs over a small portion of the time frame of interest, in other words, a "short-term" phenomenon.

\[\textsuperscript{***}\] A physical process is a natural or anthropogenic phenomenon that occurs over a significant portion of the time frame of interest, in other words, a "long-term" phenomenon.

\[\textsuperscript{†}\] Once a mathematical model of the disposal system has been developed, the term "scenario" can be precisely defined in terms of the parameter space of the model, that is, a scenario is a subset of the model parameter space. Elaborating, a scenario is a "class" of histories with a subset of similar parameters, where a "history" is a point in the parameter space.

\[\textsuperscript{††}\] In the WIPP, scenarios are often described as summary or computational. Summary scenarios are those scenarios retained after the first two steps of scenario development. Computational scenarios include further divisions of coarse summary scenarios into units that are computationally more convenient.

\[\textsuperscript{±}\] Other authors have used the term scenario development to refer to steps 1 through 3, exclusively, because the first three steps and the last two steps may be performed by two different groups—a scenario team and modeling team. In this report, "scenario development" will include the identification and selection of features, events, and processes, as well as the incorporation of those components into the conceptual model to acknowledge the close relationship between modeling and scenario uncertainty and the need to have close communication between individuals performing these two tasks.
3.0 Scenario Development

The heuristic nature of this process suggests that continued re-evaluation is necessary as the general inquiry about the disposal system continues (see Section 1.1.2, Multiple Iterations: a Performance Assessment Strategy). This has indeed occurred at the WIPP. The first list of scenarios to be considered was published in 1979 and differs somewhat from those presented in this report. Also, current suggestions on scenario development and scenarios to consider differ from those presented in this report.

References
3.1 Identifying Features, Events, and Processes

Assessing the performance of the Waste Isolation Pilot Plant (WIPP) disposal system requires developing models to simulate plausible future behaviors of the disposal system. Each single history \( \chi \) (here meaning one future disposal-system condition of interest) consists of a defined sequence of features, events, and processes that could lead to radionuclide release to the accessible environment during a prescribed time period. Specifically, for the WIPP and 40 CFR 191 the single-history space is the set, \( \zeta \), of chosen \( \chi \), where \( \chi \) is a single 10,000-yr WIPP history beginning at the time of decommissioning.

Innumerable histories \( \chi \) exist (i.e., there are infinitely many points in single-history space). Histories that have several attributes in common are frequently grouped together to form a scenario, \( S_j \) (i.e., a bundle of points in the single-history space). The \( S_j \) are disjoint (exclusive) subsets of \( \zeta \); in other words,

\[
\zeta = \bigcup_{j=1}^{nS} S_j
\]

where \( nS \) is the total number of scenario subsets.

An important part of any performance assessment is the discretization of \( \zeta \) into the sets \( S_j \), commonly referred to as scenario identification and selection. In defining the disjoint sets, the following three conditions apply: (1) estimation of consequence results \( C(S_j) \) must be computationally feasible, (2) each \( S_j \) must be sufficiently homogeneous that it is reasonable to use the same consequence result (for all elements of the subset \( S_j \)), and (3) determination of a probability \( P(S_j) \) must be possible for each \( S_j \).

As part of the scenario-development process, the performance assessment team for the 1990, 1991, and 1992 performance assessment (PA) calculations used a formalized identification and selection procedure\(^1,2\) to identify features, events, and processes to be modeled (see Sections 3.1.1 and 3.1.2). Note that although this list was extensive, it must be viewed as but a starting point for the analysis. Because so much of the disposal system is characterized rather than designed, future additions to the "universe" of possibilities remain a likelihood.

The basic features, events, and processes selected for modeling in the PAs summarized in this report are described below.

**Features.** The basic features include seals in shafts and between panels; an overlying, fractured brine aquifer; anhydrite beds slightly above or below the repository horizon, full saturation of the salt; and a possible underlying pressurized brine reservoir.

**Events.** The basic events include human intrusion and its absence.

**Processes.** The basic processes (i.e., long-term phenomena) include creep of salt around the waste, gas generation within the waste because of container corrosion (drum or box) of microbial degradation of organics, two-phase (brine and gas) Darcy flow in and around the repository, and hydrological transport through fractures. Colloid transport suspended solids was not treated. Because of fractures, increased permeability formed by locally generated gas was not considered.

The two subsections that follow elaborate on the identification and selection procedure and provide an example of the initial "comprehensive list" of features, events, and procedures considered for the WIPP.

**References**


*Scenario selection is a necessary but sometimes a vague step in the construction of a model of a repository system in which the analyst(s) identify the natural and anthropogenic phenomena that might play a significant role in measuring the performance of the system. As stated in Chapter 3.0, once a mathematical model of the disposal system has been developed, the single history space \( \zeta \) can be defined in terms of the parameter space \( D \) used in discussions for the remainder of the report. The single history space \( \zeta \) is isomorphic (i.e., has a one-to-one correspondence) with the parameter space \( D \).
3.0 Scenario Development

3.1.1 Identification and Selection Procedures

Identification and selection of features, events, and processes for use in performance assessments (PAs) of the Waste Isolation Pilot Plant (WIPP) are based on the following procedure (Figure 3.1-1):1,2:

1. **Identifying the "comprehensive list" of features, events, and processes.** An initial list of features, events, and processes is developed as either an original list or adopted (or adapted) from one or more existing sources. The question of whether or not a list is comprehensive must be addressed for compliance assessment regardless of which approach is selected. (See Section 3.1.2 for more detail.)

2. **Providing rough estimates of probabilities and consequences of features, events, and processes.** PA analysts use judgment, existing data, and simple modeling to develop rough estimates of probabilities as more thoroughly described below. The estimates are then used to screen features, events, and processes.

3. **Screening features, events, and processes to establish history space.** Three criteria listed below are used to eliminate from scenario development those events and processes that are not applicable to a specific disposal system or that do not have the potential of contributing significantly to the performance measure (e.g., integrated radionuclide releases).

   **Regulatory guidance.** Guidance in 40 CFR 191 restricts events and processes that must be included in PAs. This guidance (a) limits assessments to the 10,000-yr time period immediately after disposal-facility closure, (b) limits consideration of inadvertent human intrusion, and (c) limits the severity of human intrusions at the disposal-facility location.

   **Probability of occurrence.** Guidance in Appendix C of 40 CFR 191 states that events and processes estimated to have a probability of occurrence less than 1/10,000 in 10,000 years need not be considered. The philosophy behind this screening criterion is that extremely rare events and/or processes should not be permitted to influence the performance measure for a disposal system no matter how severe the specific consequence associated with such events and processes might be. "Physical reasonableness" is also considered and may be classified as a subset of probability of occurrence. This screening is based on subjective judgment derived from logical arguments as to whether conditions can exist within the period of regulatory concern that will result in the occurrence of a particular event or process of sufficient magnitude to affect disposal-system performance. The logical arguments are based on available data and information, sometimes supplemented by calculations. In the WIPP PA, the distinction between probability of occurrence and physical reasonableness as screening criteria is the difference between (1) the ability to assign a distinct albeit small probability to an event (for example, a significant meteorite impact) versus (2) the inability to assign a meaningful probability at all because no such event has ever occurred (for example, glaciation at the WIPP site). Events in the second category have inordinately low probabilities and seem "physically unreasonable" during the next 10,000 yr.

   **Consequence.** Regardless of likelihood, if an event or process alone or in combination with other events and processes has little to no potential to affect the performance of the disposal system (e.g., through the alteration of transport pathways or the creation of new pathways), it may be omitted, providing there is a reasonable expectation that cumulative releases would remain essentially unchanged by the omission. Simplified conceptual and mathematical models are used to estimate consequences of single events and/or processes. The possibility remains, however, that a single event or process may of itself have no consequence on the disposal system, but that it could have a measurable consequence when combined with one or more other events and processes. Consequently, combinations must also be evaluated.

References


3.1 Identifying Features, Events, and Processes

1. Identify potentially disruptive features, events, and processes
   Techniques
   • Site Characterization
   • Literature e.g. IAEA List
   • Expert Evaluations

2. Estimate probabilities and consequences
   Techniques
   • Subjective Estimate
   • Use Existing Data
   • Simple Modeling

3. Screen features, events, and processes
   Criteria
   • Regulatory Guidance, (e.g. Only Consider Exploratory Drilling)
   • Low Probability
   • Low Consequence

See Figure 3.2-1

Figure 3.1-1. Identification and selection of features, events, and processes to model (Tierney et al., 1993).
3.1.2 The Universe of Features, Events, and Processes

The procedure for identifying and selecting features, events, and processes begins with creating the "universe," an initial list of features, events, and processes that is developed either as an original list or adopted (adapted) from one or more existing sources (see Section 3.1.1, Identification and Selection Procedures) that is as comprehensive as necessary for the purposes of the analysis. An example of such a list was provided by the International Atomic Energy Agency in 1981.1 Another list derived from events and processes identified by a panel of experts with diverse professional backgrounds has been provided by Cranwell et al.2 The panel met in 1976 and 1977 under the auspices of the U.S. Nuclear Regulatory Commission.3 It identified events and processes that could influence the escape or affect the transport of radionuclides from a generic, engineered, disposal facility. The list was intended to be modified on site-specific and/or performance-measure bases. Figure 3.1-2 shows an example of a modification of the list by Guzowski.4

Note that although this list is extensive, it should be viewed as but a starting point for the analysis. Because so much of the disposal system is characterized, rather than designed, additions to the initial "universe" remain a possibility and has occurred at the WIPP. The uncertainty that all features, events, and processes have been included is a type of modeling uncertainty (that often is called "completeness uncertainty." (See Section 1.3, Types of Uncertainty in Performance Assessments.)

References


Natural Phenomena and Processes

Celestial Events
- Meteorites

Surficial Phenomena and Processes

Events
- Hurricanes
- Seiches
- Tsunamis
- Landslides and Other Mass Wasting
- Flooding

Processes
- Erosion/Sedimentation
- Glaciation
- Pluvial Periods
- Sea Level Variations
- Regional Subsidence or Uplift

Subsurface Features, Events, and Processes

Features
- Undetected Fluid Reservoirs

Events
- Earthquakes (Seismic Activity)
- Volcanic Activity
- Magmatic Activity
- Faulting

Processes
- Diapirism (Regional Subsidence or Uplift)
- Dissolution Cavities
- Interconnected Fracture Systems

Human-Induced Events and Processes

Inadvertent Intrusions
- Mining
- Drilling
- Waste Injection Wells
- Explosions

Hydrologic Stresses
- Withdrawal Wells
- Irrigation
- Damming of Streams

Waste- and Repository-Induced Processes

Subsidence and Caving
Shaft and Borehole Seal Degradation
Thermally Induced Stress/Fracturing in Host Rock
Excavation-Induced Stress/Fracturing in Host Rock

Figure 3.1-2. Original comprehensive list of potentially disruptive events, features, and processes affecting a generic disposal system based on work of a Nuclear Regulatory Commission Panel3 (after Guzowski, 1990).4

3-7
3.0 Scenario Development
3.2 Grouping Features, Events, and Processes into Scenarios

After identifying features, events, and processes to be modeled, the parameter space can be grouped into scenarios. The advantage of scenario groupings, called summary scenarios, is that attention in the analysis can be focused on selected events and processes. Grouping is feasible if the probabilities of residing in certain regions of the sample space are easily calculated. At this stage of scenario development, it is assumed that behavior within the summary scenarios is similar enough that a representative (or a key subset) single history can characterize the whole subset. The scenarios retained for consequence analysis in the 1990, 1991, and 1992 performance-assessment calculations belong to two principal categories: undisturbed (base-case) performance, and disturbed (human-intrusion) performance. They are described in Sections 3.2.3 and 3.2.4.

Sections 3.2.1 and 3.2.2 describe the techniques used to arrive at the summary scenarios introduced in Sections 3.2.3 and 3.2.4.
3.0 Scenario Development

3.2.1 General Development Procedure

The general process of grouping features, events, and processes into summary scenarios was discussed in Sections 3.2.3 and 3.2.4 and consists of the following three steps (Figure 3.2-1):

1. Classifying features, events, and processes. Any of a variety of classification schemes can serve as organizational tools to aid in determining completeness. Two classification schemes are mentioned by Cranwell et al. One scheme is based on the origin of events and processes (i.e., naturally occurring, human induced, and waste/repository induced). The other is based on their primary effect on the disposal system (i.e., primarily affecting release of radionuclides from the facility or primarily affecting transport of radionuclides toward the accessible environment).

2. Combining features, events, and processes into summary scenarios. A key assumption of this step is that the various combinations of classified events and processes define all the future states of the disposal system that are of regulatory concern. In some cases, regulatory guidance can be used to eliminate selected events and processes. Thus, step two could be considered as dividing the history space into subsets. Venn diagrams assist in developing the set of summary scenarios (i.e., all possible combinations of events and processes). Each pathway through a Venn diagram results in a summary scenario that includes some and rejects other events and processes, although rejected events and processes are generally not listed. The complete diagram develops all possible combinations of events and processes located across the top of the diagram. If \( n \) is the number of events and processes, the total number of scenarios will be \( 2^n \). See Section 3.2.2, Applying the Grouping Procedure to the WIPP (Waste Isolation Pilot Plant), for an example of this diagrammatic logic. Because of the assumption that these combinations define all possible future states of the disposal system that are of regulatory concern, the sum of the probabilities of the summary scenarios developed in Figure 3.1-1 must be 1. Scenario probabilities must include values for occurrence and for nonoccurrence of all events and processes. The inclusion of non-occurring events and processes in each scenario assures that the sum of the scenario probabilities will be 1.

3. Grouping summary scenarios with similar consequences. In general, separate calculations of performance measures must be made for each summary scenario. To minimize the number of calculations, the number of distinct summary scenarios should be reduced to an absolute minimum. This reduction may be possible through a careful, logical examination of the nature of the agents (features, events, and processes) in each summary scenario and the way those agents can interact to produce consequences. In many cases, a logical, nonnumerical analysis will show that two or more summary scenarios will have identical consequences. Two summary scenarios having identical consequences may be combined in a single scenario; the probability of this single scenario is the sum of the probabilities attached to each of the two scenarios in the combination.

The application of this grouping procedure to the WIPP is described in Section 3.2.2.

References


3.2 Grouping Features, Events, and Processes into Scenarios

Optionally Classify Features, Events, and Processes
Possible Categories:
- Disruptive Source
- Natural
- Human
- Repository

Combine Features, Events, and Processes into Summary Scenarios
Aids:
- Use Classification to Group Similar Features, Events, Processes
- Use Logic Diagrams

When possible, combine those summary scenarios that logical analyses show as having identical consequences

See Figure 3.1-1

Figure 3.2-1. Grouping of features, events, and processes (which survive initial screening) into summary scenarios (Tierney et al., 1993).3
3.2.2 Applying the Grouping Procedure to the WIPP

In the scenario development process for the Waste Isolation Pilot Plant (WIPP) disposal system, several unlikely events and processes were screened out.

Exploratory drilling, potash mining near the waste panels, and water wells—these three events and processes were used to develop summary scenarios in the 1990, 1991, and 1992 performance assessment (PA) calculations. Exploratory drilling was subdivided into the following two possibilities: drilling into a waste-filled room or drift and a brine reservoir in the underlying Castile Formation (Event E1), and drilling into a waste-filled room or drift without penetrating a brine reservoir (Event E2). Mining (Event TS) was limited to potash extraction by either conventional or solution methods in areas beyond the boundaries of the waste panels. Drilling of withdrawal wells (Event E3) was limited to water wells in areas where water quantity and quality would permit water use. Retained events and processes were grouped or divided as shown in Figure 3.2.2.

The grouped events and processes are used in a decision tree to construct a preliminary set of scenarios (see Figure 3.2.2, bottom). One result of the decision tree is a base-case scenario that includes repository conditions undisturbed by potash mining or human intrusion. Figure 3.2.2 (bottom) shows all possible combinations of the first three of the four above events: For the 1990, 1991, and 1992 PA calculations, only four summary scenarios were evaluated: the base case (expected behavior of the disposal system without disruption by human intrusion) (see Section 3.2.3), E1, E2, and E1E2 (see Section 3.2.4). The drilling of withdrawal wells (E3 event) was evaluated in a National-Environmental-Policy-Act-type calculation because it provided a potential pathway through which human doses could occur (see Section 6.2, National Environmental Policy Act Simulations). The mining event (TS event) was omitted, but it could be evaluated in future performance assessments for its effect on groundwater flow in the WIPP area. Omitting this event is equivalent to assuming that subsidence has no effect on the base-case consequences calculated.

Once the summary scenarios are formed, the WIPP PA Department discretized the summary scenarios into "computational" scenarios (i.e., units of the scenario that are computationally convenient). The following assumptions were used to define computational scenarios in the 1991 and 1992 PA calculations:

1. No connections exist between panels
2. No synergistic effects result from multiple boreholes, except for E1E2-type computational scenarios
3. An E1E2-type computational scenario only occurs when intrusions of each type happen in the same panel within the same time interval, where the 10,000-yr regulatory period is divided into five time intervals
4. An E1E2-type computational scenario has the same release with more than two intrusions in one panel as with exactly two intrusions
5. In an E2-type computational scenario, a plug exists directly above the Culebra Unit in the Rustler Formation that directs flow into the Culebra, and this plug is effective for 10,000 years following decommissioning
6. In an E1-type computational scenario, a plug exists as in number five and no other plug exists to retard flow from the Castile pressurized brine reservoir
7. In an E1E2-type computational scenario, number five is true for one intrusion, and a similar plug exists between the repository and the Rustler Formation that directs flow through the penetrated waste panel toward the other intrusion in the same panel. Further, both intrusions are conservatively assumed to occur at the same time
8. Closure of the intrusion boreholes is not included

Reference

3.2 Grouping Features, Events, and Processes into Scenarios

Retained by Hunter

Groundwater Flow
Seal Performance
Leaching
Waste/Rock Interactions
Waste Effects

Drilling into Repository

Effects of Brine Pocket

Climatic Change
Effects of Mining

Nuclear Criticality

Used in Scenario Construction

Base Case Scenario

Through Waste and Pocket (E₁)
Drilling: Through Waste Only (E₂)
A Withdrawal Well (E₃)

Extreme Climatic Change (Tₐ)

Subsidence from Potash Mining (Tₛ)

Scoping calculations

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\( TS = \{X : \text{Subsidence Resulting From Solution Mining of Potash}\} \)

\( E₁ = \{X : \text{One or More Boreholes Pass Through a Waste Panel and into a Brine Pocket}\} \)

\( E₂ = \{X : \text{One or More Boreholes Pass Through a Waste Panel Without Penetration of Brine Pocket}\} \)

\( E₃ = \{X : \text{A withdrawal well-used for dose calculations only}\} \)

Superscript c (e.g., \( TS^c \)) Denotes Set Complement

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\( \chi = 10,000 \text{ yr Time History} \)

\( TS = \{X : \text{Subsidence Resulting From Solution Mining of Potash}\} \)

\( E₁ = \{X : \text{One or More Boreholes Pass Through a Waste Panel and into a Brine Pocket}\} \)

\( E₂ = \{X : \text{One or More Boreholes Pass Through a Waste Panel Without Penetration of Brine Pocket}\} \)

\( E₃ = \{X : \text{A withdrawal well-used for dose calculations only}\} \)

Superscript c (e.g., \( TS^c \)) Denotes Set Complement

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Figure 3.2-2. Development of summary scenarios for 1990-1992 performance assessment calculations.
3.2.3 Undisturbed Summary Scenario

The undisturbed scenario describes the undisturbed performance disposal system from the time of disposal and incorporates all expected changes in the system and associated uncertainties for the 10,000-yr regulatory period. As described in Section 3.1, the basic features, events, and processes considered for the 1990 through 1992 performance assessments (PAs) were as follows. The basic features important for the undisturbed scenario include seals in the shafts to limit downward movement of Culebra brine or upward movement of contaminated gas and brine from the repository (see Section 2.3.5, Sealing), an overlying, fractured brine aquifer in the Culebra Dolomite Member of the Rustler Formation, and anhydrite beds slightly above or below the repository horizon (see Section 2.1.2, Stratigraphy). Anhydrite is more brittle than halite, so fracturing within these interbeds has the potential to provide a pathway for gas and brine (and therefore, contaminants) to migrate from the repository. Because disruptive natural events with probabilities greater than 10⁻⁷ were not identified, the only basic event considered was human intrusion and is discussed in Section 3.2.4. All natural processes retained for scenario construction (e.g., climate variability) were considered to occur and be nondisruptive. The processes include hydrologic transport in fractures of the Culebra, generating gas because of container corrosion or microbial degradation of organic material (e.g., cellulose) in the waste, dynamic pressure-dependent creep of salt around the waste, and two-phase (brine and gas) Darcy flow into and around the repository in the Salado Formation. The Salado Formation is assumed to be saturated with brine throughout, but low permeability (from low porosity and lack of open fractures in the plastic salt) allows for little groundwater movement.

Two potential pathways for migration of contaminants were considered in this undisturbed scenario (Figure 3.2-3). In the first path, the pressure gradient between the waste-disposal panels and the Culebra causes brine and radionuclides to migrate either through drifts or through the anhydrite interbeds to the base of the shafts and then upward to the Culebra, which is the most permeable water-saturated unit overlying the repository. Transport may then occur laterally in the Culebra toward the subsurface boundary of the accessible environment. In the second path, brine and radionuclides migrate laterally from the undisturbed repository through thin anhydrite interbeds toward the subsurface boundary of the accessible environment within the Salado Formation. These undisturbed pathways may also function as routes for releases of hazardous gaseous chemicals (see Section 6.3, Resource Conservation and Recovery Act Simulations).

The geologic disposal system as shown in Figure 3.2-3 appears simple, but it is deceptive because all geologic and engineered barriers and their various components change slowly with time and are not independent of each other. The modeling of the processes that influences these changes with time can become quite complex. Further, even those aspects and components of the geologic disposal system that can be studied separately require consistent assumptions of behavior. Hence, a data base of model parameters used throughout the analysis is very important to the performance assessment process (see Section 4.2, Compiling Model Parameters).

Calculated aqueous releases (consequences) from the undisturbed scenario are used for the Containment Requirements, Individual Protection Requirements, and the Groundwater Protection Requirements. (Refer to Section 6.1.1, Overview of 40 CFR 191.) For the 1990-1992 PAs no radionuclide releases occurred.

Calculated gaseous releases from the undisturbed scenario were used to evaluate parameter importance in sensitivity analysis (see Section 7.1.1, Ranking Important Model Parameters).

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* "Undisturbed performance" is defined in 40 CFR 191.12 as "the predicted behavior of a disposal system, including consideration of the uncertainties in predicted behavior, if the disposal system is not disturbed by human intrusion or the occurrence of unlikely natural events." It likely is not defined in the regulation, but the WIPP Project interprets the probability cutoff of 10⁻⁷ proposed in Appendix C of 40 CFR 191 to be a suitable definition for the term.

** A sequence of episodes leading from the point of waste placement to consolidation of the waste through creep closure is postulated in Section 5.1.1, Repository Episodes Leading to Undisturbed Conditions.
3.2 Grouping Features, Events, and Processes into Scenarios

Figure 3.2-3. Undisturbed summary scenario (base case scenario) used in the 1991 and 1992 performance assessment simulations for the Resource Conservation and Recovery Act of 1976 (see Section 6.3). Heavy arrows indicate two possible pathways to the accessible environment defined in 40 CFR 191.
3.2.4 Human Intrusion Summary Scenarios

In the 1990, 1991, and 1992 performance assessments (PAs), the only disruptive event used for scenario construction (see Section 3.2.2) was inadvertent human intrusion. Appendix C of 10 CFR 191 states: “Inadvertent and intermittent intrusion by exploratory drilling for resources ... can be the most severe intrusion scenario assumed.” Consequently, the inadvertent human intrusion was assumed to be a result of exploratory drilling for oil and gas deposits using technology currently in use in the region around the WIPP. Furthermore, when modeling the human intrusion summary scenarios, the 1990, 1991, and 1992 PAs assumed future inadvertent drilling events would occur as a random process in time and space—each drilling event being independent of every other drilling event, the suite thus being mathematically describable as an ideal Poisson process (see Section 4.3.1, Using Poisson Functions to Estimate the Probability of Human Intrusion). Finally, the brine was assumed be thoroughly mixed with the entire waste contents of one panel and thus mathematically described as a “mixing cell” (see Section 5.1.8, Linkage of PANEL Code).

If the disposal area of the repository is penetrated by an exploratory borehole, radionuclides may be released in two different ways: at two different times (see also Section 5.1 Repository Modeling). First, an immediate release occurs during the drilling process, because it is assumed the drill bit directly bores vertically through a stack of contact-handled TRU waste containers (or through a single remotely handled waste container). Material within the containers is ground up by the drill bit (cuttings) and transported to the surface by the circulating drilling fluid. Additional material may be eroded from the walls of the borehole by the swirling action of the drilling fluid (cuttings) or the spalling of solid material into the hole as the panel depressurizes. It is assumed the boreholes would be plugged according to current industry standards upon abandonment. Selective degradation of these plugs leads to the possibility of much longer-term releases by the second method that is, transport up the boreholes to the aquifer in the Culebra and then laterally toward the subsurface boundary within the accessible environment.

Three representative intrusion scenarios were used in the 1990-1992 PAs (see also Section 3.2.2). Applying the Grouping Procedure to the WIPP: In the E1 scenario, a borehole penetrates the repository and a hypothetical pressurized brine reservoir in the underlying Castile Formation. In the E2 scenario, a borehole penetrates the repository and misses the hypothetical brine reservoir. In the E1E2 scenario, two or more boreholes occur: one borehole that penetrates the repository and the hypothetical brine reservoir (E1-type borehole) and a second borehole that penetrates the repository but misses the pressurized brine reservoir (E2-type borehole). The boreholes are assumed to penetrate a waste-filled room within a single panel. In all scenarios, the borehole plugs were assumed to degrade in such a way as to maximize contact between the pressurized Castile brine and panel wastes. For example, for the E1E2 scenario, the borehole that penetrates the Castile brine reservoir (E1-type borehole) is assumed to remain plugged just above the level of the waste panel; the other (E2-type borehole) is assumed to remain plugged just above the level of the Culebra aquifer. Thus, the pressure-driven brine flows through the panel before flowing up the E2 borehole to the Culebra aquifer. These plug configurations were chosen to facilitate examination of the specific scenarios and do not reflect the most realistic conditions expected.

For improved computational resolution, the three scenarios were divided further into computational scenarios (see Section 6.1.5) on the basis of time intrusion and radioactivity of the intersected wastes. Releases of cuttings were calculated for six time intervals. Five different levels of radioactivity in the intersected wastes were considered. In addition, E1-type intrusions were not analyzed explicitly but rather assumed to have the same consequences as E2-type intrusions.

Reference

Figure 3.2-4. One human intrusion summary scenario (E1E2 scenario) considered in the 1990, 1991, and 1992 performance assessment simulations for Environmental Protection Agency standard, 40 CFR 191, and the National Environmental Policy Act of 1969 (see Sections 6.1 and 6.2). Heavy arrow indicates pathway of radionuclides to accessible environment or to food chain.
3.0 Scenario Development
3.3 Modeling System Selection

Once site characterization and the choice of features, events, and processes has been completed, design of a performance assessment (PA) calculation can begin. In this section, we discuss the calculational design that was selected for the 1990, 1991, and 1992 simulations. Other design choices are discussed elsewhere. For example, simplifying assumptions made for some features, and simplifications of certain processes are discussed in Sections 3.2.3 and 3.2.4.

Consequence models may be categorized into groups that mirror the fundamental steps of a performance assessment: model design, consequence modeling, probability modeling, compliance assessment (complementary cumulative distribution function construction), and sensitivity analysis. For the Waste Isolation Pilot Plant PA, the consequence modeling category is divided into repository modeling, groundwater flow modeling, and transport modeling; scenario probability modeling and compliance assessment modeling are grouped together. Each of these categories contains a few principal modeling codes and various utility codes that support them. The linkage of these software components into a well integrated modeling system is through CAMCON.

The subsections that follow describe the modeling scales used for consequence modeling (Section 3.3.1), introduce the main modeling codes (Section 3.3.2, these modeling codes being discussed further in Section 5.0), introduce several utility codes that support the main modeling codes (Section 3.3.3), and provide further detail of CAMCON (Sections 3.3.4 and 3.3.5).

Reference


* Remember, the PA process is iterative. Thus, the site characterization may be preliminary and incomplete, and the choices of features, events, and processes may accordingly be tentative. Still, the PA can be run, although results will be preliminary and the foundations incomplete.

** As noted in Section 3.0, the incorporation of the results of features, events, and processes identification and selection into conceptual models, and the subsequent design of the PA calculation, is considered as the later part of scenario development in this report.

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3.3.1 External Scales for Consequence Models

As shown in Figure 3.3-1, there are three length scales imposed by the physical configuration of the Waste Isolation Pilot Plant disposal system.

1. The Repository Scale, which is determined by the repository/shaft/borehole system and runs a few meters to a kilometer. This domain contains the repository itself, the shaft, the immediately surrounding geology, and any intruding boreholes. Within this domain, repository phenomena are modeled, including (a) gas generation from corrosion and microbiological degradation of the waste, (b) brine movement around the waste over time, as well as (c) the hypothesized saturation of the waste by the brine reservoir following intrusion and creep closure (see Section 5.1).

2 and 3 The Local and Regional Scales include variabilities from 1 to 10 km (0.62 to 6.2 mi) and from 10 to 100 km (6.2 to 62 mi), respectively. The groundwater flow is modeled separately on two different domain and resolution scales, local and regional, to provide increased resolution in the area of primary interest immediately around the boreholes. Depending upon geological and hydrological conditions along regional boundaries, regional boundary conditions may be prescribed as values of (a) the dependent variable (Dirichlet conditions), (b) the gradient of the dependent variable (Neuman conditions), or (c) a linear combination of cases (a) and (b) (mixed conditions). Once the regional flow field is calculated, boundary conditions for the local grid, over which radionuclide transport is modeled, may be determined. This is done by interpolating the solution of the calculated groundwater flow from the regional grid onto the nodal points or elements of the superimposed local grid. The local grid is then calculated over time in such a way that the two solutions always agree at their common boundaries.

The largest external time scales are determined by the duration of the calculation itself (10,000 yr), the scales of climatic variability (a few thousand years), the times of intrusion, the half-lives of the various radionuclides (decades to millions of years), and the various flow characteristics (for example, transmissivities) in combination with the three external length scales noted above. The effects of climate change are simulated through the inclusion of a slowly varying time-dependent, regional Dirichlet boundary condition. Because there was, in the undisturbed case, no predicted liquid radionuclide transport beyond the top of the repository shaft, the regional- and local-model Culebra calculations were used only for the disturbed performance (human intrusion) calculations (see Sections 5.2 and 5.3).

Reference

3. REGIONAL SCALE
Regional (Los Medanos) Model Domain
Boundaries Set by:
• Known Head or Flux Conditions
• Scenario Requirements (e.g., Climatic Change with Increased Aquifer Recharge)
• Model Size Feasibility

2. LOCAL SCALE
Local Model Domain
Boundaries Usually Set by Transport Considerations

Maximum Size of Geologic Barrier
according to Federal Regulation 140 CFR 1911
< 5 km from Waste and < 100 km Area

1. REPOSITORY SCALE
Repository/Shaft/Borehole System
(Engineered Barrier) Includes:
• Repository Rooms, Backfill and Seals
• Direct Connection with Aquifers
  (e.g., Mine Shafts)

Figure 3.3-1. Three model scales used for consequence modeling for the Waste Isolation Pilot Plant. (Rechard, ed., 1992, Figure A-11).¹
3.3.2 The Component Computational Models

A "complete" (or "total system") consequence model, \( C \), for the Waste Isolation Pilot Plant (WIPP) disposal system predicts a consequence, \( C([x, S_j(x)]) \), for each value of the scenario, \( S_j \), and each value of the model parameter vector \( x \). The consequence model, \( C \), is actually a sequential hierarchy comprised of many component, computational models, \( M_j \), that transform variables produced by the \( M_{j+1} \) model to variables used by the next model, \( M_{j+1} \). The last model in the sequence illustrates potential releases. All models, \( M_j \), are dependent on the scenario, \( S_j \), and the complete suite of model parameters \( x = (x_1, x_2, ..., x_{np}) \).

The individual computational models (or "codes," as they are also known) are the heart of the performance assessment (PA) analysis. They are selected and/or designed by PA analysts to simulate the major physical features of the WIPP disposal system such as the following: inadvertent drilling into the repository, two-phase ground-fluid flow, source-term concentrations, aquifer flow, and radionuclide transport in the groundwater.

In the 1991 performance assessment,\(^1\) the principal, component, computational models, \( M_j \), were as shown in Figures 3.3-2a and 3.3-2b. A simple example of a partial sequence is sketched below in Figure 3.3-2a. For simplicity, a few of the major computational codes, such as CUTTINGS and GENII-S, are omitted from the example below, although they are also necessary to model various intrusion phenomena in the WIPP disposal system. CUTTINGS and GENII-S are shown in Figure 3.3-2b.

Reference


![Figure 3.3-2a. Partial linked sequence of the component computational models of the WIPP consequence model.](image)
Figure 3.3-2b. Generic computational models selected for 1991 preliminary performance assessment. The use and linkage of these models to evaluate consequences (consequence model) is described in Chapter 5.
3.3.3 Support Codes Used in the Modeling System

The codes available in the Waste Isolation Pilot Plant (WIPP) performance assessment (PA) modeling system may be categorized into various groupings according to their functions. For example, many of the specialized requirements for pre- and post-processing of input data and results, respectively, of a modeling system have been separated into individual codes that reside in the Compliance Assessment Methodology Controller (CAMCON) system. Several (but not all) of these codes, which include the mesh generation, property assignment, boundary and initial condition assignment, and visualization codes, are described here (see Figure 3.3.3) rather than in Chapters 4, 5, and 6. All the codes of the CAMCON modeling system (see Section 3.3.4) used in the 1990-1992 PA calculations were documented via on-line help commands on WIPP PA computers and by Reichard. 1

Mesh Generation Modules

GENMESH is the principal mesh-generation code that produces a rectilinear, finite-element or finite-difference mesh that is right-handed. Cartesian, rectangular, and one-, two-, or three-dimensional. User input files define the exact geometry. In addition to setting the node coordinates and mesh connectivity, GENMESH sets material regions, identifies (flags) nodes or elements for boundary conditions, and sets elevations of elements. GENMESH outputs its computed results as a computational data base file (CDB file) in Compliance Assessment Methodology Data Base (CAMDAT) (see Section 3.3.4).

GENNET is also a mesh-generation code It constructs simple one-, two-, and three-dimensional networks from a geometry specification input file. GENNET’s output is also stored in a computational data base file.

Property Assignment Modules

MATSET sets material names to specified regions (e.g., defined by GENMESH or GENNET), sets material property values, and sets attribute values into the performance-assessment computational database. CAMDAT. Both property and attribute values are obtained from either the property secondary database (usually median or mean values read from PROPERTY.SDB) (see Section 4.2) or the user-supplied MATSET input text file. Later, the user normally overwrites a subset of these parameter values with sampled values provided by running the Monte Carlo module. LHS (see Section 4.2).

ICSET assigns boundary values at nodal boundary flags and element boundary flags. The flags are defined either by the mesh generation module or by BCSET in a user input file.

BCSET assigns initial conditions. Specifically, ICSET sets CAMDAT analysis array variables: history, global, nodal, and/or element variable values, at the first time step. It obtains the values from a user file. In addition, any nodal or element variables (existing or new) can be linearly interpolated by specifying interpolation tables in the ICSET input text file.

Algebraic Manipulation Module

ALGEBRACDB is capable of performing most algebraic manipulations to prepare already existing data for transfer between analytic codes. This normally entails changing units, decomposing vectors to appropriate components, integrating over-time results at specified boundaries, and deleting redundant data. With ALGEBRACDB, an analyst can generate pertinent data external to a code by combining data already stored in CAMDAT rather than by modifying a code and thereby involving a new quality assessment.

Visualization Modules

CAMDAT data are stored and manipulated in binary format and are not, therefore, readily readable. BLOTDB is the plotting support module. It plots binary results from all main modules directly on screen by reading the CAMDAT files and plotting them in scientific units. Three plotting subroutines are available: (1) the computational mesh with contoured analysis results overlaid, (2) grid distance versus any variable, and/or (3) any variable versus any other variable. GROPE does essentially the same thing, but reports its results numerically in tabular format.

Reference

Figure 3.3-3. Software used to model the WIPP shown according to function. The computational codes for evaluating consequence under "Consequence Modeling" are discussed in Section 3.3.2 (The Component Computational Models).
3.0 Scenario Development

3.3.4 The CAMCON Modeling System

Assessing compliance of the Waste Isolation Pilot Plant (WIPP) with the Environmental Protection Agency's nuclear waste standard 40 CFR 191, Subparts B and C, is a multidisciplinary task requiring scores of codes and personnel to predict probabilistic releases into the accessible environment as a consequence of various hypothetical performance scenarios. The massiveness of the system and the scrutiny with which it will be examined leads to two general computational-system requirements, namely: flexibility and quality assurance. Because of the variety of release scenarios analyzed, the varying complexity of the models used, and the need to interchange codes readily, a flexible and versatile overall computational tool is vital. Likewise, because of the large number of repetitive computer simulations, the need to identify simulation results properly, and the need to document steps and numbers that might influence the results, a quality-assurance scheme is equally vital.

Although several software analysis systems have been built to perform the numerous computer simulations necessary for a performance assessment (PA), the Sandia WIPP PA Department chose to build the Compliance Assessment Methodology Controller (CAMCON) system (see Figure 3.3-4). The CAMCON approach accepts the disciplinary expertise represented in pre-existing codes rather than endeavoring to incorporate all the individual concepts into one, interdisciplinary, comprehensive code, and (2) allows the same managerial system to be used for individual components as well as the overall computational system as a whole (with the possible exception of substituting fast-running codes or modeling subdomains in the latter analysis when necessary). Both points are especially important for radioactive waste disposal where the calculations are under intense scrutiny and elaborate procedures are sometimes necessary to ensure that all steps taken in the analysis are documented and defensible. A PA system that is capable of handling both detailed and simplified computational models is invaluable in this regard.

The CAMCON system consists of six components: (1) a directory structure that facilitates configuration control; (2) a series of procedural files that allows an analyst to link the individual component codes and execute portions or all of a compliance assessment, CAMCONexec; (3) two data bases; (4) a set of libraries to interface with; (5) a series of help files containing instructions on use and history of updates and (6) code groupings, or modules. CAMDAT (Compliance Assessment Methodology Database) is a computational data base containing code outputs in "CDB files." It is used as the link between the computer modules and the secondary data base, which contains all WIPP parameter distributions. The primary data base contains raw measured data.

References
3.3 Modeling System Selection

Figure 3.3-4. The modeling system CAMCON. The CAMCON system consists of (1) directory structures and protocols for storing software (not shown); (2) an executive package to access modules; (3) code modules consisting of seven computational modules, one support module, one utility module, and a data base module; (4) the computational data base (CAMDAT contains ".CDB" files) and secondary data base; (5) software libraries (not shown); and (6) help files for on-line documentation (not shown). (After Rechard, 1989, Figure 1.1).4
3.3.5 CAMCON Support of Performance Assessment Calculations

The components of the Compliance Assessment Methodology CONtroller (CAMCON) modeling system provide the structural framework that supports performance-assessment (PA) calculations. The simplified drawing of this framework shown in Fig 3.3-5 provides an overview of the flow of information within PA calculations and of the numerous computational data base files (".CDB" files) produced by each Monte Carlo sample set (see Section 4.2.3, Executing Latin Hypercube Sampling).

All ".CDB" files have the same format, and any number of codes can write to a ".CDB" file. A .CDB file is generated by the very first GENMESH run. The intermediate results of all computer codes thereafter must pass through the same evolving .CDB file for each Monte Carlo simulation. This concept of tracking a run through the complex code system via its developing .CDB file is the single most important concept used by the CAMCON system to process the tasks of the compliance assessment. It controls the linking codes, the property-identifying Monte Carlo simulations, and the overall data flow. There are several advantages of linking codes by a "zig-zag" connection (see figure below) rather than by the more common serial connection.  

- Linking to a plotting code is more straightforward and though not limited to one plotting code, one general-purpose plotting code can be easily used at all phases of data analysis.
- Algebraic manipulation of the data can be easily accomplished by one standard code that can read a .CDB file and, for example, integrate stored fluxes crossing a boundary.
- Analysts can more easily change to different codes to obtain better precision, faster speed, etc.
- The code-application order is easily changed.
- Crude interactions at each time step between uncoupled codes can be attempted.
- Design of an executive package (CAMCONexec) to aid in running numerous simulations is facilitated.
- Quality assurance is straightforward because all input data, except code-control input parameters, reside within the .CDB file for each sample set.

Reference

Figure 3.3-5. The computational data base files (.CDB files), a primary component of the CAMCON system, are the behind-the-scenes structure that supports the performance assessment calculations. The calculations necessary for repository consequence modeling (Section 5.1) are shown as an example. The numerous .CDB files are not shown in subsequent figures of this report; rather, the repetitive simulations and numerous files are depicted as multiple sheets of a book (after Rechard et al., 1991, figure A-5).
3.0 Scenario Development
4.0 PROBABILITY ESTIMATION

Answering the second question in the risk triplet—How likely are things to happen? (see Section 1.2.2)—requires probability estimates. Two types of probability models are used in a performance assessment (PA). The first estimates the likelihood of uncertain (imprecisely known) model parameters by constructing distributions of their values. The construction of a probability distribution is itself an exercise in mathematical modeling and is thus validly called a probability model. The second PA probability model estimates the likelihood of scenarios (see Chapter 3, Scenario Development.) These two types of uncertainty are closely related and were introduced in Section 1.3, Types of Uncertainty in Performance Assessments.

Various degrees of formality can be used in developing probability models for both types of uncertainty. Probability models for estimating parameter uncertainty can be (1) fully objective, if sufficient high-quality data are available, or (2) more subjective, if only indirect data are available or if no data are available (e.g., the future states of society). In Waste Isolation Pilot Plant (WIPP) modeling, variations in degree of formality are more common for the first type of probability modeling because there are many parameters to be treated and great differences in the quantity and quality of the data. Examples of two different degrees of formality for the first type of probability model are presented in Section 4.1, Assigning Parameter Uncertainties.

Compilation of the hundreds of parameters required for a WIPP PA calculation is an enormous task. In Section 4.2, Compiling Model Parameters, that process is described. Section 4.2 deals with model parameters themselves, as distinct from the numerical data that characterize them.

Section 4.3, Estimating Probability of Human Intrusion Scenario, describes a probability model of the second type, that is, probability models to estimate scenario probabilities. Preliminary assessments prior to 1990 had considered a fixed number of human intrusions with fixed probabilities estimated by one individual. In the 1990-1992 PAs, the Poisson analytical function was used to evaluate the probability of inadvertent intrusion into the repository by exploratory drillers. In addition, the 1992 PA used an external expert judgment panel to estimate time-varying rates of future intrusions, taking into consideration the features of the WIPP site, repository design, and proposed institutional controls as suggested in Appendix C of 40 CFR 191. Specifically, teams of experts from outside the WIPP Project looked at (1) the nature of future societies and possible modes of intrusion and (2) the type of markers and their potential effectiveness in deterring intrusion. The time-dependent procedure that included the deterrence effect of markers and the future states of society resulted in significantly fewer intrusions (a maximum of 3 by 1,000 yr, and 4 by 10,000 yr) compared to the time invariant rate of intrusion used in 1991 and 1992 (a maximum of 8 by 1,000 yr and 10 by 10,000 yr).

Reference


4.0 Probability Estimation
4.1 Assigning Parameter Uncertainties

A model parameter is virtually any number required in a mathematical model. It may be a scalar, a vector, or a higher order quantity, and it may have a functional dependency on the dependent or independent variables of the problem. However, most Waste Isolation Pilot Plant (WIPP) performance assessment (PA) parameters are scalar quantities. An uncertain (or imprecisely known) parameter is one that cannot be assigned a single, universally accepted value. The manner in which parameter uncertainty is quantified and the magnitude of its influence on calculated results depend on the type of model parameter involved as described below.

In WIPP PAs, three types of model parameters\( ^* \) are recognized. They are (1) fixed parameters consisting of (a) model constants, (b) model-domain and model-control parameters, (c) decision or value parameters, and (d) indices for alternative models; (2) probabilistic epistemic parameters; and (3) event and feature aleatoric parameters. ** Only in categories 2 and 3 is it common to express uncertainty as a probability distribution and thus to use the techniques of uncertainty propagation (see in Section 1.3.1.)

To elaborate, model constants (category 1a) are certain, by definition. For the WIPP disposal system, they include precisely known values (for the purposes of the analysis) such as radionuclide half-lives, acceleration of gravity, etc. Model-domain parameters (category 1b) reflect the overall size and appropriate temporal and spatial mesh used in discretizing the calculation. Model-control parameters represent, for example, convergence criteria for solution algorithms. Both model-domain and model-control parameter types can be uncertain and, although it is necessary to examine how different values influence results, it is impractical to express the uncertainty as a probability distribution.

Decision and value parameters (category 1c) represent the various alternatives that are of high interest to decision makers. Index parameters (category 1d) represent model-form choices. Sometimes, different weights can be assigned to alternative models explicitly identified, and the alternatives combined to form a single “megamodel.” In both cases, this type of parameter uncertainty may be described by a distribution. However, that is uncommon when strong disagreements exist about the decisions and/or alternative model forms. The impact of decision and index parameters with strong disagreements (categories 1c and 1d) is usually evaluated with all other parameters being held constant, *ceteris paribus*, and results are presented individually. Decisions and model form alternatives not explicitly identified are treated in the analysis along with epistemic parameters described below or not at all.

Some degree of uncertainty always exists for probabilistic epistemic parameters (category 2). These include properties such as transmissivity fields whose values are uncertain because geological formations are inhomogeneous and mostly inaccessible, and therefore impossible to characterize precisely without destroying the formation. The same is true for the aleatoric parameters in category 3, which represent, for example, the times of occurrence of exploratory drilling events. The probability of occurrence of the various scenarios must be evaluated with a probability model that, in turn, has uncertain model parameters (of category 2). Apart from placing known, common-sense bounds on their ranges, these parameters are not amenable to estimation by classical techniques. This situation is true whether or not event and feature parameters are used to define scenarios. ***

The remainder of this section discusses category 2 and 3 parameters that are characterized by probability distributions. Section 4.1.1 provides examples of various types of probabilistic distributions used to characterize uncertain parameters. Section 4.1.2, describes different degrees of formalism in assigning parameter distributions. Sections 4.1.3 and 4.1.4, give examples of assigning parameter distributions (a) in a classical statistical sense and (b) with a formalized subjective interpretation.

Reference


\( ^* \) Morgan et al.\(^1 \) provide a different taxonomy, but the purpose is the same: to demonstrate that not all parameter uncertainty should be expressed and evaluated in the same way.

\( ^{**} \) Use of process parameters to describe scenarios is possible in theory, but difficult in practice. They act continuously in time rather than at discrete times, like events.

\( ^{***} \) As discussed in Chapter 3, Scenario Development, event and feature aleatoric parameters may be used to define scenarios. The influence of their uncertainty on results is described in Section 1.3.2, Propagating Aleatoric Uncertainty through Performance Assessment.
4.0 Probability Estimation

4.1.1 Characterizing Parameter Uncertainty

Characterizing the uncertainty of any parameters $x = x_1, x_2, \ldots, x_n$ of the performance assessment (PA) consequence and/or probability models requires developing a joint cumulative distribution function (CDF), $F(x)$. Usually, the joint distribution is approximated by the product of the distributions of the individual parameters, $F(x_1) \cdot F(x_2) \cdot \ldots \cdot F(x_n)$. This substitution is exact if the parameters vary independently, which is usually assumed. (However, in contradiction to this assumption, rank correlations are sometimes specified among a few of the $x_i$ during sampling.) Individual distribution functions, $F(x_i)$, are defined by individual CDFs. The CDF of a parameter, $x_i$, ideally represents what is known and what is not known about that parameter, and should reflect current knowledge of the range and likelihood of the parameter values most appropriate for consequence and/or probability modeling. It is especially true for nonlinear computational models because it is often impossible to know a priori how a bias in a parameter distribution will affect results. In other words, preselecting a bias to ensure "conservative" results is sometimes impossible with nonlinear models, especially when several linear models are linked together as in a PA.

To appropriately assign a distribution, $F(x_i)$, that reflects both the numerical discretization of the model domain and the small-scale spatial variability that may appear in measurements, both experimentalists and PA analysts (modelers) are involved. Parameter distribution characterization is not guided by a rigid series of steps because distributions must be tailored to the type of data available and to the parameter's role in PA computational models. It is possible that the $F(x_i)$ may be obtained by classical statistical techniques for some parameters (i.e., objective techniques that are easily reproduced by others. See, for example Figure 4.1-1). However, in most cases, each $F(x_i)$ will include subjective factors representing the "degree of belief" of program investigators. Subjective opinions are developed using available scientific information that a consensus developed through a suitable review process. Results of these techniques are not easily reproduced unless the methods are well documented. Examples of both methods are presented in Sections 4.1.3 and 4.1.4.

In general, a maximum entropy formalism was used to minimize the amount of spurious information and to provide a consistent procedure for constructing the CDFs. In practice, the maximum entropy formalism involves connecting data points or subjectively estimated points with straight lines.

References


* A cumulative distribution function (CDF), $F(x)$, is the integral of the probability distribution function (PDF) $f(t)$ from $t = 0$ to $x$. 

4-4
Figure 4.1-1. Examples of various probability distribution functions (dotted) and their corresponding cumulative distribution functions (solid) characterizing different kinds of parameter uncertainties (WIPP PA Division, 1991, Vol. 3, Figure 1.2-1).
4.1.2 Degree of Formalism

The degree of formalism used for the interpretation of primary (raw) data and subsequent determination of model parameters and uncertainties can vary over a wide spectrum. It ranges from (1) interpretation by an individual with general knowledge of a given subject area, to (2) interpretation and publication by a recognized expert, to (3) general interpretation by a group of consultants, to (4) formal selection of a panel of experts and formal elicitation of interpretations from the panel (see Figure 4.1-2). At one end of the spectrum, an investigator with general knowledge in a given subject area applies personal professional judgment to interpret observational data, either from personal experiments or experiments of others, and within the context of performance-assessment analysis assumptions and requirements. At the other end of the spectrum, the process of interpreting data and information can involve a group of recognized experts—called an expert judgment panel—who are formally selected from representative disciplines, nominated by various stakeholders and from whom judgments are formally elicited. The reasoning behind panel judgmental interpretations is more likely to be formally documented and thus plainly acknowledge the importance of subjective judgments in the performance assessment. Like individual professional judgments, expert-panel judgments do not create data. Rather, they combine separate pieces of existing data and related information to determine appropriate model parameters, parameter ranges, and uncertainties.¹

Performance assessments have used varying degrees of formality in the acceptance of professional judgments regarding data. The advantages of formalizing how judgments are elicited are that (1) it promotes clear and thorough documentation of how an interpretation was achieved, for example, characterizing parameter uncertainty through a cumulative probability distribution function, (2) it offers a structured procedure for gathering opinions, (3) it encourages diversity of opinion and thus guards against understating or overstating uncertainties, and (4) it brings together representatives of diverse disciplines to address interdisciplinary issues, which, in turn, (5) initiates exchanges of ideas that would take many years to occur through the open literature.¹

Reference

Figure 4.1-2. Various degrees of formalism are possible in interpreting observational data to develop model parameters appropriate for individual computational models of the WIPP consequence model.
4.1.3 Example of Data Interpretation to Evaluate Model Parameters

Excavations at the Waste Isolation Pilot Plant (WIPP) are very dry, which affects the modeling of radionuclide mobility because mobility depends critically on the presence of fluids. One hypothesized sequence of events envisions brine inflows from the surrounding bedded halite and anhydrites that will, over time, supply sufficient fluids to the repository to saturate the waste and backfill, at least partially, thus allowing for radionuclide movement (see Section 5.1, Repository Modeling). A critical parameter that affects the movement of brine into the repository is the intrinsic permeability of the halite and anhydrite beds.

Measuring intrinsic permeability of rock salt has been a demanding exercise at the WIPP, and several specialized measurement techniques have been developed. Plots of the interpreted permeability versus distance from the excavation (see Figure 4.1-3, inset) show a clear correlation between distance from the excavation, \( x \), and a decreasing trend in permeability to an asymptotic far-field value denoted as \( a \). To represent this variability, an exponential curve with undetermined asymptote (three unspecified coefficients) was used to approximate the data: \( y = a + be^{-cx} \).

For WIPP performance assessment purposes, the distribution of the far-field undisturbed permeability (the unspecified coefficient \( a \)), not the near-field, short-term disturbed permeability, is of primary interest. The distribution of \( a \) was simulated by sampling values at each of the normally distributed measurement points and repeatedly fitting the nonlinear curve to the sampled values. Because the functional form used in the non-linear regression is not unique, a hyperbolic functional form with four rather than three adjustable coefficients was also applied. The distribution of the far-field permeability was similar to that developed with an exponential approximation and, thus, apparently not unduly sensitive to the chosen functional form of the model.

References


4.1 Assigning Parameter Uncertainties

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Figure 4.1-3. Example of standard interpretation of data to evaluate the far-field cumulative distribution function (CDF) of the halite permeability.\(^5\)
4.0 Probability Estimation

4.1.4 Example of Formalized Data Interpretation

Formal procedures to elicit expert judgment arise for any of the following reasons: (1) an issue is of particular interest or sensitivity to policy makers or the public, (2) requisite data will never be available, or (3) previous performance assessment calculations have shown a particular parameter value to influence results greatly, but site-specific data or information are unavailable, conflicting, or too expensive to obtain. An example of formalized interpretations in which the requisite data will never be available (Case 2) is provided by the two groups of external experts formed to address questions regarding future states of society and how they might relate to future intrusion boreholes into the Waste Isolation Pilot Plant (WIPP). 1,2 One group of experts (called the Futures Panel) studied technology levels that might be attained by future societies and how/why these societies might inadvertently intrude into the waste panels. 1 The second group of experts (called the Markers Panel) studied how markers might be used to warn future societies about the presence of buried wastes2 and the dangers of on-site drilling. An example of the use of formalized interpretation for Case 3 is the formation of an expert panel to evaluate solubility data of radionuclides. Questions of radionuclide solubility in WIPP-repository-like environments are interdisciplinary, and a synthesis of disparate data in the literature has not yet occurred. Consequently, an expert panel was convened to examine existing data and develop plausible distributions of radionuclide solubilities for conditions thought to pertain to the WIPP repository (see Figure 4.1-4). 3,4

References


4.1 Assigning Parameter Uncertainties

Figure 4.1-4. Results of formalized interpretation of solubility data for radionuclides in the WIPP disposal room [probability density functions (PDFs) shown as Tukey box plots, whose meaning is shown for plus-6-valence uranium (U^{6+})] [after WIPP Performance Assessment Division, 1991, Figure 3.3-8].
4.0 Probability Estimation
4.2 Compiling Model Parameters

The use of a consistent set of parameters for the performance assessments was an important aspect of the 1989-1992 PA calculations and done to help coordinate the many diverse aspects of the performance analysis of the WIPP. In this section, we describe the mechanical steps usually followed to compile model parameters and to apply them in analytical models. The two previous procedural steps, (i) developing the model form (Section 3.3, Modeling System Selection) and (ii) assigning uncertainties in parameter values (Section 4.1, Assigning Parameter Uncertainties), are not disjoint. Rather, one step flows smoothly into the next as part of the overall "modeling" process. Boundaries were introduced primarily as pedagogical artifacts to help the reader understand the many diverse facets of the modeling process. However, the boundary demarking the realm of model parameter completion is real. From this point onward, the CAMCON modeling system (see Section 3.3, Modeling System Selection) provides assistance in the process of determining parameters with which to assess the performance of the Waste Isolation Pilot Plant disposal system.

Section 4.2.1 describes the gathering of model parameters. Sections 4.2.2 and 4.2.3 describe the sampling of probabilistic random parameters (see Section 4.1) for propagation (see Section 1.3.1) and parameter uncertainty (see Section 4.1) using Latin hypercube sampling.
4.0 Probability Estimation

4.2.1 Gathering and Storing Model Parameters

Three categories of data bases are used in Waste Isolation Pilot Plant (WIPP) performance assessments (PAs) and are known as the primary, secondary, and "computational" data bases. The "computational" data base is generated during each analysis and contains the calculated results generated each time one of the system's codes is exercised (see Section 3.3.4, The CAMCON Modeling System). The primary data bases contain measured field and laboratory data gathered by the experimental groups (e.g., investigators) to characterize the WIPP disposal system (see Chapter 2.0). In general, the information stored in the primary data base is controlled by the investigators. The secondary data base contains distributions of model parameters constructed specifically for the computational models. It is developed from the primary data base by PA personnel. The general procedure used to acquire parameter distributions in the 1990, 1991, and 1992 PA calculations is as follows (see Figure 4.2-1)\(^1\):  

1. **Identify Necessary Data.** Annually from 1990-1992, the PA group identified parameter sets \((x = x_1, \ldots, x_{np})\) that were necessary for PA calculations. Occasionally, the PA personnel also compiled data to aid preliminary calculations and gathered information to document the status of the data, in order to inform experimental investigators.  

2. **Set Parameter Values.** After essential model parameters had been identified, the PA group formally requested WIPP observational data from appropriate WIPP Project investigators. Ideally, investigators who provided observational data also (1) provided a statement regarding the precision of the observed data (measurement error), (2) removed known systematic errors or biases through calibration curves or other means (accuracy), (3) provided a clear statement of what was measured and the scale or representative volume over which the property was measured (representativeness), and (4) provided citable sources.\(^1\) The investigator or PA personnel may have supplemented these data with additional data and general information from various sources to bridge any remaining data gaps in the conceptual model. From this information, consistent with the manner of use in PA consequence models, the PA group then either constructed parameter distributions or used distributions provided by investigators as described in Section 4.1, Assigning Parameter Uncertainties. As this annual data-acquisition procedure was repeated from 1990-1992, some of the parameters were re-evaluated through the formal elicitation process (e.g., by expert panels. See Section 4.1.2, Degree of Formalism).  

3. **Update Secondary Data Base.** The next step was updating or entering endorsed or elicited information on the model parameters into the secondary data base. From this secondary data base, several ASCII SDB computer files are created for consequence modeling and a formal report on the model parameters is written (e.g., a model parameter report).\(^2\)  

4. **Select parameters \((x = x_1, \ldots, x_{np})\) to be sampled.** Once the secondary data base was complete, several model parameters were chosen for sampling in each annual PA based on one of the following criteria: (1) the parameter had proved to be at least moderately sensitive in previous sensitivity analysis; (2) the parameter was new and thought to be a highly or moderately imprecise, and (3) new observational data suggested a significant revision of the parameter's distribution. All other parameters were kept consistent at their median values, unless specifically noted.  

5. **Sample parameters with Latin hypercube sampling (LHS).**  

This fifth step is discussed in greater detail in Sections 4.2.2 and 4.2.3.

References


Figure 4.2-1. Overview of compilation and storage of model parameters for their eventual use by various codes in the CAMCON modeling system (after Rechard et al., Figure 1-3).
4.2.2 Latin Hypercube Sampling

The Waste Isolation Pilot Plant performance assessments use Latin hypercube sampling methods to generate samples from the distributions developed in the first step of a Monte Carlo analysis (see Section 1.3.2). Latin hypercube sampling ensures representative coverage of the full range of each variable. 1

Once cumulative distribution functions have been developed for each parameter to be sampled, Latin hypercube methods are used to generate a sample. For example, in a five-sample set, the range of each parameter is divided into five intervals of equal probability (see Figure 4.2-2, top), and one value is selected at random from each such interval. The five values thus obtained for \( x_1 \) are paired at random with five similarly obtained values for \( x_2 \). These five ordered pairs are further combined at random with the five similarly obtained values of \( x_3 \) to form five ordered triples, and so on until all sampled variables have been included. The final result is five ordered sets of different parameter values. The results of a Latin hypercube sample can be visualized in scatterplots (see Figure 4.2-2, bottom). A sample over two, normally distributed parameters from the \( n = 5 \) example is used. Five ordered pairs result.

Latin hypercube sampling has a number of desirable properties, 1 including

- full coverage ("stratification") across the range of each variable (extremes as well as midpoints)
- relatively small sample sizes
- direct estimation of means, variances, and distribution functions
- availability of a variety of techniques for sensitivity analysis

Another desirable property of Latin hypercube sampling is that it is possible to determine the effects of different distributions for the input variables on the estimated distribution for an output variable without rerunning the model. 2,3

References

Figure 4.2-2. Latin hypercube samples from cumulative distribution function of one parameter, $x_1$, [Latin hypercube samples ($n=5$)] and resulting scatterplot of joint probability space for two parameters, $x_1$ and $x_2$. 
4.2.3 Executing Latin Hypercube Sampling

The Waste Isolation Pilot Plant performance assessment codes used to execute Latin hypercube sampling (LHS) are INGRES, PRELHS, and LHS (see Figure 4.2-3).

- **INGRES®**
  
  **Function:** INGRES is the relational data-base software. It stores and manipulates distributions of model parameters.

- **PRELHS**
  
  **Function:** PRELHS translates from the ASCII.SDB file (see Section 4.2.1) to the LHS code. It extracts parameter-distribution data requested by the user from the PROPERTY.SDB file and sets up the LHS input file.

- **LHS**
  
  **Function:** LHS samples distributions of input parameters using either normal Monte Carlo sampling or the more efficient Latin hypercube sampling. LHS permits correlations (restricted pairings) between parameters. In the 1990-1992 analysis, the number of sample sets \([nK]\) was set at about \((4/3)nV\), where \(nV\) is the number of varying parameters from the total number of parameters \(nP\).

**References**


Figure 4.2-3. Linkage of software to perform Latin hypercube sampling in the 1990-1992 performance assessment calculations.
4.0 Probability Estimation
4.3 Estimating Probability of Human Intrusion Scenario

The exploratory drilling and inadvertent intrusion into the Waste Isolation Pilot Plant (WIPP) repository that occurs in the hydrocarbon-exploration scenarios are treated as random processes. That is, intrusions are treated as processes that are controlled, at least in part, by chance mechanisms. The Poisson analytic distribution function adequately describes many random processes that take place over time. Correspondingly, the Poisson distribution was assumed to describe exploratory drilling events in the 1990, 1991, and 1992 PA calculations.

Although it is formally a part of "probability estimation" in WIPP performance assessments (PAs), the coding that implements the Poisson analytic function is actually imbedded in the software that constructs the complementary cumulative distribution functions (CCDFs). The function is straightforward to evaluate and computationally easy to implement at that point in the PA simulation (see Sections 6.1.4 and 6.1.5 about constructing CCDFs).

Section 4.3.1 describes the Poisson analytic function.
4.0 Probability Estimation

4.3.1 Using Poisson Functions to Estimate the Probability of Human Intrusion

The 1990 through 1992 Models

In 1990 through 1992, the probability model for the event "unintentional intrusion into Waste Isolation Pilot Plant (WIPP) waste panels by exploratory drilling" was based on the assumption that future episodes of exploratory drilling are describable as a Poisson processes with constant intensity, \( \lambda \) (see Figure 4.3-1). Under those conditions, the probability that the waste panels are drilled through exactly \( n \) times in a period of \( T \) years is given by \[ \Pr\{N = n\} = \frac{(\lambda T)^n}{n!} e^{-\lambda T}, \quad n = 0, 1, 2, \ldots \]

The intensity of drilling, \( \lambda \), was an imprecisely known parameter assumed to be uniformly distributed within a range of 0 to 30 boreholes/\((\text{km}^2 \cdot 10^4 \text{ yr})\) for the area of the excavated disposal region (see distribution in Section 4.1.1). This maximum rate is defined in Appendix C of 40 CFR 191: "the likelihood of such inadvertent and intermittent drilling need not be taken to be greater than 30 boreholes per square kilometer per 10,000 yr for a geologic repository in proximity to sedimentary rock formations, ..." For \( \lambda_{\text{max}} = 30 \text{ boreholes}/(\text{km}^2 \cdot 10^4 \text{ yr}) \cdot [1.09 \times 10^5 \text{ m}^2] \), the average number of drilling intrusions into the disposal panels over the 10,000-yr regulatory period is 3.6.

The 1992 Model

In 1992, the probability model also used a Poisson counting process with a time-varying \( \lambda(t) \). Under those conditions, the probability, \( P_i \), that exactly \( n \) intrusions occur in a time interval, \( T_i = t_i - t_{i-1} \), is

\[ P_i[n] = \frac{[M_i]}{n!} e^{-M_i}, \]

\[ M_i = \int_{t_{i-1}}^{t_i} \lambda(t) \, dt \]

A set of intensity functions, \( \lambda(t) \), was generated using the results of the expert panels describing future states of society and efforts to construct adequate markers. The \( \lambda(t) \) were ordered by increasing values of intrusions and one intensity function randomly selected for each sample set from Monte Carlo analysis through Latin hypercube sampling (see Section 4.2.2).

References


4.3 Estimating Probability of Human Intrusion Scenario

Poisson Analytic Function

\[ P\{N=n\} = \frac{(\lambda T)^n}{n!} e^{-\lambda T}, \quad n=0,1,2,... \]

(See § 4.1.1 for distribution of \( \lambda_{\text{max}} \))

1990 and 1991 PA

\( \lambda_{\text{max}} \)

1992 PA

Time (t)

T=10,000 Yr

An average of 3.6 drilling intrusions occur in 10,000 years assuming constant \( \lambda_{\text{max}} = \left[30 \text{ boreholes/} (\text{km}^2 \cdot 10^4 \text{ yr})\right] \) times [disposal area]

Disposal area \( \sim 1.09 \times 10^5 \text{ m}^2 \)

Figure 4.3-1. Poisson analytic function model for estimating the probability of inadvertent human intrusion.
4.0 Probability Estimation
5.0 CONSEQUENCE ANALYSIS

Here, we address the question: "What are the consequences of the various hypothetical chains of events called scenarios?" (See Section 1.2.2.) The quantitative answers required by the Environmental Protection Agency are specific performance measures that must be estimated using a site-specific modeling system designed to calculate the amount of contaminants released to the accessible environment because of hypothesized features, events, and processes, and include in the answer estimates of the uncertainties associated with the illustrative calculations. This step in the performance-assessment (PA) process is referred to as consequence modeling and analysis. The "model" used for consequence modeling is actually an ordered system or hierarchy of composite models linked together.

Because a single three-dimensional consequence model having the detail necessary to simulate the features, events, and processes of the entire disposal system would require too much time and money to build and modify and too much computer capacity to solve, the consequence model is divided into four principal submodels that correspond to the major physical components of the Waste Isolation Pilot Plant (WIPP) (see Section 3.3, Modeling System Selection). Each of the four submodels is discussed in the principal four sections of this chapter: (1) repository, (2) groundwater flow, (3) radionuclide transport, and (4) biosphere transport. The repository submodel estimates the amount of radionuclides that leave the repository during drilling as drill cuttings and materials suspended and/or dissolved in drilling fluids. Radionuclides can leave the repository as a result of natural groundwater flow and leakage up plugged boreholes are also estimated. The radionuclides that escape in this manner become the source input for the groundwater-transport modeling subsystem, where groundwater transport is controlled by the groundwater-flow modeling system. Finally, the radionuclide concentrations from the transport modeling system provide source input for the biospheric-transport modeling subsystem.

In WIPP performance assessments, uncertainty in performance estimates results from (1) the existence of alternative conceptual models and (2) uncertainty in the values of certain model parameters. Uncertainty model parameters are propagated through the WIPP PA calculation through a Monte Carlo technique (see Section 1.3.1). Latin hypercube sampling is used to minimize the number of samples needed to describe parameter uncertainties adequately and thereby to minimize the number of simulations required to assess performance over the entire range of the parameter space (see Sections 4.2.2 and 4.2.3).

The primary purposes of the descriptions to follow are (1) to enlarge the cursory description of the computational models ("codes") given in Section 3.3 (Modeling System Selection), (2) to document the actual linkages between the various codes, (3) to provide a macroscopic overview of the modeling system and its component functions, (4) to strip away as much of the system's inherent complexity as is possible, and thereby (5) to expose the system's inner workings at their most transparent level. Once the calculational procedure is understood, the reader should be able to focus on the natural phenomena being modeled and the working details of the models. It is beyond the intent of this document to describe the natural science or the mathematical formulations that comprise the theoretical basis for the computational models. For information on those subjects, see the work of Helton et al. for the 1991 simulation and Volume 2 of the series of volumes describing the 1992 PA simulation.

References


* Uncertainty propagation includes methods to propagate uncertainty in model parameters through the model and, thereby, to estimate the effects of that uncertainty on the results. It is an important aspect of stochastic simulations.

** Monte Carlo methods use random sampling to integrate mathematical models approximately. The practicality of their use has increased with the advent of computers.

*** Latin hypercube sampling is a Monte Carlo sampling technique that divides the cumulative distribution function into intervals of equal probability and then samples from each interval (see Section 4.2.2).
5.0 Consequence Analysis
5.1 Repository Modeling

The first submodel of the overall consequence model is the repository submodel. It describes removal of radionuclides from the repository and introduction into the surrounding regions. Conceptually, the repository submodel is dominated by phenomena on two very different time scales* (see Figure 5-1): (1) short-term cuttings release to the surface and (2) long-term brine inflow and radionuclide dissolution. On the short time scale, fluid inflow to the repository is not required. Rather, transport results from direct contact with the bit used to drill an exploratory borehole as it passes through the repository. Wastes are transported to the surface together with halite and other drilled minerals. Specifically, on the shorter time, the repository submodel calculates contaminant releases to the accessible environment at the surface from drilling byproducts. The longer time scale model requires an inflow of fluid from a source near the repository, the source being scenario dependent. Normally, it is provided by a submodel code that is dedicated to that function. Given the inflow, another code of the repository submodel introduces into the inflow a series of radionuclide concentrations for transport out of the repository. The fluid slowly makes its way toward the accessible environment either laterally through an anhydrite layer or Marker Bed, or vertically up a repository shaft or drilled borehole to the overlying Culebra aquifer. The overall process treats mixing and flow phenomena in the waste parcel, disposal room, drifts, shafts, and backfill. Specifically, on the longer time scale, the repository submodel calculates (1) the fluid flux from a source through the disposal area of the repository and (2) the introduction of contaminant concentrations in the fluid (gas or liquid) flowing through the disposal area.

Sections 5.1.1 and 5.1.2 describe a hypothesized sequence of events for the disposal area of the repository and demonstrate the type of results calculated by repository submodels. Strictly speaking, the sequences are not scenarios because the interaction of the features, events, and processes are postulated to aid in the discussion.

Sections 5.1.3 through 5.1.6 provide examples of modeling assumptions and computational models that were actually used in past performance assessments. The short-term time scale consists of one software group, drill cuttings (see Sections 5.1.3 and 5.1.4). The long-term, brine-inflow time scale consists of two main software groups: two-phase flow and source-term modeling (see Sections 5.1.6 and 5.1.8). The three software groups produce the three primary results of the repository submodel introduced above.

Recall, WIPP disposal-system phenomena are dominated by four principal spatial scales that form the basis for the subsections of this chapter (see Section 3.3.1, External Scales for Consequence Models). The four scales are (1) repository, (2) local, (3) regional, and (4) external (surface and atmospheric).

Figure 5-1. Time scales and corresponding software groups for modeling the repository.
5.1.1 Repository Episodes Leading to Undisturbed Conditions

The following hypothesized sequence of episodes leads to so-called "undisturbed conditions" and gives an idea of the types of phenomena modeled as well as the kinds of results to be expected from the repository portion of the consequence model. These are not scenarios. They are hypothetical episodes because the interaction of features, events, and processes is postulated. The "undisturbed conditions" described here are those that may occur because of natural processes in the absence of human intervention or catastrophic natural events (see Section 5.1.2). Initially, panels of the repository would be filled with waste and in the 1990 to 1992 performance assessment (PA) calculation was assumed to be backfilled with salt. All access drifts and the experimental area to the north of the repository were also assumed to be backfilled and the shafts sealed (see Section 2.3.3, Sealing). No free brine would likely be present in the repository at that time, although MB139 might become fractured as a result of excavating repository panels or in response to initial creep into the excavated region. During the operational life of the repository, the fractures in MB139 might fill with brine from the Salado Formation (Figure 5.1-la). During the first 50 to 200 yr after decommissioning, creep would first collapse the room and then compress the voids around the waste to encapsulate it. Any brine in the salt would likely flow into the disturbed rock zone (DRZ) or remain in small pockets within the waste and panel rooms (Figure 5.1-lb). In the 1990, 1991, and 1992 PAs, the initial disturbance of the salt around the repository and the creep closure of the excavation were modeled prior to the PA calculations and thus used as inputs to the calculations.

The presence of water in the disposal rooms would promote corrosion of the steel containers and of steel wastes within them. Initially this corrosion would consume oxygen. However, once the oxygen was gone, anaerobic corrosion could occur and generate hydrogen gas. In the sequence of events described here, room closure is assumed to be nearly complete before anaerobic corrosion of the containers begins. Microbial degradation of organic materials in the wastes is also a possibility and would produce carbon dioxide, although its rate of production is thought to be slow. Gases generated in the room would fill interstitial voids, increasing room pressures, and eventually reverse the seepage of brine so as to drive it out of the room. The gas could also migrate into anhydrite layers above the room (Figure 5.1-lc).

The room is assumed to remain in this gas-filled, pressurized state of the "undisturbed" scenario (Figure 5.1-la) (see Section 3.2.3, Undisturbed Summary Scenario). This episode assumes the lower shaft seal is well consolidated prior to producing gas, such that the gas is trapped in the repository rather than venting through the shaft to the Culebra. In the early 1980s, pressurization of the room was not considered feasible because of the relatively high permeabilities assigned to the salt formation. However, in the late 1980s, extensive measurements revealed relatively low salt permeabilities (as presented as an example in Section 4.1.3). As a result, room pressurization became an important consideration.\footnote{Lippin, A.R., R.L. Hunter, D.P. Garber, and P.B. Davies, eds. 1989. Systems Analysis, Long-Term Radionuclide Transport, and Dose Assessments. Waste Isolation Pilot Plant (WIPP), southeastern New Mexico, March 1989. SAND89-0462. Albuquerque, NM: Sandia National Laboratories.}

Although this hypothesized sequence of events is regarded as reasonable, a broad range of system responses can occur. Evaluating the interaction of phenomena and predicting the entire range of responses leading up to the "undisturbed state" of the repository is the topic of the two-phase flow modeling described in Section 5.1.6. Although these "undisturbed conditions" are the starting point for evaluating "human-intervention (disturbed) conditions" in the next section, important aspects of the undisturbed conditions must be examined to determine compliance with regulations specified in the Resource Conservation and Recovery Act (RCRA) of 1976 (see Section 6.3). These aspects include the influence of various parameters on the movement of gases that might contain hazardous volatile organic compounds that might be transported into the anhydrite layers above the disposal room or into the seals of the shaft and eventually beyond disposal unit boundaries as defined by RCRA (see Section 1.4.1). An example of an evaluation of the influence of various parameters for undisturbed conditions is given in Section 7.1.1, Ranking Important Model Parameters.

References


*See also Section 3.2.3, Undisturbed Summary Scenario.*
Figure 5.1-1. Hypothesized episodes in the disposal area leading to an undisturbed state of the WIPP disposal system. This drawing shows (a) initial conditions after disposal, (b) room creep closure and brine inflow, (c) gas generation, brine outflow, and room expansion, and (d) undisturbed conditions with a gas-filled room surrounded by gas-saturated brine (after Rechard et al., 1990b).
5.0 Consequence Analysis

5.1.2 Repository Episodes after Intrusion

The scenario-development program for the 1992 performance assessment (PA) retained two events and processes: (1) nearby potash mining resulting in subsidence (TS), and (2) inadvertent human intrusion through three different exploratory drilling events (E1, E2, and E1E2, see Section 3.2.4, Appyling the Grouping Procedure to the WIPP). Subsidence was not modeled in 1992. The episode described herein treats the E1 event in which a borehole is drilled through a disposal room and then into a pressurized brine pocket beneath the repository in the Castile Formation. As is readily seen in Figure 5.1.2, this drilling event initiates a complicated interaction of phenomena within the disposal room. A two-phase flow code is required to model it (see Section 5.1.5). However, for the 1990, 1991, and 1992 PAs, the most important part of the event was the short-term result, namely the entrainment of wastes into the drilling fluid and their immediate release at the surface during drilling operations (the modeling of which is described in Section 5.1.3, Modeling of Cuttings/Cavings).

In the drilling intrusion scenario E1, the initial breakthrough into a repository panel quickly depressurizes a disposal room (Figure 5.1.2a). According to the 40 CFR 191 Standard, the intruders "soon" realize the area is "incompatible" with their purposes. The drillers seal the borehole using present-day technology and abandon it. Scaling permits the room to represurize from ongoing gas generation (Figure 5.1.2b).

Within 100 yr following abandonment, degradation of the borehole plug throughout its length allows any remaining gases to migrate out of the room. The degradation also allows the waste and room to reconsolidate at lithostatic pressure with brine refilling any remaining voids. Depending on pressure differences, whether borehole plugs above or below the repository degrade first, and the depth of drilling, brine could flow down from the repository into underpressurized formations below the repository. However, in the cases considered in PA calculations through 1992, brine flow from the Salado Formation and from the brine pocket beneath was assumed to mix within the room, to dissolve the inventory to saturation upon contact, and then to flow up the borehole to the overlying brine aquifer in the Culebra Dolomite Member of the Rustler Formation (Figure 5.1.2c). The dissolution of radionuclides is described in Section 5.1.7. In PA calculations through 1992, movement from the repository to the Culebra was assumed to be instantaneous. The fluid flow regime of the Culebra is described in Section 5.2, Groundwater Flow Modeling. The transport of contaminants through the Culebra to the accessible environment is described in Section 5.3, Radionuclide Transport Modeling.

The above sequence of events resulting from human intrusion is regarded as reasonable. However, it is important to bear in mind that a wide range of system responses can occur. For example, changes in the rate and timing of gas generation, the timing of human intrusion, and the rates of gas leakage through the borehole affect the system. Some mechanisms operate only immediately after plug degradation, such as depressurization within the repository; others, such as fluid from the brine pocket and brine inflow from the Salado Formation, are active over much longer time periods.

References


* "Soon" is the term used in the guidance for 40 CFR 191. However, it is not defined quantitatively. The author takes it to mean less than a month.
Figure 5.1-2. Hypothesized episodes in the disposal area after human intrusion (E1 scenario, see Section 3.2.2). Drawing (a) shows initial depressurization when the room is penetrated by an exploratory borehole. The hole is plugged, and repressurization occurs. In (b), a second gas and brine depressurization occurs as borehole seals degrade. In (c), brine flows through the borehole to the Culebra Dolomite (after Rechard et al., 1990b).
5.1.3 Modeling of Cuttings/Cavings

In the 1990 through 1992 PA calculations, the most important pathway for release during the 10,000-yr regulatory period was direct removal of waste in the event that an exploratory drill bit inadvertently penetrates a waste-storage room. To quantify the extent of radioactive release resulting from direct removal of wastes, the CUTTINGS model was developed. The performance assessment (PA) model assumed future drilling techniques would be similar to those in use today. This assumption is necessary to provide a reasonable quantitative basis on which release predictions can be made.

In rotary drilling, a cutting bit attached to a series of hollow drill collars and drill pipes is rotated at a fixed angular velocity and is directed to cut downward through underlying strata. To remove the material loosened by the drilling action, a drilling fluid ("mud") is pumped down the drill pipe, through and around the drill bit, and back up to the surface within the annulus formed by the drill pipe and the borehole wall (see Figure 5.1-3).

If an exploratory drill bit penetrates a waste-filled room, waste resulting from three separate physical processes can mix with the drilling fluid and be transported to the surface. These wastes have three distinct names:

- **Cuttings** are the wastes that occupied the cylindrical void created by the cutting action of the drill bit through the repository. Cuttings are brought to the surface in the drilling fluid of a rotary drill.
- **Cavings** are wastes that eroded from the sides of the borehole in response to the upward-flowing drilling fluid within the annulus. They are usually particulates and are brought to the surface in the drilling fluid of a rotary drill.
- **Spallings** are the wastes surrounding the eroded borehole that are broken away by the action of waste-generated gases escaping to the lower-pressure borehole. Spallings were not incorporated in the 1990, 1991, or 1992 PA calculations.

Section 5.1.4 describes the code linkages surrounding the analytical code used to evaluate cuttings/cavings.

References


*If a direct repository hit occurs, drilling operation causes the immediate release of radionuclides through the cuttings, cavings, or spallings brought to the surface in the drilling fluid ("mud"). Environmental Protection Agency (EPA) release limits in 40 CFR 191 (see Section 6.1.3, Containment Requirements) lead to overly conservative limits on this type of release. Specifically, the EPA release limits for all radionuclides except $^{14}$C were developed considering only the drinking-water pathway to humans. The release limits for $^{14}$C were evaluated considering atmospheric releases (EPA. 1985b, O'Brien et al., 1977). As a result, the EPA release limits are unrealistically scaled for cuttings-type releases. Effects are grossly exaggerated (see Section 5.4.1, Radionuclide Pathways to Humans). Nevertheless, Waste Isolation Pilot Plant (WIPP) performance assessments have traditionally included the cuttings and cavings releases (e.g., WIPP Performance Assessment Division, 1991). The tradition results from identifying "those energy sources that could move a quantity of waste sufficient to violate the standard from the repository horizon to the land surface" (Performance Assessment Group, 1990). Drilling fluids in an exploratory drilling operation were regarded as a plausible "energy source."
Mathematical equations solved to evaluate \( r \) assuming turbulent flow \( (R_e > 2100) \)

\[
\tau_{fail} = \frac{fpv^2}{(0.8165)^2} \left( \frac{E}{3.72D} + \frac{1.255}{R_e^{1/2}} \right)
\]

\[
\frac{1}{f^{1/2}} = -4 \log \left( \frac{E}{3.72D} + \frac{1.255}{R_e^{1/2}} \right)
\]

\[D = 2(r \cdot r_p)\]

\[R_e = \frac{\rho Vp}{\mu_\infty}\]

---

Figure 5.1-3. Conceptual model for the removal of cuttings/cavings from the disposal area of an exploratory drilling operation inadvertently intruding into the repository.
5.0 Consequence Analysis

5.1.4 Linkage of the CUTTINGS Model

CUTTINGS models the direct removal of wastes from the Waste Isolation Pilot Plant (WIPP) repository as a result of exploratory drilling. Assuming current industry drilling practices for gas and oil are used, radioactive waste will be released to the ground surface in the drilling fluid (mud) in the form of cuttings and cavings. As currently configured, the CUTTINGS code calculates the drilling mud fluid shear stress acting on the borehole wall and the subsequent erosion of repository materials. The total volume of material removed by drilling is the sum of the eroded material plus the material directly cut by the drill bit. CUTTINGS also decays the radionuclide inventory to the time of intrusion.

The first steps in using CUTTINGS are to use GENNET to establish a grid and then to use MATSET, which extracts attribute and property data from the secondary data base and generates a computational data base template (PRECUTTINGS.CDB). See Figure 5.1-4 and Section 3.3.3, Support Codes Used in the Modeling System. POSTLHS is then used to generate NK computational data files (CUT_R#.CDB) using sampled parameters from LHS.OUT (see Section 4.2.3, Executing Latin Hypercube Sampling).

In the calculations, the drill-bit diameter was a sampled quantity for CUTTINGS; hence, GENNET itself was sampled. This led to double-sampling and (NK)^2 samples. To reduce the number of samples consistently to NK, the (NK - 1) samples corresponding to drill-bit diameters other than the bit diameter used in the present GENNET sample are deleted. That process was repeated NK times, resulting in a remainder of NK fully sampled, self-consistent parameter sets that include sampled borehole sizes.

With sampling completed, the CAMDAT.CDB and CUTTINGS.INP files were used as input to the CUTTINGS code. CUTTINGS computed the surface release of radionuclides for the NK sampled cases and placed the results on NK output CDB files. The files were named CUTCH_S#.R#.CDB for contact-handled waste and CUTRH_S#.R#.CDB for remotely handled waste. These files were then used by CCDFCALC (see Section 6.1.6, Software for Calculating Complementary Cumulative Distribution Functions).

References


Figure 5.1-4. Linkage of the CUTTINGS computer code to the modeling system to evaluate the release of radionuclides from inadvertent intrusion into the repository.
5.1.5 Modeling of Two-Phase Flow

To study the effects of gas generated by corrosion of metals (primarily steel) and degradation of organic material (primarily cellulose) on the flow of brine into and through the repository and then up an intrusion borehole, Sandia National Laboratories developed a standard mathematical model of two-phase flow through a porous, heterogeneous material. The implementation of this mathematical model was the computational model called BRAGFLO (see Section 5.1.6). The starting equations of the mathematical model are as follows:

Conservation of Gas Components:
\[ \nabla \cdot \left[ \frac{\alpha P_n K_{rn}}{\mu_n} \left( \nabla P_n - \rho_{ng} \nabla D \right) + \frac{\alpha C_{NW} P_w K_{rw}}{\mu_w} \left( \nabla P_w - \rho_{nw} \nabla D \right) \right] + \alpha q_n + \alpha q_{rn} = \frac{\partial \left( \phi P_n S_n + \phi C_{NW} P_w S_w \right)}{\partial t}, \]

Conservation of Brine Component:
\[ \nabla \cdot \left[ \frac{\alpha C_{W} P_w K_{rw}}{\mu_w} \left( \nabla P_w - \rho_{nw} g \nabla D \right) \right] + \alpha q_w + \alpha q_{rw} = \frac{\partial \left( \phi C_{W} P_w S_w \right)}{\partial t}, \]

Constraint on Saturations: \( S_n + S_w = 1, \)

Constraint on Mass Fraction: \( C_{NW} + C_{Ww} = 1.0, \)

Constraint on Capillary Pressure: \( P_n + P_w = P_c, \)

where the quantities have the following meanings:

- \( C_M \) = mass fraction of component \( M \) dissolved or miscible in phase \( \ell \); \( g \) = gravitational acceleration constant \([L^2, \text{m s}^{-2}]\); \( K \) = absolute permeability of the reservoir \([L^2, \text{m}^2]\); \( k_{r\ell} \) = relative permeability to phase \( \ell \) \([\text{dimensionless}]\); \( P_c \) = capillary pressure \([ML^{-1}T^{-2}, \text{Pa}]\); \( q_{f} \) = mass rate of well injection (or production, if negative) per unit volume of reservoir \([ML^{-3}T^{-1}, \text{kg m}^{-3}s^{-1}]\); \( q_{r} \) = mass rate of products produced (or reactant consumed, if negative) per unit volume of reservoir due to chemical reaction \([ML^{-3}T^{-1}, \text{kg m}^{-3}s^{-1}]\); \( S_\ell \) = saturation of phase \( \ell \) \([\text{dimensionless}]\); \( x, y \) = spatial dimensions (\( x \)-horizontal, \( y \)-vertical); \( \alpha \) = geometric factor (\( \alpha = 1 \) in three dimensions, \( \alpha = a \) in two dimensions, \( \alpha = l \) in one dimension); \( \nabla \) = gradient, shorthand for \( \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \) in two dimensions; \( \nabla \cdot \) = divergence, shorthand for \( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \) in two dimensions; \( \phi \) = reservoir porosity \([\text{dimensionless}]\); \( \rho_\ell \) = density of phase \( \ell \) \([ML^{-3}, \text{kg}^{-3}]\); and \( \mu_\ell \) = viscosity of phase \( \ell \) \([ML^{-1}T^{-1}, \text{cp}]\).

The meaning of the subscripts are as follows: \( N \) = nonwetting components (gas component); \( n \) = nonwetting phase (gas phase); \( W \) = wetting component (brine component); and \( w \) = wetting phase (brine phase).

Although the flow-flow fields within and around the repository are three dimensional, the repository was modeled in two rather than three because of the numerous stochastic calculations required. The transformation from three to two dimensions was accomplished using a combination of element radial flaring and volumetrically averaging material properties. The element flaring is discussed further here (Figure 5.1-5). Element flaring is the process of defining one or more subregions in a two-dimensional mesh where radially symmetric flow is assumed to occur, then evaluating the width of the element assuming radial coordinates. This process has been used quite successfully ever since 1989 to approximate flow near a point of interest in a system that is not fully axisymmetric. The distinction between element flaring and fully axisymmetric modeling is that not all of the elements are automatically increased in width by the radial distance times the full \( 2\pi \) arc. Rather, several origins may be used and portions of the study domain with, for example, an approximately uniform flow can have constant widths.

References
Figure 5.1-5. Conceptual and numerical logic grids for applied models used for 1992 PA simulations of the repository: (a) mesh of undisturbed scenario using a grid with a portion of the elements "flared" (i.e., elements increased in width to approximate radial flow), and (b) mesh of disturbed scenario using all axisymmetric elements.
5.0 Consequence Analysis

5.1.6 Linkage of the BRAGFLO Code

Section 5.1.2. described the interaction of (a) brine flowing into the disposal rooms, (b) gas being generated as steel corrodes and organic materials degrade, and (c) an assumed intrusion into a disposal room by a borehole. These events necessitate the use of a two-phase hydrological flow code. BRAGFLO\(^1\) was adopted and developed specifically for this purpose.

BRAGFLO\(^1\) simulates two-phase, three-dimensional, isothermal fluid flow in porous heterogeneous media using a finite-difference numerical solution scheme. The fully implicit formulation makes BRAGFLO well suited for simulating convergent flow into a well.\(^2\) BRAGFLO includes a corrosion and biodegradation gas-generation submodel that operates on whatever iron and cellulose may be available in the waste. A BRAGFLO user's/theory manual is in preparation.

The linkage of BRAGFLO to other portions of the consequence model (depicted in Section 3.3.2, The Component Computational Models) is typical and is described below (see also Figure 5.1-6):

1. The underlying data for BRAGFLO comes from two files: LHS.OUT and PROPERTY.SDB (described in Section 4.2.3, Executing Latin Hypercube Sampling).
2. The borehole diameter is sampled. Therefore, grid spacing near the borehole must be adjusted accordingly. GEN_INP is a program written specifically for each year's calculational grid. It adjusts the GENMESH input file using mesh parameters from LHS.OUT.\(^3\)**
3. GENMESH\(^2\) defines a finite-difference mesh from the Castile to the Culebra, from the borehole to the accessible environment, and creates a .CDB file for BRAGFLO.
4. MATSET\(^2\) assigns a constant, usually median value for each parameter required by the model. It uses values from the PROPERTY.SDB file (depicted in Section 4.2.3).
5. POSTLHS\(^* * *\) overwrites the .CBD file using sampled parameters from LHS. This step results in the production of nK.CDB files, one for each sampled data set.
6. BRAGFLO requires several parameters that are derived from other parameters stored in the .CDB file. For example, compressibility divided by porosity. This manipulative step is accomplished with ALGEBRACDB.\(^5\)
7. ICSET is used to set initial liquid and gas saturations and pressures.
8. The two-phase flow simulations are run using BRAGFLO, which includes a pre- and a post-processing code to prepare inputs for BRAGFLO and for the downstream codes. They are named PREBRAG and POSTBRAG.
9. ALGEBRACDB is usually applied at this point to strip the POSTBRAG output .CBD file of data that is not needed for the next step in the process. This step is not absolutely required, but it shortens run times and facilitates troubleshooting.

The dissolution of radionuclides into the brine filling the disposal room is decoupled from BRAGFLO. A specialized code has been written specifically for that purpose. It is described in Section 5.1.8.

References


\* The 1990 performance assessment (PA) calculations used the two-phase flow code BOAST.\(^3\) However, its implicit/explicit (IMPES) formulation could not adequately solve convergent flow into an intrusion borehole.
\** If a mesh-dependent parameter is sampled, the following two steps must be run nK times where nK is the number of sample sets.
\*** Pre- and post-processor codes of the Waste Isolation Pilot Plant's (WIPP's) analytical codes are usually omitted in this report. They are ancillary codes used solely to manipulate data in a preparatory fashion. They do not solve equations or embody physical laws. POSTLHS, however, is an exception. It plays a critical role in WIPP PA sampling and is therefore included here and elsewhere.
Figure 5.1-6. Linkage of software to model two-phase (brine and gas) flow in and around the WIPP repository for both the undisturbed and disturbed scenarios in the 1991 and 1992 performance assessment calculations.
5.0 Consequence Analysis

5.1.7 Modeling of Source-Term

The source-term model estimates the radionuclide discharge rates leaving the repository resulting from one or more boreholes penetrating the repository and a possible pressurized brine reservoir in the Castile formation below the Salado Formation (see Sections 3.2.4 and 3.3.2). Specifically, the source-term model evaluates the concentration of the ith chemical element (e.g., radionuclide) leaving from a specified portion ("cell") of the repository (usually an entire panel) as a function of time as follows.1,2,3 A cell within the Waste Isolation Pilot Plant (WIPP) repository is idealized as a single connected cavity with contaminants within the waste uniformly distributed throughout the cavity. It assumes dissolution equilibrium at all times (infinitely efficient mixing in the cell, and negligible kinetic effects of dissolution for the time scales used). If sufficient inventory of the element is present at time \( t \), \( C_i(t) \), the model determines concentrations of the ith element entirely by solubility limit (suspended radionuclides [colloids] are ignored), that is, \( C_i(t) = S_i \) if \( I_i(t)/V(t) \geq S_i \) otherwise \( C_i(t) = I_i(t)/V(t) \) if \( I_i(t)/V(t) < S_i \), where \( V(t) \) is the volume of brine present in the cell at time \( t \) (concentrations of radionuclides within the gas phase are negligible and concentrations of hazardous volatile compounds are simply set equal to measured concentrations). The volume of fluid flowing through a panel, \( V(t) \), was determined by the repository model BRAGFLO in the 1991 and 1992 performance assessment (PA) calculations (see Section 5.1.5). A simple single-phase, analytic model of the repository, the Salado Formation, and the brine reservoir was used in the 1990 PA.4 The time dependence of the inventory of an element, \( I_i(t) \), is determined using the Bateman equations\(^5\) to account for radioactive decay and growth of daughter products. Furthermore, when a chemical element has several isotopes, the relative amount of each isotope in solution is set equal to the relative amount present in the total inventory of the element in the cell.

The calculational procedure at each discrete time step (\( \Delta t \)) is as follows:

1. A volume of fluid \( (\Sigma Q_{in} \Delta t) \), constrained to be no more than 10% of the volume of a cell, displaces an equal volume of fluid leaving the panel, \( \Sigma Q_{in} \Delta t = \Sigma Q_{out} \Delta t \). (hence, \( V(t) \) is constant throughout the calculation; furthermore, the cell volume is set equal to the entire panel volume).

2. The concentration of chemical elements, \( C_i(t) \), within the panel are updated by
   a. mixing the remaining panel pore fluid with the introduced fluid
   b. evaluating the inventory of an element from radioactive decay at the end of the time step, \( I_i(t + \Delta t) = I_i(t)e^{-\lambda \Delta t} \), plus contributions of parents, grandparents, and great-grandparents as defined by Bateman equations plus inventory of other isotopes of the element
   c. calculating the concentration of an element \( C_i(t+\Delta t) \) as the minimum of \( S_i \) and \( I_i(t+\Delta t)/V(t) \)
   d. Calculating the concentration of jth isotopes of an element, \( C_{ij}(t+\Delta t) \) by proportioning the isotopes according to the relative abundance in the inventory of each isotope at \( t+\Delta t \) [i.e. \( C_{ij}(t+\Delta t) = \sum C_i(t+\Delta t) M_i/M_{ij} \)]

3. The concentration \( C_i(t+\Delta t) \) is assumed to flow up the borehole and discharge directly into the brine aquifer in the Castile Dolomite Member of the Rustler Formation. This procedure neglects decay or sorption of radionuclides while transported through the upper portion of the borehole because of the short travel time due to the high permeabilities of the borehole fill material.

References

Flow rate out \( (q_{out}) \) concentration of radionuclides \( c_{i,j} \)

Flow rate in \( (q_{in}) \) Homogeneous, isotropic porous matrix

Solubility of element \( i \), \( (S_j) \)
Inventory of element \( i \), \( I_i(t) \)
Volume of brine \( V(t) \)

\[ \text{mass discharge} = \frac{dn}{dt} = C_{i,j}(t) q_{out} \]

\[ \begin{align*}
S_j \left( \frac{m_j}{\sum m_j} (q_{out}) - \lambda_j m_j \right) + \lambda_k m_k, & \quad \text{if } I_i(t)/V \geq S_j \\
\frac{I_i(t)}{V(t)} \left( \frac{m_j}{\sum m_j} (q_{out}) - \lambda_j m_j + \lambda_k m_k \right), & \quad \text{if } I_i(t)/V < S_j
\end{align*} \]

Figure 5.1-7. Idealization of the WIPP repository for evaluating concentration (or mass discharge) of radionuclides leaving a panel: a) conceptual model and b) mathematical model.
5.0 Consequence Analysis

5.1.8 Linkage of PANEL Code

The source-term modeling portion of the repository submodel calculates the amounts of radionuclides that are dissolved from an assumed repository inventory into brines that pass through all or part of the repository. The contaminated brine is then usually transported immediately to the Culebra Dolomite aquifer. The output flow rate to the aquifer is set equal to the rate of brine flow into the repository, as described in Section 5.1.6. These radionuclide concentrations represent the first introduction of radionuclides into the groundwater flow. Thus, they are "source-terms" in the mathematical sense, which explains the name of this subsection, "source-term modeling."

The dissolution of radionuclides from the waste matrix into disposal-room brines is modeled via an infinitely efficient mixing cell. The code that implements this mathematical model is called PANEL1 (see Section 5.1.7).

PANEL (1) evaluates radionuclide concentrations discharged from a specified portion of the repository (usually an entire panel) as a function of time. It assumes dissolution equilibrium at all times (infinitely efficient mixing in the cell, and no kinetic effects of dissolution). (2) If sufficient inventories are available, PANEL determines concentrations entirely by solubility. (3) When an element has several isotopes, the relative amount of each isotope in solution is set equal to the relative amount present in the total inventory. (4) PANEL also monitors the natural decay of the radionuclide inventory as a function of time using Bateman's equations. The amount of fluid flowing through PANEL's cell can be input or calculated internally by PANEL assuming simple models of the brine reservoir and Salado Formation. The internally generated flow rates were used only in parts of the 1990 performance assessment. Thereafter, BRAGFLO was used.

PANEL's code-linkage scheme (see Figure 5.1-8) is less complicated than but similar to the process described in Section 5.1.6 for Two-Phase Flow Modeling. Specifically, the simulation begins with GENNET1, which is a mesh-generating code similar to but considerably simpler than GENMESH. As PANEL's mesh is a single element, GENNET is adequate. GENNET also creates a template *.CDB file for PANEL in the CAMDAT data base. MATSET adds constant model parameters such as the inventory (depicted in Section 2.2.1) to the .CDB file. POSTLHS adds sampled model parameters and replicates the .CDB file nK times (depicted in Figure 3.3-5 as Run 1, 2, ...), once for each sample. PANEL then uses the liquid volume present in a panel, outputted in BRAGFLO's output file, to calculate the maximum radionuclide concentrations that the fluids can carry. An optional step is to use ALGEBRACDB to extract only the flow through the repository panel to speed up the use of the file by PANEL, and thereby the calculations. The results are outputted in PANEL's final S#.R#.CDB file for use in groundwater-transport calculations for the Culebra aquifer (described in Section 5.3). The results can also be used to calculate conditional complementary cumulative distribution functions (CCDFs) using the CCDPFCALC and CCDPFPLOT codes (described in Section 6.1.6, Software for Calculating Complementary Cumulative Distribution Functions). This step is often performed to allow for comparisons with the final CCDFs calculated at the boundaries of the Waste Isolation Pilot Plant (WIPP) disposal system. An example of the results from PANEL, assuming sufficient water to dissolve all radionuclides at any time, is shown in Section 2.2.3.

Reference

Figure 5.1-8. Linkage of PANEL to the modeling system to evaluate concentrations of radionuclides with one panel of the WIPP repository. The use of ALGEBRA CDB to extract only the flow values through the repository panel is optional but greatly speeds up the calculation.
5.0 Consequence Analysis
5.2 Groundwater Flow Modeling

Groundwater flow modeling within the Culebra Dolomite Member of the Rustler Formation consists of two main models and two corresponding groups of software. The first model generates spatially varying transmissivity* fields over the domain of interest of the Culebra Dolomite. The second model simulates groundwater flow on both regional and local scales of that spatial domain. Transmissivity fields are required parameters for groundwater flow, and their generation is therefore a necessary precursor to groundwater flow modeling. Groundwater-flow simulations modeling software simulates local and regional fluid-flow conditions within (1) a small region immediately overlying the repository and (2) a larger region surrounding the disposal system. Only the liquid phase is treated within the aquifer, so the working fluid is brine. Once a fluid-flow field has been evaluated for each sample set of flow parameters on the regional and local domains, the transport of radionuclides within each of the flow fields is predicted in the third portion of the consequence model (see Section 5.3, Radionuclide Transport Modeling).

Sections 5.2.1 through 5.2.5 discuss groundwater-flow modeling. Sections 5.2.6 and 5.2.7 discuss the generation of the transmissivity fields. As noted above, this is the reverse order in which the simulations are actually run, but a general discussion of groundwater-flow modeling was thought to be of interest to a wider audience and to help the general reader understand the need for the transmissivity fields. Sections 5.2.1 through 5.2.3 present examples of results of groundwater flow modeling. Because the software used for evaluating results differed substantially in the 1990 and 1992 performance assessment calculations, the code linkages for both years are described in Sections 5.2.4 and 5.2.5.

Transmissivity (T) is the rate at which water, driven by a unit hydraulic gradient, is transmitted through a unit width of aquifer. It is the hydraulic conductivity (K) times the thickness of the aquifer, where hydraulic conductivity measures the ability of a rock or soil to allow fluid to pass through it. In turn, hydraulic conductivity is a function of the intrinsic permeability (Kₐ) of the media and the viscosity (μ) and density (ρ) of the fluid.
5.2.1 Regional and Local Groundwater Flow Modeling

Groundwater flow in the Culebra Dolomite located above the Waste Isolation Pilot Plant (WIPP) repository is modeled on both regional and local spatial scales (Figure 5.2-1) (see also Chapter 2.0, Disposal System and Regional Characterization). Climate effects, described in Section 2.1.6, are incorporated into the regional model via time-varying boundary conditions. Boundary conditions for the local scale are interpolated from pressures calculated during the regional simulation.

The conceptual model for evaluating groundwater fluid flow in the Culebra Dolomite consists of the following assumptions: (1) single-porosity Darcian flow (however, dual porosity effects on transport are considered; see Section 5.3.2), (2) two-dimensional flow through uniform thickness aquifer even though localized flow in certain cross-sections is known to occur because most hydrologic test wells (see Section 2.1.5) arc completed across entire Culebra thickness, (3) axis of Nash Draw treated as a streamline (no-flow) boundary, (4) hydraulic heads (related to fluid pressure) assumed to be in equilibrium with heads around the boundary of the regional modeling domain, (5) future changes in flow induced solely by changes in recharge from climate change on northern boundary of domain, (6) no flow ("leakage") through bottom and top planes of the aquifer as indicated by differences in heads between adjacent layers of the Rustler Formation.

The mathematical model solved in two dimensions \((x,y)\) is

\[
S \cdot \frac{\partial h}{\partial t} = \nabla \cdot (K \cdot \nabla h) - W,
\]

where \(h = h(x,y,t)\), the potentiometric head \((\text{m})\), \(S_x = S_x(x,y,t)\), the specific storage of the Culebra \((\text{m}^{-1})\), \(K = K(x,y,t)\), the hydraulic conductivity tensor \((\text{m/s})\), and \(W = W(x,y,t)\), a volumetric flux per unit volume of formation \((s^{-1})\), (used to simulate wells or recharge).

The specific storage and hydraulic conductivity tensor are obtained from more directly measurable quantities,

\[
S = \frac{S(x,y)}{\Delta Z}, \quad K = \frac{T(x,y)}{\Delta Z},
\]

where \(S(x,y)\) = storage coefficient in the Culebra (dimensionless) and \(\Delta Z(x,y)\), Culebra thickness (m).

From given initial and boundary conditions, the mathematical model is solved numerically to yield Darcy velocity (or specific discharge) for use in evaluating radionuclide transport (see Section 5.3):

\[
q_i(x,y,t) = -K \cdot \nabla h \quad (\text{m/s}).
\]

Either of two codes may be used to model groundwater flow. They are as follows: (1) SECOFL2D, developed by the Performance Assessment Department, which automates the calculation of and interaction between the regional and local models, and (2) several other flow codes including STAFF2D, SUTRA, and SWIFT in concert with various support modules that can be linked in a serial procedure using the CAMCONexec driver to calculate regional flow, interpolate properties and pressures onto the local grid and boundary, and calculate local flow. The first procedure uses a code specifically tailored for analysis of the WIPP and is more streamlined. The second procedure allows the analyst to use the capabilities of a greater number of available flow codes. Sections 5.2.2 and 5.2.3 present examples of results from the groundwater-flow modeling. Sections 5.2.4 and 5.2.5 describe the two procedures for linking the above codes.

References


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5.2 Groundwater Flow Modeling

Figure 5.2-1. Regional and local groundwater flow modeling of brine aquifer in the Culebra Dolomite Member of the Rustler Formation ~300m above the WIPP repository horizon (see Section 2.2.1): (a) regional and local meshes, (b) contours of equal hydraulic head \( h = \frac{P}{K} + z \) for conditions at present and conditions 10,000 yr in the future from change in climate for one sample in 1992 performance assessment.\(^3\)
5.0 Consequence Analysis

5.2.2 Cumulative Travel-Time Distributions

In the CAMCON modeling system, groundwater-flow fields are used directly by the codes of the groundwater-transport module (see Section 5.3, Radionuclide Transport Modeling) to evaluate radionuclide transports. However, a distribution of travel times of neutrally buoyant particles from the projected center of the repository in the Culebra to a boundary 5 km (3 mi) from the disposal system is a convenient way to summarize the results of the groundwater-modeling step. The resultant distribution of travel times is presented in Figure 5.2-2. The method of calculating particle paths is shown in Section 5.2.3. In general, the travel times of neutrally buoyant particles varied over 27,000 yr for the transmissivity fields generated in the 1992 performance assessment calculations.¹ (See Section 5.2.3 for examples of particle paths from which the distribution of travel time was evaluated.)

Reference

Figure 5.2-2. Cumulative distribution travel time to the maximum 5-km (3 mi) boundary of the Waste Isolation Pilot Plant disposal system, using transmissivity fields calculated for the 1992 performance assessment simulations (see Section 5.2.7). Travel times change dramatically if matrix or fraction porosity are used. The relative change (rather than absolute value) in travel times across the simulated transmissivity fields assuming contaminated movement through the matrix porosity is presented.
5.0 Consequence Analysis

5.2.3 Neutrally Buoyant Particle Paths

A possible summary measure of the groundwater flow is the envelope of shapes of paths taken by neutrally buoyant particles through the various fluid-flow fields (see Figure 5.2-3). Particles are released at an intrusion borehole intersecting the center of the repository. Using the first 20 flow fields generated in the 1992 performance assessment calculations, a considerable variation in travel pathways to the Waste Isolation Pilot Plant (WIPP) disposal-system boundary is observed (the WIPP land-withdrawal boundary is ~2.4 km (1.5 mi) from the outer edge of the repository). The method of calculating particle paths is shown in Sections 5.3.2 and 5.3.3.

Reference

Figure 5.2-3. Paths for neutrally buoyant particles released in the Culebra Dolomite Member of the Rustler Formation at an intrusion borehole intersecting the center of the repository, based on the first 20 flow fields generated from the 1992 performance assessment calculations (after Rechard, ed., 1993, Figure 12-27).
5.0 Consequence Analysis

5.2.4 Linkage for 1990 Groundwater-Flow Simulations

In the 1990 and some of the 1991 performance assessment calculations, various general-purpose groundwater flow codes, including STAFF2D, SUTRA, and SWIFT, were used to predict the groundwater-flow regime over both regional and local flow domains of the brine aquifer within the Culebra Dolomite Member of the Rustler Formation. The three codes are described as follows:

STAFF2D models single- or dual-porosity fluid flow and radionuclide transport using a finite-element numerical solution technique. Specifically, STAFF2D is a two-dimensional finite-element code designed to simulate confined and unconfined groundwater flow and single- or multiple-component solute transport in fractured or granular aquifers. Fractured porous media are represented using both discrete-fracture and dual-porosity approaches.

SUTRA evaluates saturated or unsaturated density-dependent groundwater flow with either (1) solute transports subject to equilibrium adsorption and zero- and first-order production or decay or (2) thermal-energy transports within the groundwater and solid matrix of the aquifer. SUTRA approximates the governing equations using two-dimensional, finite-element and integrated finite-difference methods.

SWIFT II is a general-purpose code for solving transient, three-dimensional, and coupled equations for fluid flow, heat transport, brine-miscible displacement, and radionuclide-miscible displacement in porous or fractured media.

In general, several steps were necessary to link these codes to other portions of the consequence model. First, it was necessary to create regional and local CAMDAT data bases (groupings of CDB files) for groundwater flow modeling. The regional input CDB files were created from the files containing transmissivity fields (TFIELDS_R#.CDB) (created in Section 5.2.6). POSTLHS was exercised to add sampled parameters. ALGEBRACDB was then run to calculate parameters specifically required by the flow codes (see Section 3.3.3, Support Codes Used in the Modeling System, for a description of ALGEBRACDB). The groundwater flow codes followed, including any pre- and/or post-processor codes that were required. Climate changes were modeled as time-dependent boundary conditions (as described in Section 2.1.6). Using RELATE, results were interpolated (as boundary conditions) and pertinent parameters were transferred from the regional model domain onto a local-scale model domain previously created using GENMESH. One of the above flow codes, not necessarily the same one used for the regional flow, was then used to calculate the local groundwater flow regime (see Figure 5.2-4). The local fluid-velocity fields (LOCAL_FLOW_R#.CDB) were saved for subsequent use in groundwater transport modeling (described in Section 5.3).

References


5.2 Groundwater Flow Modeling

Figure 5.2-4. Linkage of software to calculate the groundwater flow regime (i.e., spatial distribution of brine velocity) within the Culebra Dolomite Member of the Rustler Formation in the 1990 and 1991 performance assessment calculations.
5.0 Consequence Analysis

5.2.5 Linkage of the SECOFL2D Flow Code

In the 1991* and 1992 performance assessment calculations, SECOFL2D was used to predict the groundwater-flow regime on a regional and local model domain for the brine aquifer in the Culebra Dolomite Member of the Rustler Formation, which overlies the Waste Isolation Pilot Plant. SECOFL2D is described as follows:

SECOFL2D simulates groundwater flow by solving a partial differential equation with head (water elevation) as the solution variable. It uses a fully implicit, finite-difference numerical solution technique. Problems may be run on regional and local model domains in which the local grid is decoupled from the regional mesh in space and time. The code is designed so that the numerical computational meshes are decoupled from the grid-defining material properties. A user's and theory manual is in preparation.

In general, several steps are necessary to link SECOFL2D to other portions of the consequence model (see Figure 5.2-5) using the CAMCON modeling system, but the steps are similar to those required for linking other general-purpose groundwater-flow codes described in Section 5.2.4. First, it is necessary to create regional and local CAMDAT data base files (.CDB files) for groundwater flow modeling using GENMESH and MATSET (see Section 3.3.3, Support Codes Used in the Modeling System, for a description of GENMESH, MATSET, and ALGEBRACDB used here). POSTLHS, a postprocessing code for LHS is then used to add sampled parameters to the regional .CDB file. The transmissivity fields (TFIELDS_R#.CDB), one for each sample set, are then merged with the regional files (REGIONAL_R#.CDB). The analyst can use ALGEBRACDB to evaluate specific parameters needed by SECOFL2D, but it is not usually necessary at this point. The regional files (REGIONAL_R#.CDB) and one file for the local model domain (LOCAL_R#.CDB) are used by the preprocessor to SECOFL2D to create input files for SECOFL2D, which calculates both the regional and local groundwater flow regime, and most importantly the fluid-flow velocities. The flow velocities on the local-scale domain are used (in double precision) in subsequent groundwater-transport simulations (described in Section 5.3, Radionuclide Transport Modeling).

Reference


* Other groundwater flow codes were also used in 1991. See Section 5.2.4.
Figure 5.2-5. Linkage of SECOFL2D in the modeling system to calculate velocity of brine moving through the Culebra Dolomite in the 1991 and 1992 performance assessment calculations.
5.2.6 Generating Transmissivity Fields

Efforts to incorporate uncertainty into numerical representations of the Culebra's transmissivity field have been evolutionary. In the 1990 performance assessment (PA), the Culebra was divided into seven zones or regions. A mean transmissivity value and an associated standard deviation were assigned to each zone. By sampling from the distributions associated with each zone, multiple realizations of zonal transmissivity values were created and subsequently used as input to flow and transport calculations. Although computationally simple, this specification of transmissivity zones significantly reduced the spatial variability within a given realization because each zone was characterized by a constant value. Moreover, in a given realization, large differences in the values assigned to neighboring zones could occur, leading to artificial internal boundaries over which abrupt changes in transmissivity occurred.

In an effort to improve the accuracy and representativeness of the transmissivity fields used in the 1991 PA calculations, simulations of Culebra transmissivity fields were produced that agreed with observed transmissivity values at all tested wells. This work resulted in 60 transmissivity fields that were also in acceptable agreement with steady-state, freshwater heads calculated from observed water elevations in the region around the Waste Isolation Pilot Plant (see Section 2.1.5 for location of observation wells).

The transmissivity fields of the Culebra Dolomite aquifer were evaluated, in the 1991 PA calculations, using GARFIELD, GENOBS, FITBND, and the groundwater-flow code SWIFT II. The procedure consisted of exercising GARFIELD, which randomly generated hundreds of transmissivity fields from tests at scattered wells (see Section 2.1.5) (see Figure 5.2-6). The estimated mean transmissivity and estimated error were determined for each block of the regional grid previously generated by GENMESH using generalized kriging, which is a type of interpolation that takes account of known or assumed statistical properties of the field that is being interpolated. GARFIELD rapidly created the transmissivity fields using Cholesky decomposition of the matrix consisting of covariances of transmissivities measured at the wells. Using GENOBS, a set of linear impulse functions for selected segments of the mesh was generated. The number and shape of the perturbations were controlled independently of the mesh. The steady-state response of modeled pressures (using the hundreds of Culebra transmissivity fields, taken one at a time) to the generated impulse functions was evaluated using the hydrologic code SWIFT II. Finally, FITBND was used to select a weighting of the boundary-condition perturbations, based on minimizing errors with respect to the known, steady-state, freshwater heads at the wells. In the 1991 PA calculations, 45 parameters were assumed uncertain. The number of samples, \( n_K \), was usually taken approximately equal to 4/3 of the number of uncertain (varied) parameters, \( n_P \). Hence, 60 samples were taken for propagating uncertainty (see Section 1.3.1). The first \( n_K \) (60) transmissivity fields that had (1) good agreement (i.e., small error) with the freshwater heads and (2) good subjective agreement with known flow directions and magnitudes in the area were retained.

References


- Transmissivity \( T \) is the rate at which water, driven by a unit hydraulic gradient, is transmitted through a unit width of aquifer. It is the hydraulic conductivity \( K \) times the thickness of the aquifer, where hydraulic conductivity measures the ability of a rock or soil to allow fluid to pass through it. In turn, hydraulic conductivity is a function intrinsic permeability \( K \) of the media and the viscosity and density \( \rho \) of the fluid.
- Cholesky decomposition is a type of matrix inversion.
Repeated 100's of times to produce $nK$ fields because some fields are rejected by FITBND.

Figure 5.2-6. Linkage of software to generate fields of the Culebra Dolomite transmissivity (hydraulic conductivity times aquifer thickness) in the 1991 performance assessment calculations.
5.2.7 Transmissivity Fields by Pilot Points

In 1992 performance assessment (PA) calculations, pilot-point methods were used to generate transmissivity fields over the calculational grid. The method involves generation of a large number of random transmissivity fields, each of which is in close agreement with all the measured data at the Waste Isolation Pilot Plant (WIPP) site, namely (1) hydraulic conductivity measurements of samples and (2) steady-state pressure measurements for in-situ well tests, and (3) transient pressure measurements (see Section 2.1.5, Hydrological Characterization of the Culebra). Agreement between generated transmissivity fields and the measured data was achieved by taking the following steps:

1. First, statistically conditioned simulations of the WIPP transmissivity fields were generated. These were random fields that had the same statistical moments (the mean and the variance) and the same spatial correlation structure as the WIPP site's field, based on transmissivity measurements. The generated fields did not generally match the measured transmissivities at every location. However, the two fields were statistically similar.

2. These transmissivity fields were further conditioned so that they agreed with measured transmissivities at every location where hydraulic conductivity measurements were available. The resulting fields are called conditional simulations of the transmissivity field.

3. The conditional simulations of the transmissivity field were still further conditioned, such that the steady and transient pressures computed by the groundwater-flow model agreed closely with measured pressures in a least-squares sense. This step is known as calibration and involves solution of the inverse problem. It accounted for a large part of the time and effort devoted to transmissivity-field generation in the 1992 PA calculations. When the calibration was completed, a random transmissivity field was obtained that conforms with all the data. It is therefore regarded as a plausible representation of the transmissivity field of the Culebra aquifer at the WIPP site.

Calibration is an indirect process. An objective function is defined as the weighted sum of the squared deviations between the model-computed pressures and the observed pressures, the summation being extended in the spatial and temporal domain where pressure measurements were taken. The calibration process endeavors to minimize the objective function by iteratively adjusting the transmissivity field, recalculating pressures using the time-varying groundwater equations, recalculating the objective function, and continuing iteratively until the objective function is reduced to a prescribed minimum value.

Iterative adjustment of the transmissivity fields is accomplished through pilot points, which are artificial transmissivity data points that are intentionally added to the observed transmissivity data set during the course of calibration. A pilot point is characterized by its spatial location and the transmissivity value assigned to it. Addition of a pilot point thus increases or decreases the transmissivity in the neighborhood of the point, which increases or decreases the flow locally and adjusts the local pressure distributions correspondingly. After a pilot point is added to the transmissivity data set, the augmented data set is kriged to generate an adjusted transmissivity field for subsequent solution and calibration. Usually, the kriged transmissivity field is modified most in the neighborhood of the pilot point. Modifications in the different grid blocks are determined by kriging weights, which are not necessarily uniform over the field as a whole.

A coupled kriging-and-adjoint sensitivity analysis was used in 1992 to determine best locations for pilot points. Optimization algorithms were used to assign pilot-point transmissivities. In that way, the pilot-point approach to calibration was more objective, a feature considered desirable for assessing the performance of the WIPP disposal system.

The software for this task was assembled from many codes already developed and frequently used in groundwater-flow simulations (Figure 5.2-7). The codes are listed below. Interested readers will find details of the theory and application of these codes in the references cited below.

- TUBA, unconditional simulation of transmissivity field (Zimmerman and Wilson, 1990)
- AKRIP, generalized kriging (Kafritsas and Bras, 1981)
- SWIFT II, modeling pressures (steady and transient state) (Reeves et al., 1986a,b,c)
- GRASP II, adjoint sensitivity analysis (steady and transient state) (Wilson et al., 1986; Ramaraao and Reeves, 1990)
Figure 5.2-7. Linkage of software to generate transmissivity fields by the pilot-point method in the 1992 performance assessment calculations (see Section 5.2.2 for example of results).
5.0 Consequence Analysis

STLINE, groundwater travel time and travel paths (Intera, 1989) 9
MAIN, drives the different modules (WIPP PA Dept., 1992; LaVenue and Rama Rao, 1992) 1, 10
CONSIM, generates conditional simulations of transmissivity from the unconditional simulations of transmissivity (WIPP PA Dept., 1992; LaVenue and Rama Rao, 1992) 1, 10
PILOTL, locates the pilot points based on sensitivity analysis (Kafritsas and Bras, 1981) 3
FAREST, assigns the pilot point transmissivities by minimization of a least-square objective function (LaVenue and Rama Rao, 1992) 1

References


9 Intera, Inc. 1989. Users Manual for STLINE. QA CIN097B-12C-001B. [Austin, TX]: Intera, Inc. (Copy on file at the Sandia WIPP Central Files, Sandia National Laboratories, Albuquerque, NM.)


5.3 Radionuclide Transport Modeling

The third principal part of consequence modeling is devoted to radionuclide transport to the accessible environment. Radionuclides were introduced by PANEL. In the E1 scenario, they are released to the borehole directly above the breached room of the Waste Isolation Pilot Plant (WIPP) repository (evaluated in Section 5.1). From there, they are transported immediately up the borehole to the groundwater-flow regime of the Culebra Dolomite Member of the Rustler Formation (discussed in Section 5.2). In WIPP performance-assessment (PA) calculations to date, radionuclide transport has been modeled only on the local model domain of the Culebra Dolomite (see Section 5.2.1, Regional and Local Groundwater Flow Modeling).

Important potential aspects of the groundwater transport of radionuclides include the following: (1) the fluid velocity fields in the aquifer (discussed in Section 5.2), (2) the ability of the porous dolomite matrix to communicate readily with fluid flowing through secondary porosity postulated to exist within the dolomite, (3) the ability of material within the dolomite to adsorb radionuclides from the contaminated brine, and (4) the ability of clay minerals that may line the secondary porosity surfaces to adsorb radionuclides from the contaminated brine.

The latter three aspects were used to define alternative conceptual models (i.e., alternative sets of assumptions that describe the same process for the same purpose, where each set of assumptions is consistent with existing data and cannot be fully refuted) were considered. The alternative conceptual models were defined on the basis of (1) presence or absence of matrix porosity, (2) presence or absence of chemical retardation in the Culebra matrix, and (3) presence or absence of clay linings in secondary porosity (modeled as fractures) to provide chemical retardation in the secondary porosity. Although one of the conceptual models (the combination of item 1 and 2) was felt to provide the most realistic representation of radionuclide transport, the other alternatives could not be refuted at the time of the 1990-1992 performance assessments (PAs).

Using concentration contours of transmitted radionuclides, analysts calculate (1) the total cumulative release of radionuclides past the disposal-system boundary over 10,000 yr and (2) the maximum concentrations beyond the disposal-system boundary. When salt concentrations in the brine drop low, aquifer waters become suitable for consumption by cattle. Result (1) above becomes an input for the regulatory step of the performance assessment (PA), which is based on complementary cumulative distribution functions (see Section 6.1, Environmental Protection Agency 40 CFR 191 Simulations). Result (2) is necessary for evaluating individual doses (see Section 5.4, Biosphere Transport Modeling).

Section 5.3.1 provides an example of the concentration contours for one transmissivity field used in the 1991 PA calculations. Section 5.3.2 describes the underlying conceptual model for radionuclide transport. Sections 5.3.3 and 5.3.4 provide a discussion of the flow of information through the software used in the 1991 and 1992 PA calculations.
5.0 Consequence Analysis

5.3.1 Example of Radionuclide Transport

Contours of radionuclide concentration ("plumes") as a function of time are the direct output of radionuclide-transport models of the Culebra Dolomite Member of the Rustler Formation. Results suggest various long-lived radionuclides—such as americium (241 Am), plutonium (239Pu, 240Pu, 238Pu), and uranium (233U, 234U)—can, under some circumstances, be released at the disposal-system boundary.*

Because they are biologically more harmful, the maximum concentration of short-lived daughter radionuclides at the land-withdrawal boundary within the 10,000-yr regulatory period are critical inputs to the biosphere transport model (see Section 5.4, Biosphere Transport Modeling).

The total amounts of each of the long-lived radionuclides, accumulated over 10,000 yr, are critical inputs to the regulatory-assessment software for constructing the complementary cumulative distribution function for comparison with the Containment Requirements in 40 CFR 191 (see Section 6.1, Environmental Protection Agency 40 CFR 191 Simulations).

As an example of these types of output, Figure 5.3-1 shows both (a) a contour of the concentrations of 234U after 10,000 yr for one transmissivity field from the 1991 performance assessment calculations and (b) the cumulative release of 234U. The variations in the cumulative releases are considerable when sampling all 45** model parameters, except the parameter that selected the transmissivity field† (Figure 5.3-1).

Reference


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* The Waste Isolation Pilot Plant land-withdrawal boundary is ~2.4 km (1.5 mi) from the edge of the repository.

** Not all of the 45 parameters influenced the observed variation at this point of the calculation. Several parameters, such as λ in the Poisson analytic function (see Section 4.2, Compiling Model Parameters), were used only in later submodels.
Figure 5.3-1. Example of radionuclide release (a) concentration contours of $^{234}$U after 10,000 yr for one simulation and (b) variation in cumulative release of $^{234}$U to the 5-km (3-mi) boundary when varying model parameters, except those associated with the transmissivity field. [This example used data from the 1991 performance assessment (PA) calculations, but uses SECO2P2D, a transport code used in the 1992 PA calculations and mentioned in Section 5.3.4. This work was part of the Probabilistic Safety Assessment Code Intercomparisons (PSACOIN), an exercise sponsored by the Nuclear Energy Agency (NEA) of the Organisation for Economic Co-Operation and Development (OECD).]
5.3.2 Modeling of Radionuclide Transport

Releases of radionuclides from the WIPP repository to the accessible environment might occur along liquid pathways through the brine aquifer in the Culebra Dolomite Member of the Rustler Formation (see Sections 3.3.3 and 3.3.4). The conceptualization of the Culebra consisted of two continuums: one continuum associated with the intact dolomite matrix with an original porosity and one continuum associated with secondary porosity through the dolomite matrix that is modeled as fractures. Based on available field evidence at the time a dual porosity model of contaminant transport in the Culebra was used, that is, transport of contaminants was advected by fluid flow through the fracture continuum but diffusion of contaminants into the matrix continuum surrounding the fracture could occur. The fracture system was idealized as planar and parallel (Figure 5.3-2); in some alternative conceptual models each fracture was coated with a layer of clay of uniform thickness.

The governing equation for mass transport in a single fracture is

\[
\frac{\partial C_i}{\partial t} = -\frac{\partial}{\partial x_1} \left( V_i C_i - D_{ij} \frac{\partial C_i}{\partial x_j} \right) - \lambda \xi \gamma_m \mu_m C_i + \sum_{m=1}^{m} \xi \mu_m \gamma_m C_i + Q \left( C_{in} - C_i \right) + \Gamma_i,
\]

where the summation convention has been used \((x_1 = x, x_2 = y)\); \(m = 1, 2, \ldots, m\) label the radionuclides; and the quantities have the following meanings:

- \(C_i\) = concentration of \(i\)th radionuclide in fracture fluid \((\text{kg/m}^3)\).
- \(V_i\) = average linear velocity vector in fracture system \((\text{m/s})\).
- \(D_{ij}\) = Hydrodynamic dispersion tensor \((\text{m}^2/\text{s})\).
- \(\lambda\) = decay constant for \(i\)th radionuclide \((\text{radionuclide, s}^{-1})\).
- \(\xi\) = fraction of \(n\)th parent radionuclide that decays into \(i\)th radionuclide \((\text{dimensionless})\).
- \(Q\) = rate of fluid injection per unit volume of formation \((\text{s}^{-1})\) (see Section 5.1.7).
- \(C_{in}\) = concentration of \(i\)th radionuclide in injected fluid \((\text{kg/m}^3)\) (see Section 5.1.7).
- \(\Gamma_i\) = rate of mass transfer of \(i\)th radionuclide from matrix system to fracture system \((\text{kg/m}^3 \cdot \text{s})\).

The average linear velocity vector, \(V_i\), is related to the specific discharge in the Culebra by

\[
V_i = \frac{q_i \phi_f}{\phi_{fr}}
\]

where the specific discharge, \(q_i\), is provided by the fluid flow model (see Section 5.2) and \(\phi_f\) is the fracture porosity of the Culebra. For planar parallel fractures (Figure 5.3-2) and \(b < B\), \(\phi_f = \frac{b}{b + B}\).

Mass transport into the matrix occurs by diffusion across the fracture facings. The governing equation is

\[
\phi_{R_i} \frac{\partial C_i}{\partial t} = \frac{1}{\phi_{R_i}} \left( D^' \frac{\partial^2 C_i}{\partial z^2} - \phi_{R_i} \lambda \gamma_m \mu_m C_i + \sum_{m=1}^{m} \xi \mu_m \gamma_m C_i \right),
\]

where new quantities have the following meanings.

- \(C_i'(z,t)\) = concentration of \(i\)th radionuclide in pore fluid of matrix \((\text{kg/m}^3)\).
- \(\phi\) = porosity of matrix \((\text{dimensionless})\).
- \(R_i\) = retardation coefficient of \(i\)th radionuclide in matrix \((\text{dimensionless})\).
- \(D^'\) = effective molecular diffusion coefficient through matrix \((\text{m}^2/\text{s})\).

The term \(\Gamma_i\) specifies the rate of mass transfer of the \(i\)th solute species from the fracture to the matrix continuum and takes the form

\[
\Gamma_i(x,y,t) = -\frac{2}{b_f} \left( D^' \frac{\partial C_i}{\partial z} \right)_{z=b_f},
\]

where all quantities have been defined.

References
5.3 Radionuclide Transport Modeling

Figure 5.3-2. Idealized section of the Culebra Dolomite Member of the Rustler Formation for radionuclide transport: (a) conceptual model and (b) corresponding numerical mesh.
5.0 Consequence Analysis

5.3.3 Code Linkage for 1990-1991 Transport

In the 1990 and 1991 performance assessment, various general radionuclide transport codes, including STAFF2D,¹ SUTRA,² and SWIFT³ were used to describe quantitatively the transport of radionuclides through the Culebra Dolomite Member of the Rustler Formation. These codes are described as follows:

STAFF2D models single- or dual-porosity fluid flow and radionuclide transport using a finite-element numerical solution technique. Specifically, STAFF2D is a two-dimensional finite-element code designed to simulate confined and unconfined groundwater flow and single- or multiple-component solute transport in fractured or granular aquifers. Fractured porous media are represented using both discrete-fracture and dual-porosity approaches. The dual porosity model's advective transport approach of contaminants through a fracture system (usually parallel plates) in the material and diffusion of contaminants into the rock matrix surrounding the fracture system.

SUTRA evaluates saturated or unsaturated density-dependent groundwater flow with either (1) solute transport subject to equilibrium adsorption and zero- and first-order production or decay or (2) thermal energy transports in the groundwater and solid matrix of the aquifer. SUTRA approximates the governing equations using a two-dimensional, finite-element, and integrated finite-difference method.

SWIFT II is general-purpose code for solving transient, three-dimensional, and coupled equations for fluid flow, heat transport, brine-miscible displacement, and radionuclide-miscible displacement in porous or fractured media.

Generally, the method of linking the transport software to the other portions of the consequence model starts with the local-flow, CAMDAT,⁴ data files (*.CDB files* created in Section 5.2.5 and named LOCAL_FLOW_R#.CDB; see Figure 5.3-3). RELATE⁴ is used to interpolate pertinent parameters from the regional mesh, as necessary. POSTLHS⁴ adds sampled transport parameters to the local flow .CDB files. ALGEBRACDB⁴ manipulates these parameter values to produce the specific parametric forms required by the selected transport code (see Section 3.3.3, Support Codes Used in the Modeling System, for a description of ALGEBRACDB). One of several available transport codes, which include STAFF2D¹ SUTRA,² and SWIFT,³ uses this modified file to simulate transport of the radionuclides released from the repository and contained in the source-term files (SOURCE_R#.CDB, created in Section 5.1.8). The analyst can exercise ALGEBRACDB⁴ to determine radionuclide flux rates across the Waste Isolation Pilot Plant (WIPP) disposal-system boundary. The results are passed on to the biosphere submodule (Section 5.4) or a compliance module (described in Section 6.1.6). This process is repeated for each scenario (S) using the appropriate source-term files.

The use of a groundwater-transport code developed specifically for the WIPP 1992 PA calculations is described in Section 5.3.4.

**References**


5.3 Radionuclide Transport Modeling

Figure 5.3-3. Linkage of software to simulate radionuclide-transport in the Culebra Dolomite Member of the Rustler Formation for the 1990 and 1992 performance assessment calculations.
5.0 Consequence Analysis

5.3.4 Linkage of the SECOTP2D Transport Code

SECOTP2D was used in the 1992 performance-assessment (PA) calculations to evaluate the transport of radionuclides released directly above the center of the repository in the brine within the Culebra Dolomite of the Rustler Formation. SECOTP2D is defined as follows:

SECOTP2D is a transport code that simulates single- or multiple-component radionuclide transports in fractured or porous aquifers. Fractured porous media are represented by a dual-porosity model. In 1992, the code was two-dimensional, did not allow mixtures of fractured and non-fractured materials, and required a constant aquifer thickness. The code uses total-variation-diminishing (TVD) schemes to model the advective part of the transport equation. The TVD schemes help eliminate the need to guess the required amount of “upwinding” (numerical smoothing) to control sharp gradients in the solution. Traditional upwind weighting schemes require the user to specify a weight, a priori. A user's and theory manual is in preparation.

Generally, the method of linking SECOTP2D is similar to the 1990 and 1991 PA transport-code linkage method in that the transfer files are the local velocity fields (LOCAL_FLOW_R#.CDB). However, these files are now created by SECOFL2D, which produces both regional and local .CDB flow files (both files are described in Section 5.2.5). The local .CDB file with double-precision velocities is used in SECOTP2D. As in the linkage of other transport codes (Section 5.3.3), POSTLHS and RELATE are used to place sampled transport parameters and to interpolate pertinent parameters from the regional mesh onto the local flow files (.CDB files). The analyst exercises ALGEBRACDB to compute specific parametric forms required by SECOTP2D from parameters already existing on the data base. SECOTP2D uses the modified file and time-varying concentrations of radionuclides released from the repository and stored in the source-term files (SOURCE_R#.CDB—created in Section 5.1.8) to simulate radionuclide transport in the Culebra. SECOTP2D calculates radionuclide flux rates at specified boundaries to estimate releases to the accessible environment and places them on the output .CDB files, TRANSPORT_R#.CDB. This file is used by the biosphere transport submodel (described in Section 5.4) or the compliance module to estimate cumulative releases (described in Section 6.1.6). As with other transport codes, the process is repeated for each scenario (S) using the appropriate source-term files.

The use of various other transport codes for the 1990 and 1991 PA calculations is described in Section 5.3.3.

References


Figure 5.3-4. The linkage of SECOTP2D with the modeling system to predict transport of radionuclides within the Culebra Dolomite Member of the Rustler Formation above the Waste Isolation Pilot Plant repository in the 1992 performance assessment calculations.
5.0 Consequence Analysis
5.4 Biosphere Transport Modeling

Traditionally, estimates of radiological doses have been used to evaluate the impact of the Waste Isolation Pilot Plant (WIPP) project on the human environment, at least in Environmental Impact Statements,\textsuperscript{1,2} which have been required of major federal projects, according to the National Environmental Policy Act\textsuperscript{3} (see Section 6.2, National Environmental Policy Act Simulations). To evaluate potential radiological effects on hypothetical individuals living around the WIPP site up to 10,000 yr in the future, it is necessary to model radionuclide transport through the Earth's biosphere. The WIPP Project's approach in the 1990-1992 performance assessment was stochastic. Performance-assessment analysts use the stochastic concentrations of the various radionuclides transported in the groundwater from the previous section (Section 5.3). However, constant, median values were used for all numerous model parameters required by the biosphere transport model described here (i.e., no biosphere model parameters were sampled). The mean doses from biospheric-transport calculations were then reported and compared with other types of radiological doses and accepted risk limits from other national geologic-disposal programs (see Section 6.2, National Environmental Policy Act Simulations).

Sections 5.4.1 and 5.4.2 briefly describe the three predominate pathways for radionuclides that might be released from the WIPP repository to reach humans and the linkage of software in the consequence-modeling system that calculates them.

References
\begin{enumerate}
\end{enumerate}
5.0 Consequence Analysis

5.4.1 Radionuclide Pathways to Humans

Biospheric transport models use results from both cuttings-removal calculations and groundwater-transport calculations (Section 5.3) to assess potential radiological effects on individuals. In evaluating the transport of radionuclides through the biosphere (Section 5.1.6), three principal exposure routes or pathways through the biosphere were considered in the 1991 and 1992 performance assessment calculations. Each requires a human-intrusion event. The pathways are briefly sketched as follows:

(a) Individuals operating the exploratory drill that penetrates the Waste Isolation Pilot Plant repository are exposed externally and internally (through inhalation) to contaminated soil and rock dust because of their proximity to the drilling operations (see Figure 5.4-1, top). (b) Contaminated brine from an exploratory drillhole leaks into the Culebra Dolomite aquifer and its groundwater is pumped into a stockpond. Livestock drink exclusively from this pond and ranchers consume the livestock (see Figure 5.4-1, middle). (c) Contaminants from either a dried stockpond or dried drilling-mud pit are suspended in an air plume that continually deposits the contaminants onto a nearby farm. The farm family consumes food produced from the contaminated soil (see Figure 5.4-1, bottom). In all these pathways, present-day conditions regarding social behavior, eating habits, and available technology, etc., are assumed to persist for the next 10,000 yr. Furthermore, the hypothetical stock well in Case (b) is assumed to be located downgradient from the waste panels at a point where the high-salinity groundwater is dilute enough that cattle can consume it exclusively. Moreover, the stock well is assumed to be located so it pumps the highest concentration of groundwater radionuclides near their peak arrival time or at 10,000 yr, whichever occurs first. Finally, none of the exposures to (1) the driller, (2) the ranch families who consume contaminated beef, (3) the ranch families who receive contaminated dust from the dried stockpond, or (4) the ranch families who receive contaminated dust from the drilling-mud pit are assumed necessarily to occur at the same time. These assumptions are consistent with recommendations by the International Commission on Radiological Protection (ICRP), the National Council on Radiation Protection and Measurements (NCRP), and the Nuclear Energy Agency (NEA) of the Organisation for Economic Co-Operation and Development. Results for Case (b) are presented in Section 6.2.1, Dose Assessments.

References


5.4 Biosphere Transport Modeling

(a) Future drillers contact contaminated cuttings by direct handling or inhalation of particles.

(b) Cattle drink from stock pond filled with contaminated water pumped from local aquifer; beef is later consumed by local ranch family.

(c) Wind blown dust and water runoff from contaminated tailings is deposited onto local crops; crops are later consumed by humans.

Figure 5.4-1. Three potential pathways for humans to come into contact with radionuclides released from the Waste Isolation Pilot Plant disposal system.
5.4.2 Executing Biosphere Transport Codes

In the 1992 performance-assessment calculations, the computer code GENII-S\textsuperscript{1,2} simulated contaminant transport in the biosphere (Figure 5.4-2). Initial radionuclide concentrations in contaminated groundwater or drill cuttings were retrieved from TRANSPORT\_S#\_R#.CDB or CUT\_CH or CUT\_RH\_SH\_RH.CD\_S#\_R#.CDB, respectively, where S# is the scenario identification number and R# is the three-digit sample set number. Because GENII-S has a built-in version of Latin hypercube sampling\textsuperscript{3} (LHS), GENII-S allows both deterministic and statistical calculations. For statistical calculations, the radionuclide concentrations must be statistically characterized to allow for LHS sampling within GENII-S. Based on directives in an input file (named PREGENII.INP), PREGENII processes statistically characterized radionuclide concentrations so they are compatible with input required by GENII-S. Depending on whether the cumulative distribution functions (CDFs) for the input parameters are continuous (e.g., uniform or normal) or discrete ("empirical," e.g., step or piecewise linear) (see Section 4.1.1, Characterizing Parameter Uncertainty), two file formats are produced by PREGENII. For continuous distributions, the processed file is NUCSTAT\_Source\_S#\_R#\_Location\_Flag.TRN, where Source is either TR for groundwater transport, CH for contact-handled cuttings, or RH for remotely handled cuttings. For discrete distributions, the processed file is \texttt{Fnuclide\_Name\_S#\_Rli\_Location\_Flag.TRN}, where location\_Flag identifies the location of groundwater withdrawal. In both files, the results from all Monte Carlo simulations are contained in one file.

In addition to these processed files, the analyst enters other pertinent input information manually using a menu to run GENII-S on a personal computer.\textsuperscript{1} However, much of the necessary data such as biologic transfer factors or internal dose factors are available from and described in an internal data base (Section 6.2, National Environmental Policy Act Simulations). The output for GENII-S includes doses to the whole body or to individual organs displayed in various graphics (e.g., complementary cumulative distribution functions [CCDFs] of doses) and an ASCII file.\textsuperscript{1}

References


Figure 5.4-2. Flow of information for 1992 performance assessment calculations for biosphere transport code, GENII-S, to evaluate potential radionuclide doses to humans.
5.0 Consequence Analysis
6.0 LONG-TERM REGULATORY ASSESSMENT

The Waste Isolation Pilot Plant (WIPP) must comply with or is indirectly affected by a wide assortment of laws and regulations. Although the Environmental Protection Agency Standard (EPA), 40 CFR 191 Subpart B, Environmental Radiation Protection Standards for the Management and Disposal of Spent Nuclear Fuel, High-Level and Transuranic Radioactive Wastes\(^1,2\) is the focal point of this document, three other laws and corresponding implementation regulations have prominent effects on the model simulations designed for performance assessments and are therefore summarized in this chapter:

1. EPA Standard, 40 CFR 191 Subpart B
   - Requires probabilistic model simulations to evaluate 10,000-yr compliance for scenarios with and without human intrusion (see Section 3.2.4, Human Intrusion Summary Scenarios)
   - Requires 10,000-yr individual dose calculations for scenarios without human intrusion (see Section 3.2.3, Undisturbed Summary Scenario)
   - Requires 10,000-yr calculation of radionuclide concentrations in underground sources of drinking water for scenarios without human intrusion

   - Requires Environmental Impact Statement and supporting scientific information

   - Requires model calculations, verified with monitoring, that indicate "no migration" of hazardous materials, such as lead or volatile organic compounds, beyond the "unit" boundary (see Section 1.4.1)

   - Requires EPA to certify that the WIPP meets 40 CFR 191 standards. The certification process will be detailed in 40 CFR 194\(^9\) (criteria for implementing 40 CFR 191), which will likely contain requirements that influence future model simulations
   - Requires Department of Energy (DOE) compliance with numerous other laws

Other laws and regulations have indirect influences on WIPP long-term performance calculations. Although there are too many to list exhaustively here, the following list provides a representative sample:

1. Other environmental laws
   - Safe Drinking Water Act\(^10\) (42 U.S.C. 300f et seq.) and regulations in 40 CFR 700
   - Toxic Substances Control Act\(^11\) (15 U.S.C. §2601 et seq.) and corresponding implementation regulations (40 CFR 761)\(^12\) that could affect disposal of materials contaminated with polychlorinated biphenyls (PCBs)

2. Hazardous Materials Transportation Uniform Safety Act of 1990\(^13\) (49 U.S.C. §1801 et seq.) and applicable regulations such as 49 CFR 171-177\(^14\) and Nuclear Regulatory Commission (NRC) regulations in 10 CFR 71\(^15\) that specify rules on transportation containers and transportation practices for nuclear materials

3. Laws and regulations applicable to the operating phase of the WIPP
   - Occupational Safety and Health Act of 1970\(^17\) (OSHA) (Pub L. 91-596, 84 Stat. 1590, 29 U.S.C. 651 et seq.) and implementing regulations such as 29 CFR 1910\(^18\) that specify training for hazardous waste and noise exposure to employees
   - Clean Air Amendments of 1970\(^19\) (CAA) (Pub L. 91-604), Clean Air Amendments of 1977 (Pub L. 95-95, 42 U.S.C. 7401-7428),\(^20\) and implementing regulations such as 40 CFR 61,\(^21\) which establishes standards for radionuclides in air
• Federal Water Pollution Control Act of 1982  

The main sections of this chapter describe the first three principal laws and regulations, which influence model simulations for the WIPP. Section 6.1 describes simulations for 40 CFR 191. Section 6.2 describes simulations for NEPA. Section 6.3 describes simulations for RCRA.

References

6.1 Environmental Protection Agency 40 CFR 191 Simulations

In September 1985, the U.S. Environmental Protection Agency (EPA) promulgated 40 CFR 191, *Environmental Standards for the Management and Disposal of Spent Nuclear Fuel, High-Level and Transuranic Radioactive Wastes*. The regulation's preamble states that the intent of 40 CFR 191 is (1) to provide an achievable level of protection, given the existing disposal alternatives, and (2) to reduce the risk from nuclear waste to future generations to "acceptably" low levels. The latter purpose is accomplished by isolating the wastes for a significantly long time such that the risk is no greater than if the source of the waste, uranium ore, had not been mined.

The EPA 40 CFR 191 Subpart B Standard requires simulations to evaluate (1) total releases over 10,000 yr from the Waste Isolation Pilot Plant (WIPP) disposal system, (2) individual doses to the public in the accessible environment beyond the boundary of the disposal system, and (3) radionuclides concentration in any underground drinking water. These later requirements do not greatly influence the required simulation at the WIPP and so they are not emphasized in the remainder of the section. As described in Chapter 1, Sandia's approach to evaluating the WIPP against first environmental criteria resembles a scenario-based, probabilistic risk assessment (PRA) such as those designed for nuclear reactor safety studies—in which the performance metric, total cumulative radioactive release, is specified in probabilistic terms as a complementary cumulative distribution function (CCDF).

The U.S. Court of Appeals for the First Circuit vacated (i.e., rescinded) Subpart B of 40 CFR 191 in July 1987 and remanded it to the EPA for further consideration. Some major points of contention were the 1000-yr time period for Individual Protection Requirements and the Groundwater Protection Requirements.

The *Waste Isolation Pilot Plant Land Withdrawal Act* (WIPP LWA) (Pub. L. 102-579, 1992) transferred land for the site from the Bureau of Land Management in the Department of the Interior to the Department of Energy. More important from the standpoint of the PA process, it set policy guidelines for the certification of the WIPP as a disposal facility for transuranic waste. Specifically, it established the EPA as the regulator for the WIPP. The EPA intends to provide further guidance on how it will interpret aspects of 40 CFR 191 in 40 CFR 194, which will possibly influence the style of calculations to be performed.

The WIPP LWA also required the EPA to repromulgate 40 CFR 191 for the WIPP. Although the repromulgation of 40 CFR 191 in December 1993 increased the regulatory period for individual protection and groundwater-protection requirements to 10,000 yr, it did not significantly change the application of 40 CFR 191 to the WIPP.

Section 6.1.1 describes 40 CFR 191 and two aspects of the Containment Requirements. Section 6.1.2 outlines EPA release limits. A brief overview of CCDF construction is given in Section 6.1.3. Sections 6.1.4 through 6.1.6 provide details on the construction of CCDFs for WIPP PAs.

References


* A plot of probability of exceedance of a given level versus that level.
6.0 Long-Term Regulatory Assessment

6.1.1 Overview of 40 CFR 191

The Environmental Protection Agency's (EPA's) radioactive-waste disposal regulation, 40 CFR Part 191, Environmental Standards for the Management and Disposal of Spent Nuclear Fuel, High-Level and Transuranic Radioactive Wastes, was originally promulgated in 1985. The 1985 regulation was divided into two subparts (see Figure 6.1-1(a)). Subpart A limited the radiation doses received by members of the public in the "general environment" as a result of management and storage of transuranic waste, high-level waste, and spent nuclear fuel. Subpart B provided long-term performance measures for the disposal system and contained four major sections: post-closure Containment Requirements (Section 191.13), Assurance Requirements (Section 191.14), post-closure Individual Protection Requirements (Section 191.15), and post-closure Groundwater Requirements.

The Containment Requirements were based on a fundamental criterion that no more than one premature cancer death per decade would occur over the first 10,000 yr from the disposal of wastes produced from 100,000 metric tons of heavy metals (MTHM), or \( 10^{-6} \) health effects/MTHM-yr on average. This corresponds to one hundredth the risk factor predicted for an equivalent amount of unmined uranium from three actual ore bodies and appeared achievable without significant effects on the costs of deep geologic disposal. The derived criteria given in the Containment Requirements were probabilistic limits (see Section 6.1.2. Environmental Protection Agency Release Limits) on time-integrated radionuclide releases from the disposal system (see Section 1.4.1. Terminology Used in 40 CFR 191). The models the EPA used to move from the fundamental criterion to quantitative limits considered releases to a river, an ocean, the land surface, and included a volcanic and meteoritic disruption. The most stringent of the three pathways—river water ingestion—was used in calculating the release limits (see Section 6.1.2). The regulatory time period for assessments, 10,000 yr, was selected to be sufficiently short that potential changes in geologic conditions would not add undue uncertainty to the calculations yet long enough that (1) many radionuclides would have undergone decay, (2) several radionuclides would likely be in transit through the disposal system, and (3) the probability of inadvertent disruptive events would be large enough to include.

The Assurance Requirements established a qualitative design and control philosophy to increase confidence that the probabilistic release limits in the Containment Requirements would be met. The Assurance Requirements included a multiple-barrier concept, a feasibility-of-retrievability position, and passive institutional controls such as government ownership and permanent markers. The Individual Protection Requirements established maximum annual radiation doses to the public in the accessible environment. The Groundwater Protection Requirements established limits on radionuclide contamination in certain sources of water near or within the controlled area. The latter two requirements were established to promote the use of well engineered barriers.

The repromulgated 1993 regulation is now divided into three subparts (see Figure 6.1-1(b)). Subpart A remains unchanged from the 1985 version. Changes were made to the Individual Protection Requirements of Subpart B, and Subpart C redefined the Groundwater Protection Requirements that were originally included in Subpart B. The important change to the Individual Protection Requirements in Subpart B was the lengthening of the time interval for consideration of undisturbed performance from 1000 to 10,000 yr. Subpart C includes the Environmental Standards for Groundwater Protection that are also based on evaluations for a period of 10,000 yr. In addition, the groundwater protection standards are now more closely tied to Safe Drinking Water Act requirements.

References


Management & Short-Term Storage (Operational Criteria)  

40 CFR 191  

Dose Limits to Public During Operation of Repository  

(191.03)  

Management & Storage Standards  

(191.13)  

Containment  

Release Limits up to 10,000 yr for all Scenarios  

(191.14)  

Assurance Design & Control Philosophy  

• Multiple Barriers  
  • Natural Resources  
  • Recoverability  
  • Monitoring  
  • Institutional Controls  

(191.15)  

Individual Protection  

Dose Limits to Public for 1000 yr for Undisturbed Scenarios  

(191.16)  

Groundwater Protection  

Concentration Limits to Special Sources of Drinking Water for 1000 yr for Undisturbed Scenarios  

Subpart A  

Subpart B  

Subpart C  

Figure 6.1-1. Organization of 40 CFR 191: (a) original 1985 Rule 1 and (b) repromulgated 1993 Rule. 3
6.1.2 Environmental Protection Agency Release Limits

Containment Requirements (40 CFR 191.13) specify general limits on the release of transuranic (TRU) waste, high-level waste, or spent nuclear fuel (SNF) from a geologic repository. Environmental Protection Agency (EPA) release limits are defined as the normalizing factors for various radionuclides listed in Table I of Appendix A of EPA regulation 40 CFR 191 (see Figure 6.1-2). According to the Containment Requirements, there must be a reasonable expectation, based on a performance assessment that includes all significant processes and events, that the cumulative release of any one radionuclide over 10,000 yr to the accessible environment shall have

- less than 1 chance in 10 of exceeding the promulgated EPA radionuclide limits \(L_i\), and
- less than 1 chance in 1000 of exceeding 10 times those quantities.

For a mix of radionuclides, the sum of all releases, where each radionuclide is normalized with respect to its \(L_i\), shall have

- less than 1 chance in 10 of exceeding 1, and
- less than 1 chance in 1000 of exceeding 10.

\[
R_j = \frac{1}{f_w} \left( \frac{Q_{1j}}{L_1} + \frac{Q_{2j}}{L_2} + \ldots + \frac{Q_{nRj}}{L_{nR}} \right) = \sum_{i=1}^{nR} \frac{Q_{ij}}{f_w L_i} \leq 1 \text{ (or 10)}
\]

where

- \(f_w\) = waste unit factor = \(\sum W_i / 10^6 C_i\), see Figure 6.1-2 for units
- \(W_i\) = activities in Curies (Ci) for \(\alpha\)-emitting TRU repository wastes having half-lives \(t_{1/2}\) greater than 20 yr
- \(L_i\) = the EPA release limit for radionuclide \(i\) (see Figure 6.1-2 for examples and units)
- \(nR\) = number of radionuclides contributing to the release
- \(R_j\) = total normalized release (EPA sum) for the \(j\)th scenario
- \(Q_{ij}\) = cumulative release for radionuclide \(i\) beyond a specified boundary, calculated from consequence model(s) (see Chapter 5.0, Consequence Analysis)
- \(q_{ij}\) = release rate into accessible environment at time \(t\) for radionuclide \(i\) and scenario \(j\) calculated from consequence model(s) (see Chapter 5.0, Consequence Analysis)

The EPA release limits \(L_i\) for radionuclides \(i = 1, \ldots, nR\) are based on generic analyses of hypothetical repositories containing SNF, not TRU waste. The models the contractors for the EPA used to establish the limits considered releases to a river, an ocean, and the land surface. The analysis assumed radionuclides released from the disposal-system boundary were instantaneously deposited into a river, an ocean, or into the land surface. The total cancers per curie were then calculated for each of the three pathways to humans. The most stringent of the three pathways, river water ingestion, was used in calculating the release limits. That is, the release limits are determined such that releases from the disposal system, the land withdrawal boundary for the WIPP [less than the maximum 5 km (-3 mi) from the boundary of the disposal region] into a river providing a large population with drinking water, would result in fewer than 1000 cancer deaths over 10,000 yr, a health hazard less than the hazard from the amount of mined uranium ore needed to produce 100,000 metric tons of reactor fuel. \(^1\) (Refer to Section 5.1.4, Linkage of the CUTTINGS Code, for unforeseen consequences of this conservative definition.)

Reference

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* These two points alone determine the EPA limits drawn on all WIPP CCDFs. See Section 6.1.3, Containment Requirements.
<table>
<thead>
<tr>
<th>Radionuclides with limits on release</th>
<th>Limit, $^* L_i$ (Ci)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Americium (Am)-241 or -243</td>
<td>100</td>
</tr>
<tr>
<td>Carbon (C)-14</td>
<td>100</td>
</tr>
<tr>
<td>Cesium (Cs)-135 or -137</td>
<td>1000</td>
</tr>
<tr>
<td>Iodine (I)-129</td>
<td>100</td>
</tr>
<tr>
<td>Neptunium (Np)-237</td>
<td>100</td>
</tr>
<tr>
<td>Plutonium (Pu)-238, -239, -240, or -242</td>
<td>100</td>
</tr>
<tr>
<td>Radium (Ra)-226</td>
<td>100</td>
</tr>
<tr>
<td>Strontium (Sr)-90</td>
<td>1000</td>
</tr>
<tr>
<td>Technetium (Tc)-99</td>
<td>10000</td>
</tr>
<tr>
<td>Thorium (Th)-230 or -232</td>
<td>10</td>
</tr>
<tr>
<td>Tin (Sn)-126</td>
<td>1000</td>
</tr>
<tr>
<td>Uranium (U)-233, -234, -235, -236, or -238</td>
<td>100</td>
</tr>
<tr>
<td>Any other $\alpha$-emitting radionuclide with $t_{1/2} &gt; 20$ yr</td>
<td>100</td>
</tr>
<tr>
<td>Any other non $\alpha$-emitting radionuclide with $t_{1/2} &gt; 20$ yr</td>
<td>1000</td>
</tr>
</tbody>
</table>

*For transuranic waste, these limits apply to $10^6$ Ci of $\alpha$-emitting TRU nuclides with $t_{1/2} > 20$ yr (hence, the waste unit factor, $f_w$, is the amount of the $\alpha$-emitting TRU nuclides with $t_{1/2} > 20$ yr in the repository divided by $10^6$ Ci). Other units of waste are described in 40 CFR 191, Appendix A.

Figure 6.1-2. Environmental Protection Agency release limits defined in Table 1 of Appendix A of 40 CFR 191.
6.0 Long-Term Regulatory Assessment

6.1.3 Containment Requirements

The Containment Requirements given in Section 13 of 40 CFR 191 express Environmental Protection Agency (EPA) probabilistic release limits, normally plotted as a line* (see Section 6.1.2, Environmental Protection Agency Release Limits). In evaluating compliance with these requirements, predicted releases $q_j$ from a consequence model $C$ (see Section 3.3.2, The Component Computational Models) are integrated and normalized by the EPA release limits to produce the performance measure $R_j$. See Section 6.1.2 for the equation defining $R_j$. The values of $R_j$ are then ordered from least to greatest,

$$R(S_j) < R(S_{j+1}), \text{ for } j = 1, \ldots, nS - 1$$

and are paired with the estimated cumulative probability for the $j$th scenario

$$\sum_{m=j}^{nS} P[x, S_m(x)]$$

All the consequence-probability pairs, one for each scenario, are plotted and joined stepwise to produce a piecewise continuous curve defining the probability of exceeding any given consequence value $R$, normalized by the EPA release limit. This curve is a complementary cumulative distribution function (CCDF)** from which direct comparisons with EPA regulatory limits may be made. In Appendix C of 40 CFR 191, the EPA specifically suggests this type of display for the best results. For example: "... whenever practicable, the implementing agency will assemble all of the results of the performance assessments to determine compliance with §191.13 into a complementary cumulative distribution function that indicates the probability of exceeding various levels of cumulative release." A CCDF is actually a sum of horizontal step functions. Vertical segments are usually added to avoid a broken appearance. The theoretical foundations of CCDF construction are explained in detail by Tierney and Helton.

If the sampled parameters $(x = x_1, x_2, \ldots, x_{nK})$ vary on account of uncertainties, the variation is propagated through the consequence model via Monte Carlo sampled sets, and results in a set of $nK$ CCDFs, one for each set of sampled values (see Section 1.3.1, Propagating Uncertain Parameters [Epistemic Uncertainty] through Consequence Models). The resulting distribution of CCDFs and various statistical measures of this family such as the mean, median, and percentiles are plotted. Percentiles display variance. For example, $n\%$ of the family of CCDFs lie beneath the $n$th percentile curve. (Also, the median is the 50th percentile curve.) This suite of curves (see Figure 6.1-3, bottom), together with extensive documentation of the performance assessment process, was typically presented in the 1990-1992 calculations.

References


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* The EPA limits, quoted in Section 6.1.2 are depicted in CCDF space as a set of lines connecting the two EPA limiting points as shown in Figure 6.1-3. According to the guidance of Appendix C of 40 CFR 191, the EPA can consider a disposal system to be in compliance if the CCDF (predicted by the appropriate probability and consequence models) equals or is less than the two limiting points.

** The CCDF is one minus the values of the CDF ($1 - \text{CDF}$), where the cumulative distribution function is the integral (or sum, as appropriate) of the probability density function from zero to a variable upper limit.
Figure 6.1-3. Construction of complementary cumulative distribution functions (CCDFs) (Rechard, ed., 1992, Figures A-6, A-8). A single CCDF constructed by pairing exceedance probabilities \( [\Sigma P(S)] \) and normalized releases \( R_j \) calculated for a consequence model C using one set of model parameters \( x_m \). Summary statistics of a distribution (family) of CCDFs produced from all Monte Carlo samples of model parameters and used for comparison with the EPA limiting line.
6.1.4 CCDFs When Parameter Space Is Not Decomposed into Scenarios\footnote{In WIPP PAs, parameter space is decomposed into scenarios. Section 6.1.4 is included only because it lays the groundwork for the WIPP case in which parameter space is decomposed into scenarios (see Section 6.1.5.)}

If the sample space of possible futures of the disposal system is not divided into \( n_S \) summary scenarios or computational scenarios, the complementary cumulative distribution function (CCDF) is calculated as follows\footnote{Tierney, M.S., R.V. Guzowski, and R.P. Rechard. 1993. "Scenario Development," Initial Performance Assessment of the Disposal of Spent Nuclear Fuel and High-Level Waste Stored at Idaho National Engineering Laboratory. Volume I: Methodology and Results. Ed. R.P. Rechard. SAND93-2330/1. Albuquerque, NM: Sandia National Laboratories. 7-1 through 7-27.}: (Figure 6.1-4):

1. \( n_K \) Latin hypercube samples are drawn from the \( n_P \)-dimensional parameter space, where \( n_P \) is the total number of model parameters in the model of the disposal system and \( n_V \) is the number of parameters that vary \( n_V \leq n_P \) and \( n_V \leq n_K \).

2. Radionuclide releases of each \( i \)th radionuclide over time, \( q_{ik} \), are evaluated using each of the \( n_K \) sample sets of uncertain parameters; all other parameters are held constant in the modeling system. Results of each of the \( n_K \) evaluations are recorded.

3. The performance measure, \( R_k \) (e.g., the EPA summed normalized release), is evaluated for each of the \( k = 1, \ldots, n_K \) releases.

\[
R_k = \sum_{i=1}^{n_R} \frac{Q_{ik}}{f_w L_i}, \quad k = 1, 2, \ldots, n_K
\]

where
\[
\begin{align*}
\frac{f_w}{L_i} &= \text{the waste unit factor for scaling EPA release limits} \\
L_i &= \text{the EPA release limit for } i \text{th radionuclide} \\
n_R &= \text{number of radionuclides monitored for 40 CFR 191} \\
n_K &= \text{number of samples} \\
Q_{ik} &= \text{cumulative release for } i \text{th radionuclide}, \int_0^{10,000 \text{ yr}} q_{ik} \, dt \\
q_{ik} &= \text{release rate at time } t \text{ for radionuclide } i \text{ calculated from consequence models.}
\end{align*}
\]

4. The performance measures, \( R_k \), are ranked.

5. The probability of the performance measure exceeding a specified value \( P(R_k > R) \) is estimated from the frequency:

\[
P(R_k > R) = n_G / n_K
\]

where
\[
\begin{align*}
n_G &= \text{number of simulations with } R_k \text{ exceeding } R \\
n_K &= \text{number of samples} \\
R &= \text{specified value (on graph abscissa).}
\end{align*}
\]

6. The value of the performance measure, \( R_k \), is then paired with the probability \( P(R_k > R) \) to produce a mean CCDF.

Reference

Sample all $nV$ parameters $nK$ times (e.g., time of intrusion, drilling position, and number).

Order all performance metric values, $R$, evaluated from the consequences, $C$.

Where $nG$ is number of simulations with $R_k > R$, and $nK$ is total number of samples (16 shown as example).

Shape of Mean curve approximately the same as in §6.1.5 but $nk$ (16) steps.

Figure 6.1-4. Method of calculating CCDF when parameter space is not decomposed into scenarios (Tierney et al., 1993).
6.1.5 CCDFs When Parameter Space Is Decomposed into Scenarios

When a sample space is discretized, results may be presented in several ways\(^1,2\): (1) a complementary cumulative distribution function (CCDF) can be calculated for each scenario, conditional on the scenario occurring; (2) a CCDF can be calculated for all the scenarios, using the sample space set for each scenario; or (3) the mean CCDF can be calculated from either (1) or (2). This mean CCDF is approximately equal to the mean CCDF calculated without discretizing the sample space into scenarios (provided the scenario discretization is not so coarse that it ignores significant variations and provided the approximations in calculating the individual scenario probabilities \(P(S_j)\) are acceptable). The following text describes the steps necessary for presenting the results by the three methods. The second method was used for the 1991 and 1992 PAs; the third method was used for the 1990 and 1991 PAs.

**CCDF Conditional on Scenario \(S_j\) Occurring.** The method of calculating a CCDF conditional on the scenario occurring is identical to that described for CCDF construction without scenarios except that only those performance metric values, \(R(S_j)\), from the scenario of interest, \(S_j\), are used.

**CCDF of All Scenarios Using One Sample Set** (used by the Waste Isolation Pilot Plant [WIPP] Project). To calculate one CCDF for a sample set over all scenarios, only subtle differences exist in a few of the steps from Section 6.1.4:

1. Radionuclide releases over time, \(q_{ik}\), are evaluated using one sample set of varied parameters with all other parameters held constant in the modeling system. The sample sets of varied parameters are slightly different from those without scenario discretization because those parameters that define the scenario are now held constant. This step is repeated for each sample set.
2. The performance measures are ranked such that \(R_k(S_j) < R_k(S_j+1)\) for \(j = 1, \ldots, nS-1\).
3. The probability of a scenario, \(P_k(S_j)\), is evaluated from the probability model of the scenario.
4. The value of the performance measure, \(R_k\), for one sample set is then paired with the cumulative probability

\[
\sum_{m=j}^{nS} P(S_m)
\]

This is repeated for each scenario \(S_j, j=1, \ldots, nS\), to produce a CCDF.
5. Step 4 is repeated for each sample set to produce a distribution (or "family") of \(nK\) CCDFs.

**Mean CCDF.** The mean CCDF can be estimated from either the distribution of CCDFs produced above or the CCDFs conditional on the scenario. The mean CCDF from the distribution of CCDFs is the arithmetic average of the probabilities of the family of CCDFs at specified values of \(R\). The mean CCDF from the CCDFs conditional on the scenario is calculated as follows:

1. Produce a family of \(nS\) CCDFs by evaluating the scaled CCDF, i.e., \(P_k(R_k > R) = P_k(R_k > R | S_j)\).
2. Provided that parameters in the probability model used to evaluate \(P(S_j)\) were not varied, the mean CCDF is the arithmetic average of this distribution of CCDFs.
3. If parameters in the probability model were varied, then \(P_k(x_k, S_j)\) would vary with each sample, \(x_k\), so that each conditional CCDF results in \(nK\) scaled CCDFs, i.e., \(P_k(R_k > R | S_j)\). This distribution of \(nK\times nS\) CCDFs can now be averaged as before to calculate the mean CCDF (used by the Waste Isolation Pilot Plant Project).

**References**


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Figure 6.1-5. Method of calculating a CCDF when part of the parameter space is decomposed into scenarios (Tierney et al., 1993).
6.0 Long-Term Regulatory Assessment

6.1.6 Software for Calculating Complementary Cumulative Distribution Functions

Construction of a complementary cumulative distribution function (CCDF) for comparison with the Containment Requirements of 40 CFR 191 consists of (1) normalizing and summing cumulative releases \((Q_n) of nR\) radionuclides to the accessible environment \((R_n)\) for each \(nK\), samples to obtain \(nk\) summed, normalized releases for each of the \(nS\) scenarios, and (2) plotting the \(nR \cdot nk\) summed normalized releases versus the appropriate scenario probabilities \((p)\) (see Sections 6.1.3, 6.1.4, and 6.1.5.). The following software is typically used:

CCDFCALC

The CCDFCALC code\(^1\) generates conditional CCDFs where "conditional" means the CCDF is contingent on certain events or processes occurring. Most frequently, the selected event was a single or double intrusion into the Waste Isolation Pilot Plant (WIPP) repository for performance assessment calculations in 1991 and 1992.

The CCDFCALC code uses contaminant releases across a specified boundary such as the 2.4-km (1.5-mi) land-withdrawal boundary depicted in Section 1.4.1. Releases were generated by a groundwater transport code such as STAFF2D or SECOTP2D (see Section 5.3.3 or 5.3.4) for each set of sampled parameters. One conditional CCDF curve is generated from each sampled set in which the following three types of intrusions usually are considered: a single intrusion into a panel of the repository (Case E2); a single panel intrusion that continues down to a pressurized brine pocket (Case E1); and a double intrusion into one panel with one intrusion continuing down to a pressurized brine pocket (Case E1E2) (see Section 3.2.2, Applying the Grouping Procedure to the WIPP).

Radionuclides brought to the surface by drilling into the repository (see Section 5.1.4) can also be included in the CCDFCALC plot. Those data include contact-handled (CH) and remotely handled (RH) contaminant releases that reside in the binary files CUT_CH_R#.CDB and CUT_RH_R#.CDB (see Figure 6.1-6). CCDFCALC writes the normalized discharges (cuttings and groundwater releases) for all the sample sets to the ASCII file, CCDFCALC.TRN, that can be used for sensitivity/uncertainty analysis (see Chapter 7).

CCDFPERM\(^1,2\)

If groundwater discharge and cuttings data are available for several intrusion times and for different intrusion geometries (Cases E1, E2, and E1E2), linear combinations of the data can be used by the CCDFPERM code (see Figure 6.1-6) to include the effects of intrusion geometry, multiple drilling intrusions, and different concentrations of waste activity to produce the "composite" CCDF, which is the relevant measure to compare with the EPA limiting line.

CCDFPERM takes a sampled drilling intrusion rate, \(\lambda\), either constant or time dependent, and determines the probabilities of intrusions over 10,000 yr. Some specific assumptions used in the 1991 and 1992 PA calculations are as follows. When two intrusions fall in the same time interval, the intrusion probability is apportioned between the E1E2 and non-E1E2 cases based on the number of panels. The E1E2 case requires two hits in the same panel during the same time interval. For each intrusion, all possible combinations of waste activities are considered. Each combination of intrusion time intervals and waste activities generates one point for the CCDF plot.

NUCPLLOT\(^1\)

NUCPLLOT depicts the contribution [in activity (Ci) or percentage] of each radionuclide to the final CCDF. The contribution of each radionuclide varies slightly for each parameter set. The contribution is therefore a distribution and is depicted as a Tukey bar graph.

References


Figure 6.1-6. Linkage of software for constructing complementary cumulative distribution functions (CCDFs) in the 1991 and 1992 performance assessment calculations.
6.0 Long-Term Regulatory Assessment
6.2 National Environmental Policy Act Simulations

The National Environmental Policy Act (NEPA) of 1969\(^1\) and implementing regulations in 40 CFR 1500-1508 require all federal agencies to prepare detailed statements on the impact of proposed "major federal actions significantly affecting the quality of the human environment," followed by adequate time for public comment. NEPA was the first environmental policy law to apply to the Waste Isolation Pilot Plant (WIPP) (see Section 1.5, Regulatory Influences on the Waste Isolation Pilot Plant Project). NEPA only establishes policy and regulations that implement the NEPA statute do not require specific types of model simulations.

Two environmental impact statements (EISs) have been prepared for the WIPP, one in 1979-80 during deliberations to decide whether to proceed with construction of the facility,\(^2\) and a supplement in 1989-90 during deliberations to decide whether to proceed with an experimental phase.\(^3\) In both EISs, the Department of Energy (DOE) included dose* assessments from hypothetical exposure pathways after human disturbance. Furthermore, the WIPP Panel of the Board of Radioactive Waste Management of the National Academy of Sciences, a panel that reviews the scientific basis of the WIPP, has requested dose assessments over 10,000 yr for individuals living in the future.

What follows are the types of results that have been presented to the WIPP Panel based on the 1991 and 1992 performance assessment calculations using the modeling system of Section 5.4, Biosphere Transport Modeling. These kinds of results would likely be included in future supplemental EISs.\(^3\)**

References


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* Dose is defined as the quantity of radiation absorbed. It accounts for biologic effects and is measured in sieverts (Sv) or rem.

** The new 40 CFR 191 promulgated in 1993 requires dose calculations (see Section 6.1.1) assuming no human disruption of the area. Although human disruption is not required for radionuclide releases to occur at many sites in the thick, bedded salt of the WIPP, human intrusion was found to be required before any radionuclides were released in the 1990-1992 PA. Therefore, the dose requirements in 40 CFR 191 would not have been applicable.
6.0 Long-Term Regulatory Assessment

6.2.1 Dose Assessments

For the Waste Isolation Pilot Plant (WIPP) scenarios, the concentration of radionuclides inhaled and ingested by humans depends on a number of factors. For the most important pathway to humans at the WIPP, consumption of beef stock cattle that drink water from a contaminated stockpond, the concentrations depend on (1) the concentration of radionuclides in the stockpond, (2) drinking rates of cattle from the pond, and (3) how much meat is ingested by the humans residing at the ranch site (see Section 5.4.1, Radionuclide Pathways to Humans). The damage to various organs of the human body and the chance of cancer depends, in turn, on the type of radiation and the organs of the body exposed.

The first step is the evaluation of the mean absorbed dose rate on the jth organ (or tissue) from radionuclide k ($D^k_{R,j}$). This evaluation involves four primary factors: (1) the activity in source region(s) ($\Omega$) irradiating the organ ($A_{\Omega}$), (2) the mean energy emitted by radionuclide k of radiation type R ($\Delta_R^k$), (3) the ratio of energy absorbed by the jth organ to energy emitted at the source region ($\Phi_R^k$), and adjustment factors for the last two terms, a quality factor ($Q_R$) accounting for the biological effectiveness of the radiation type and a general factor ($N$) that is currently set equal to 1; hence, $D^k_{R,j} = \sum A^k_{\Omega} \frac{\Omega}{\Delta_R^k} \Phi_R^k \frac{Q_R}{N}$ where only $A_{\Omega}(t)$ is assumed to vary with time.

The next step is the calculation of the equivalent dose rate to the jth organ (or tissue) ($H_j$) to humans from a pathway considering the various types of radiation from an absorbed dose on the jth organ ($D^k_{R,j}$) and the appropriate weighting factor$^1$ for the type of radiation R ($w_R$), that is, $H_j = \sum \sum D^k_{R,j} \cdot w_R$. The equivalent dose ($H_j$) relates radiation types (α,β,γ), energy levels of neutrons, protons, and fission fragments to biological effects in various organs and is measured in units of sieverts (Sv) or rem per time.

From ingested or inhaled radionuclides emitting radiation, this equivalent dose will be spread out over time, being gradually delivered as the kth radionuclide decays. By convention, a constant rate of intake of each radionuclide is assumed to occur over one year, and then the equivalent dose over 50 yr is evaluated, the "50-yr committed dose" (Figure 6.2-la). In other words, the committed equivalent dose over the next 50 yr to the jth organ from the kth radionuclide emitting radiation R from one year of ingestion is

$$H_j = \int_0^{50 \text{yr}} H(t) dt = \int_0^{50 \text{yr}} \sum \sum \int_0^{50 \text{yr}} A^k_{\Omega} \frac{\Omega}{\Delta_R^k} \Phi_R^k w_R dt.$$

The next step is the calculation of the effective dose ($E$) to the whole body considering the equivalent doses to the major organs. To arrive at a total risk to the whole body, each of the organs (or tissue) has an organ weighting factor$^1$ ($w_j$) that takes into account the risk irradiation or ingestion of radionuclides of that organ contributes to the total whole body risk; thus

$$E = \sum w_j \cdot H_j = \sum w_j \cdot \sum \sum \int_0^{50 \text{yr}} A^k_{\Omega} \frac{\Omega}{\Delta_R^k} \Phi_R^k w_R.$$

A detailed description of these calculations can be found in Till and Meyer.$^2$ Because most factors are considered independent, the order of summation and integration can be varied; the order shown is as described for codes in Section 5.4.2, Executing Biosphere Transport Codes.

Because the concentrations of radionuclides ingested and the numerous parameters used to calculate the transfer factors to the various organs all vary, the committed effective dose ($E$) varies. It can be displayed as a complementary cumulative distribution function. A comparison of the mean simulated committed effective dose ($E$) from the stockpond-to-cow-to-human pathway at the WIPP with other general risks to the public (Figure 6.2-1b) shows the absorbed dose from the WIPP over 10,000 yr to be very small.

References


Figure 6.2-1. Dose assessment from 1991 performance assessment calculations (a) 50-yr committed effective dose (area under curve) from 1-yr internal intake and acute external exposure of radionuclides and the accompanying extended internal dose, and (b) comparison of mean annual effective dose equivalent radionuclide dose for the Waste Isolation Pilot Plant repository with radiation doses received from other sources.
6.2.2 Evaluation of Human Health Effects Per Year

Radiation protection criteria published by international organizations provide the basis for regulations in many countries for radioactive waste disposal. In 1984, the Nuclear Energy Agency (NEA) published an expert group report that introduced the concept of individual risk criteria for radioactive-waste disposal\(^1\) where risk was defined as the product of the dose exposure. Also, it was determined that the probability that doses received would give rise to deleterious health effects in the future after a latent period could be a few years for leukemia to tens of years for other forms of malignant cancer (external and internal radiation dose is usually assumed to increase the probability of cancer, regardless of the source or the amount of radiation dose). The prestigious International Commission on Radiological Protection (ICRP) recommendations in the 1985 Report 46\(^2\) (reiterated more recently in 1990 Report 60\(^3\)) complemented the 1984 NEA report. The principal recommendation is as follows: Risk for individuals of the public should correspond to the risk associated with the current ICRP individual dose limit (1 mSv/yr) (see Section 6.2.1). This annual limit corresponds to a risk of about 1 in 100,000 of experiencing a fatal cancer in any year (Figure 6.2-2). Several national regulations (e.g., the United Kingdom, Canada, and the Nordic countries) follow this recommendation but set the risk limit one order of magnitude lower than at \(10^{-6}\) health effects/yr for radioactive waste disposal on the belief that waste disposal is only one of several potential sources for radiation exposure. Other differences in the application of this principal recommendation occur among countries because (1) some exclusively express the limits in terms of dose rather than health effects or vice-versa, (2) some use individual while others use population dose or health effect limits (3) some specify different regulatory periods, and (4) some require different levels of detail or style of the calculations.

For the purpose of making comparisons with recommendations by the ICRP and other internal criteria in the 1991 performance assessment (PA) calculations, the Waste Isolation Pilot Plant (WIPP) made the usual assumption that there was a probability of \(10^{-2}\) health effects per sievert of mean annual committed effective dose equivalent in the 1991 PA calculations. Hence, the calculated risk was about \(10^{-10}\) health effects per year \((10^{-2}\) health effects/Sv \(* 7.8 \times 10^{-9}\) Sv/yr\) (see Section 6.2.1) for the hypothetical stockpond-to-cattle-to-human pathway at the WIPP (see Section 5.4.1, Radionuclide Pathways to Humans). The hazard in this preliminary calculation was orders of magnitude less than the ICRP recommended limit and target-hazard criteria for deep geologic nuclear-waste repositories in other nations (Figure 6.2-2).

References

Figure 6.2-2. Comparison of cancer health effects from the WIPP (from 1991 performance assessment calculations, assuming $5 \times 10^{-4}$ health effects per rem) with acceptable hazards permitted by other countries.
6.0 Long-Term Regulatory Assessment
6.3 Resource Conservation and Recovery Act Simulations

The Resource Conservation and Recovery Act (RCRA) of 1976 and subsequent amendments, most notably the Hazardous and Solid Waste Amendments of 1984, provide for the management of hazardous chemical wastes. The corresponding Environmental Protection Agency (EPA) regulations are 40 CFR Parts 124-181. The primary influence of RCRA to the Waste Isolation Pilot Plant (WIPP) are the following implementing regulations:

- 40 CFR 270—specifying the permitting process and the two parts of the RCRA permit, Parts A and B. In particular, Section 270.23 specifies information required in Part B for a "miscellaneous unit" such as the WIPP.
- 40 CFR 268—specifying land-disposal restrictions for hazardous waste; specifically, Section 268.6 describes the petitioning procedure for applying for a 'No-migration' variance under these provisions.

The current WIPP approach to these RCRA regulations is to petition for a "no-migration" variance to the land-disposal restrictions for hazardous wastes that are not treated (e.g., neutralized) by approved procedures (40 CFR 268.6). Such a petition allows hazardous chemicals to be disposed of in the repository for the maximum length of time allowed in the permit, with renewals as necessary. However, the petitioner must demonstrate "to a reasonable degree of certainty that there will be no migration of hazardous constituents from the disposal unit ..." (40 CFR 268.6[a]). In March 1990, the U.S. Department of Energy (DOE) petitioned the EPA for a "no-migration" determination for the test phase of the WIPP, submitting results from deterministic modeling demonstrating to a reasonable degree of certainty, that any test wastes would not migrate from the disposal unit for the WIPP (the Salado Formation bounded by the WIPP land-withdrawal boundary—see Section 1.4.1). The EPA issued a conditional "no-migration" determination for the WIPP Test Phase only in November 1990. Also in 1990, the EPA authorized the State of New Mexico to apply RCRA regulations to facilities in the state that manage radioactive wastes (see Section 1.5.1, Timeline of Events for the WIPP Project).

In addition in May 1995, the DOE sent a draft to the EPA for a "no migration" determination for the 35-yr operational/closure phase of the WIPP that again included deterministic modeling demonstrating that concentrations of hazardous constituents remained far below health standards outside the disposal unit during operations. The analysis were limited to deterministic consequence modeling following current EPA guidance that states "model assumptions and input data should be conservative and tend toward overestimating rather than underestimating migration."

The petition for the variance for permanent disposal (after the operational phase) will require predictive calculations, but the stochastic nature and similarity to calculations performed to evaluate compliance with 40 CFR 191 must be negotiated with the EPA and the state of New Mexico. In contrast to 40 CFR 191 calculations, it is likely that only repository performance and no human intrusion, whether purposeful or inadvertent, will be evaluated. However, calculations done to date for the WIPP have used stochastic consequence modeling to present a consistent style of calculation to the EPA and the public (see Section 7.1.1, Ranking Important Model Parameters, for examples of simulations for RCRA) and this is the current intent of the DOE.

References
6.0 Long-Term Regulatory Assessment
7.0 SENSITIVITY/UNCERTAINTY ANALYSIS

Sensitivity analysis involves determining the effect of varying parameters of a model on the consequences, \( C[x, S_j(x)] \), of the model. Uncertainty analysis involves determining the contribution (importance) of variation of an individual parameter \( S_j \) to the associated uncertainty of the consequences (distribution of \( C[x, S_j(x)] \)). The latter, uncertainty analysis, is discussed in more detail elsewhere in this report. Both analyses are strongly influenced by the parameter range used, but uncertainty analysis also includes the likelihood that the parameter will reach the endpoints of its range. The uncertainty analysis method described herein includes the creation of scatterplots, the development of regression models between parameters and results (see for example, Helton et al.\(^2\)) and the use of absolute values of standardized regression coefficients (or the mathematically related partial correlation coefficients) from the regression models.

The four principal purposes of the sensitivity/uncertainty analysis are (1) to gain understanding and insight about the disposal system, (2) to help verify the correctness of the calculations, (3) to evaluate the influence of various options for waste forms on the results, and (4) to provide input so decision makers can allocate resources in later performance assessment iterations to collect data about the parameters that most influence the results, based on what is already known about the site or waste. Because uncertainty and sensitivity analyses are inherently conditional on the models, data distributions, and techniques used to generate them, they cannot provide insight about parameters not sampled, conceptual and computational models not used in the analysis, or processes that have been oversimplified in the analysis. Hence, qualitative judgment about the modeling system must be used in combination with the results of sensitivity/uncertainty analyses to set priorities for additional data acquisition and model development.

References


Uncertainty analysis is a technique to evaluate how the uncertainties in a parameter (i.e., how likely it is to vary) relate to uncertainty in the results. The results of a model may be very sensitive to varying a parameter, but if the parameter's value is precisely known, the parameter will not contribute to producing uncertainty in the prediction. (Uncertainty analysis is sometimes called importance analysis.)
7.0 Sensitivity/Uncertainty Analysis
7.1 Evaluations of Statistical Correlations

The purpose of uncertainty analysis is to determine the contribution (importance) of uncertainties in model parameters to the associated uncertainty in the result (where the results are usually the consequences, $C(x, S(x))$, but can also be the probabilities, $P(x, S(x))$). The primary measures of the uncertainty include the mean, variance, and distribution of the results of interest. This section describes briefly the uncertainty analysis techniques used, including scatterplots and stepwise regression analyses. A more detailed discussion of these techniques and their applications is given by Helton et al.\(^1\)\(^2\)\(^3\)\(^4\).

Scatterplots are the simplest sensitivity-analysis tools. The scatterplot approach consists of generating plots of the results (dependent variables) vs. model parameters (independent variables), each point in the plot representing one "realization," that is, one deterministic calculation of probability and consequence models using one set of sampled model parameters. When there is no relationship between the independent and dependent variable, the individual points are incoherently scattered over the plot or spread along a horizontal line. In contrast, the existence of a well-defined relationship between the independent and dependent variable is often revealed by patterns in the distribution of the individual points such as a spread of points along a nonhorizontal locus.

In stepwise regression analysis, a sequence of regression models is constructed. The first regression model contains the one independent variable that has the largest impact on the dependent variable. The second regression model contains the two independent variables that have the largest impacts on the dependent variable, i.e., the independent variable from the first step, plus whichever of the remaining variables has the largest impact on the variation not accounted for by the first step. Additional models are constructed in the same manner until a point is reached at which additional independent variables are unable to account meaningfully for any of variation in the dependent variable.

One way to describe meaningful improvement mathematically is through the coefficient of determination $R^2$, which is re-evaluated at each step of the regression process. $R^2$ is defined as the fraction of the total variability in the dependent variable that can be accounted for by the individual independent variable added at that step. The order in which the variables are selected in the stepwise procedure provides an indication of variable importance, with the most important variable usually being selected first, the next most important variable selected second, and so on. Further, the absolute values of the lead coefficients of the regression model normalized to make dimensionless (standardized regression coefficients [SRCs]) also provide an indication of variable importance and the sign of the SRC indicates whether the independent and dependent variables tend to increase and decrease together (a positive SRC) or tend to move in opposite directions (a negative SRC).

When the relationships between the independent and dependent variables are nonlinear, the results of regression analyses are often poor. Poor linear fits to nonlinear data can often be avoided if, instead of using the data directly, one uses the corresponding rank of the data points in order of progressive magnitude and performs the regression procedures on these ranks.\(^4\) Examples of that process are included in Figure 7.1-1.

References


\(^1\) The terms "dependent variable" and "independent variable" are used in the following paragraphs to emphasize that the result or model parameter may be modified to highlight relationships (e.g., the rank of a result may become the dependent variable and the rank of two or more model parameters multiplied together may become the independent variable).
7.0 Sensitivity/Uncertainty Analysis

7.1.1 Ranking Important Model Parameters

To demonstrate how parameter ranking is used, this section presents a small portion of the sensitivity and uncertainty analyses performed in the 1992 performance-assessment (PA) calculations to determine the factors that affect gas generation and the movement of gas and brine away from the repository for the specific purposes of assessing compliance with Resource Conservation and Recovery Act regulations (see Section 6.3). The sensitivity and uncertainty analyses use techniques based on Latin hypercube sampling, including examination of scatterplots, partial correlation analysis, and stepwise regression analysis. Specific performance measures include cumulative gas and brine outflows through the three anhydrite layers to the south of the repository (see Section 3.2.3, Undisturbed Summary Scenario), the total distance gases flow through the three anhydrite layers, and the cumulative gas and brine that flows up through the shaft seal. Also examined were various measures of the behavior of the repository itself, including cumulative gas generation by means of corrosion and biodegradation, pressure in the repository, and repository pore volume. These were analyzed to show how gas generation is affected by variability in the sampled parameters because gas generation is the driving force behind gas and brine migration away from the repository in the undisturbed scenario.

The results show that the most important parameter affecting gas and brine migration from the repository is the initial brine saturation in the waste (see Table 7.1-1 and Figure 7.1-1). This one parameter has the greatest impact on total gas generation, which in turn controls gas and brine flow into and out of the waste. Figure 7.1-1 shows several scatterplots relating brine flow to brine saturation and to anhydrite interbed porosity. It suggests that brine flows tend to increase as initial brine saturation increases. Net brine flows out of the repository range from \(-24,000 \text{ m}^3 (-845,000 \text{ ft}^3)\) to \(+11,400 \text{ m}^3 (+403,000 \text{ ft}^3)\), which suggests there is a minimum initial brine saturation \(S_{\text{init}}\) below which brine does not flow out of the waste. Because the initial brine saturation is at most half of the residual brine saturation \(S_{\text{resid}}\), the initial saturation \(S_{\text{init}}\) itself is not sufficient to cause flow from the waste. When more brine is initially present, less inflow is required to exceed the residual saturation before brine flows out. The partial rank correlation coefficients in Figure 7.1-1 confirmed that \(S_{\text{init}}\) is the dominant variable affecting net flow from the waste for the 1992 PA.

<table>
<thead>
<tr>
<th>Step</th>
<th>Variable</th>
<th>Description</th>
<th>SRC</th>
<th>R²</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>(S_{\text{init}})</td>
<td>Initial liquid saturation in waste</td>
<td>0.72</td>
<td>0.53</td>
</tr>
<tr>
<td>2</td>
<td>(\varphi_{\text{MB}})</td>
<td>Undisturbed anhydrite marker bed porosity</td>
<td>-0.30</td>
<td>0.61</td>
</tr>
<tr>
<td>3</td>
<td>(k_{\text{MB}})</td>
<td>Log of anhydrite marker bed permeability</td>
<td>-0.24</td>
<td>0.67</td>
</tr>
<tr>
<td>4</td>
<td>(S_{\text{resid}})</td>
<td>Residual brine saturation in all regions except waste</td>
<td>0.18</td>
<td>0.70</td>
</tr>
</tbody>
</table>

Reference


* The residual brine saturation is the saturation below which liquids are no longer connected through the pore network of the porous medium and therefore cannot flow regardless of the pressure gradient.
Figure 7.1-1. Scatterplots produced by STEPWISE and partial rank correlation coefficients produced by PCCSRC for cumulative net brine flow from the repository in the 1992 performance assessment calculations (WIPP PA Dept., 1993, Vol. 5, Figure 5-14). 1
(Refer to Section 7.1.2 for a brief description of STEPWISE and PCCSRC.)

7.1 Evaluations of Statistical Correlations
7.0 Sensitivity/Uncertainty Analysis

7.1.2 Computing Statistical Correlations

Sensitivity and uncertainty analyses were important parts of Waste Isolation Pilot Plant (WIPP) performance assessments (PA) in 1990 through 1992. The primary codes used to perform them were PCCSRC\(^1\) and STEPWISE\(^2\).

PCCSRC\(^1\) evaluates variable importance at each time step by reporting the partial correlation coefficients (PCCs) and standardized regression coefficients (SRCs) on either the rank or raw data.

STEPWISE\(^2\) evaluates variable importance by developing regression models between the input variable and the observed response using a forward, backward, or stepwise regression procedure on the rank or raw data. Because STEPWISE must be run separately at each time step, only regression models having results (e.g., cumulative brine flow through waste) accumulated over a few time periods (e.g., 10,000 yr) are normally used.

If useful regression models can be developed, coefficient of determination, the absolute values of the standardized regression coefficients or their mathematically related partial correlation coefficients, can be used to rank variable importance.

The complete code linkages used to perform sensitivity and uncertainty analyses on any PA results are shown in Figure 7.1-2. Access to model parameters and calculational results is gained through LHS2STEP\(^3\) and CCD2STEP,\(^3\) which act as translators, converting Latin hypercube sample output and radionuclide release output files, respectively, into forms suitable for use by the main statistical analysis codes, PCCSRC\(^1\) and STEPWISE,\(^2\) which were described above (see Section 7.1.1 for examples of results).

Two other codes, SUMMARIZE and GRAPH, are shown in Figure 7.1-2. They are support codes used often in this analysis. SUMMARIZE gathers user-specified information from the many PA files and uses it to produce tabular outputs for PCCSRC, STEPWISE, and various plotting packages such as GRAPH.

References


7.1 Evaluations of Statistical Correlations

Figure 7.1-2. Linkage of software to compute statistical correlations in the 1990-1992 performance assessment calculations.
7.0 Sensitivity/Uncertainty Analysis
8.0 PERFORMANCE ASSESSMENT ALGORITHM SUMMARY

In this report, the process of modeling the Waste Isolation Pilot Plant (WIPP) to evaluate its performance between 1989 and 1992 has been organized into six general steps. Actual assessments are, of course, continuous processes so discretization into distinct steps is an artificial and somewhat arbitrary artifact. Nevertheless, discretization is viewed as useful for describing the lengthy assessment process. The report has attempted to give concrete examples of many (but not all) of the various tasks that are associated with the six steps of a performance assessment (PA). The 1989-1992 PAs of the WIPP were a series of complicated and interdisciplinary tasks, requiring diverse skills in the physical sciences, mathematics, statistics, and numerical modeling. No one individual performed all six steps or even all of any one step of a PA. Rather, the PA calculations were performed by a coordinated team of dedicated specialists comprising analysts, modelers, code developers, data base developers, and operators. Sections 8.1 and 8.2 summarize the results of the six steps and the linkage of PA software.
8.0 Performance Assessment Algorithm Summary
8.1 Concise Review of the Six-Step Performance Assessment Process

In this section, some mathematical ideas and simple sketches are used to summarize the six steps of a performance assessment (PA) (see Figure 8.1), to list the processes within, and to state the results of each step as applied primarily to the probabilistic requirements of 40 CFR 191.1

1. Characterize the disposal system and surrounding region to develop a conceptual model. This step determines the parameter space of the conceptual model and is succinctly symbolized as \( D = \{x_1, x_2, \ldots, x_{nP}\} \), where \( nP \) is the total number of parameters of the model of the disposal system. The parameters are subdivided into three disjoint subsets as follows: (1) uncertain parameters that are classified as aleatoric or chance variables and studied through scenarios (e.g., event and feature parameters), (2) uncertain parameters that are not expressed as chance variables but rather as epistemic variables that reflect uncertainty in knowledge about a parameter (e.g., material property parameters), and (3) parameters that are fixed or varied one at a time (model constants, model domain parameters, decision parameters, and index parameters to select alternative model forms) (see Section 4.1, Assigning Parameter Uncertainties). Categorization into the three subsets is determined primarily by (1) analyst preference in exploring the uncertainty of a particular characteristic and (2) presently accepted methods of calculation, for example, expressing a "choice" or "decision" parameter such as waste-treatment options as a probability distribution is uncommon.

2. Form scenarios from the subset of uncertain parameters selected for study. Although typically handled in a heuristic manner, this step can be described as the process of describing the state of the aleatory parameters that define particular chance conditions of the disposal system such as an event—human intrusion or no human intrusion—or a feature—brine reservoir or no brine reservoir. The feasibility of quantifying the probabilities associated with these aleatory parameter choices is a very important aspect of this step. Without it, the next step becomes impossible.

3. Develop probability models to quantify the probability of occurrence of each scenario and quantify the uncertainty of model parameters. Two types of probability models are developed in this step. The first evaluates the probability of a specific summary scenario occurring. The second produces distributions to express the uncertainty in selected parameters that arise in the consequence and probability models. At this point, the PA model-system parameter space, \( D' \), can be identified. It usually differs, but only subtly, from the original conceptual-model space.

4. Develop models that simulate consequences for the sets of model parameters that occur and exercise them. This step involves developing consequence models and performing simulations. The simulations are the most mechanical part of the PA process. Because Monte Carlo simulation is used to propagate parameter uncertainties through the model, numerous repetitive simulations are required. Consequently, the model-development process must result in a product that is feasible to run many times. Consequently, several model domains, both spatial and temporal, are used, and several uncoupled but linked computational models are used.

5. Compare the generated consequence of each scenario and its corresponding probability with regulatory criteria. This and the next step correspond to analysis of results. The modeling system is quite complicated if the applied model incorporates many features, events, and processes. Correspondingly, the analysis can be complex and demanding. Results are usually displayed succinctly as complementary cumulative distribution functions (CCDFs). Means and various quantities are commonly shown.

6. Evaluate the sensitivity and uncertainty of results to changes in model parameters. Summary measures such as mean CCDFs distill into simple curves collections of results that require volumes to describe. They can, however, obscure many interesting aspects of the result. Hence, sensitivity and uncertainty analyses must be added to highlight various findings.

References

1) Characterize disposal system
   (Develop parameter space) (§ 2.0)

\[ D = \{ x_1, x_2, x_3, x_4, x_5, x_6, x_7 \} \]

Subset uncertainty studied separately
(often event and feature parameters)

Subset uncertainty characterized by
distributions (often natural process
parameters)

Subset fixed or varied one at a time
(e.g., model form indices, model
domain size, and physical
constants)

2) Form scenarios (§ 3.0)

\[ x_1 = \{ \text{intrusion, (I)} \} \]
\[ x_2 = \{ \text{no intrusion, (i)} \} \]

(§ 3.2)

\[ x_2 = \{ \text{drill into brine pocket, } E_1 \} \]
\[ x_2 = \{ \text{miss brine pocket, } \bar{E}_1 \} \]

(§ 3.2)

Note: no intrusion, I not combined
with E_1 or E_2; thus, 3 scenarios

3) Develop probability models (§ 4.0)

\[ P \{ l = n \} = \frac{\lambda^n e^{-\lambda}}{n!} \]
(§ 4.2)

\[ P \{ E_1 \} = \frac{A_{\text{rep}}}{A_{\text{pocket}}} \]

(sample value for l for kth Monte Carlo run)

\[ D' = \{ \lambda, A_{\text{pocket}}, k_{\text{salt}}, k_{\text{Culebra}} \} \]

PA model parameter set
4) Simulate consequences (including propagating uncertainty) for each scenario identified (§5.0)

\[ P \{ \tau \} \quad C \{ \tau \} \quad P \{ \tau \} = \frac{n!}{\lambda^n e^{-\lambda}} \quad C \{ E_1 \} \quad P \{ E_1 \} = \frac{A_{rep}}{A_{pocket}} \]

5) Compare results with criterion (§6.0)

\[ P(C) \]

\[ C \{ \tau \} \quad C \{ E_2 \} \quad C \{ E_1 \} \]

6) Evaluate sensitivity/uncertainty (§7.0)

\[ \lambda \quad C \quad A_{pocket} \quad k_{salt} \quad k_{culebra} \]

As a surrogate, consequences from other scenarios may be used if they are bounding (e.g., $5 \times$ consequence of one intrusion used to bound 5 single intrusions).

Figure 8.1. A schematic representation of the six principal steps of a WIPP performance assessment.\(^1\)
8.0 Performance Assessment Algorithm Summary
8.2 Summary of Performance Assessment Software Linkages

In this report, many of the subsections that describe performance assessment (PA) code applications end with a flow diagram that depicts the software linkages used to perform that particular task of a PA. This section ends with two two-page pictoral descriptions of the entire linkage, that is, summary overviews of all the code linkages shown in all the previous figures. The figures represent the overall flow of information through the PA software and give a rough idea of the "algorithm" used to perform a PA. The first two-page figure depicts the 1991 PA process; the second two-page figure presents the 1992 PA process. As in the previous subsections, important files that pass information between software are identified. However, for the sake of clarity and relative simplicity, complete suites of all the files needed to run the codes (such as input files necessary to control the numerical solution algorithms) are not shown.

Several companion documents can be used to acquire more detailed information on executing the PA modeling system. The Users' Guide to the WIPP PA Codes (version 0.6, May 24, 1995, was available at this writing) currently being written by Simmons and Froehlich describes in step-by-step fashion all the files, procedures, and commands needed to execute the 1992 PA modeling system. It does it first for a single, fixed set of model parameters for each of the principal 1992 scenarios. It then reviews that process for sampled variables and reviews sensitivity and uncertainty codes. Also useful are the summary references on the CAMCON system 1, 2 and the user and theory manuals on all individual codes; these latter documents are presently in preparation.

References


4.2.3 Parameter Selection

- Select computational model parameters (x) consistent with manner of use in models
- Place in Secondary Data Base file with data base manager (Parameter values extracted with MATSET or PRELHS)
- Select Parameters (x) to vary (Parameter Uncertainty)
- Sample Parameters with Lalin Hypercube Sampling (LHS)

Set 1... Set nK

Parameter Selection

Culebra Groundwater Flow

Transmissivity Fields

Data Preparation

WIPP Modeling Setup (1992 PA)

TRANSLOUT-File
Plot Conditional CCDFs

CCDFCALC

NUCPLTOR

CCDFERRS

Drill Cuttings

2 Phase Fluid Flow

Source Concentration

Culebra Radionuclide Transport

Cumulative Travel Time

Result Check

Probability Modeling CCDF Construction, & Results Analysis

Biosphere Consequence Modeling
8.0 Performance Assessment Algorithm Summary
REFERENCES


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References


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Ref-8
References


References


Ref-I2


(United States District Court for the District of New Mexico) July 1, 1981. (Copy on file at the Sandia WIPP Central Files, Sandia National Laboratories, Albuquerque, NM.)


References


Acronyms and Initialisms

A/E – architect/engineering firm.
AEC – Atomic Energy Commission, the forerunner of the DOE that was formed in 1946 (August 1, 1946, 60 Stat. 755).
AG – attorney general.
AL – Albuquerque operations office, DOE.
ALARA – As low as reasonably achievable with costs and benefits taken into account; a basic principle of radiation protection.
ALGEBRA DB – An algebraic manipulation code in the support module that is capable of performing most algebraic manipulations in CAMDAT files to prepare already existing data for transfer between software in the CAMCON system.
ANL – Argonne National Laboratory; see definition.
BCSET – A code in the Property Assignment Module that assigns boundary values at nodal boundary flags and element boundary flags to rectilinear one-, two-, or three-dimensional finite different grid or finite-elements meshes, or network-type grids. The flags are defined either by the mesh generation module or by BCSET in a user input file.
BLOT CDB – A plotting code in the Support Module that plots results from all main modules directly on screen or the printer by reading the CAMDAT files.
BOAST II – A Black Oil Applied Simulation Tool for predicting, isothermal flow of three phase in porous media using an implicit/explicit solution solver (IMPESS). BOAST II was used in the 1990 PA calculations.
BRAGFLO – BRine And Gas FLOw; two- and three-dimensional code in the Repository Module for evaluating the simultaneous flow of two phases (brine + gas) through a porous heterogeneous media. BRAGFLO uses a fully implicit finite difference solution of the partial differential equation of the mathematical model.
BRWM – Board of Radioactive Waste Management, a permanent Board formed in 1968 in the National Research Council, the principal operating agency of the U.S. National Academy of Sciences (NAS).
C&C – Consultation and Cooperation agreement between State of New Mexico and the DOE.
CAMCON – Compliance Assessment Methodology CONtroller. Computational system for assessing the performance of a disposal system (usually for nuclear wastes). This complex management system provides for (1) the interfacing of individual computer codes of the WIPP PA modeling system, and (2) quality assurance.
CAMCONexec – A set of procedure files in the CAMCON system that assists the analyst in interactivity running or alternately building macros for batch submission.
CAMDAT – Compliance Assessment Methodology DATa base. Data base consisting of the collection of binary computer files created during the stochastic simulation for the WIPP.
CARD – Citizens Against Radioactive Dumping.
CCD2STEP – Software within the Statistical Module that transfers CCDFCALC releases to STEPWISE or PCCSRC.
CCDF – complementary cumulative distribution function; see definition.
CCDFCALC – A code in the Compliance Module at the CAMCON system that generates conditional CCDFs where "conditional" means the CCDF is contingent on certain events or processes occurring.

CCDFPERM – A code in the Compliance Module of the CAMCON system that builds a CCDF by permutating and summing single and double intrusion data (E1 and E1E2 scenarios) to produce the "composite" CCDF, which is the relevant measure to compare with the EPA limiting line.

CCDFPLOT – A code in the Compliance Module to plot the conditional CCDFs calculated by CCDFCALC.

CDB – computational database; see CAMDAT.

CDF – cumulative distribution function; see definition.

CEC – Commission of the European Communities.

CFR – Code of Federal Regulations. A codification of all the federal regulations in force as published in the Federal Register by the departments and agencies of the federal government.

CH-TRU waste – contact-handled Transuranic waste; see definition.

CUTTINGS – A computational model (code) that calculates the quantity of radioactive material (in curies) brought to the surface as cuttings/cavings by a drilling operation that penetrates the repository. The code determines the amount of cuttings removed from a borehole by drilling and decays radionuclides within the cuttings/cavings to the specified intrusion time.

DOE – U.S. Department of Energy: formed by DOE Organization Act (Public Law 95-91, 912 Stat 565), which replaced the Energy Research and Development Agency (ERDA). ERDA was formed by the 1974 Energy Reorganization Act (Public Law 93-438) and replaced the Atomic Energy Commission (AEC), which was formed in 1946 (August 1, 1946, 60 Stat. 755).

DOI – U.S. Department of Interior.

DOT – U.S. Department of Transportation.

EEG – Environmental Evaluation Group, formed in 1978 by New Mexico from funds provided by the DOE to conduct independent technical evaluation of the WIPP. The National Defense Authorization Act, Fiscal Year 1989, Public Law 100-456, Section 1433 assigned administrative oversight of EEG to the New Mexico Institute of Mining and Technology.

EIS – Environmental Impact Statement, environmental documentation required by federal law (NEPA) for large, federally-funded programs.

EPA – U.S. Environmental Protection Agency formed by Congress on December 2, 1970, in Reorganization Plan 3 of 1970 (5 U.S.C. 552, App.; 40 CFR 1). In this act, Congress transfers to EPA the tasks of monitoring research, setting standards, and performing enforcement activities related to pollution abatement and control that allow the environment to be considered as a single, interrelated system.

EPA of 1992 – Energy Policy Act of 1992; an act that requires the U.S. Environmental Protection Agency (EPA) to contract with the National Academy of Sciences (NAS) to recommend site-specific health-based (dose) standards to individuals for the Yucca Mountain Project and subsequent promulgation of new regulations by the EPA and revision of regulations by the Nuclear Regulatory Commission (NRC) consistent with NAS findings.

ERDA – Energy Research and Development Agency, a forerunner of the DOE that was formed in 1974 (Pub. L. 93-438).

FFCA – Federal Facility Compliance Act of 1992; an act that removed sovereign immunity for federal facilities concerning hazardous waste regulations; the act requires a listing of mixed-waste inventory at U.S. DOE facilities, and the DOE chose to include spent fuel.

FITBND – A code used in the Property Assignment Module to evaluate transmissivity fields in the 1991 PA calculations; FITBND determines relationship between heads at wells and the boundary pressures and then optimizes fit of boundary pressures. Specifically, FITBND minimizes errors
with respect to the known, steady-state freshwater heads at the wells by selecting a weighting of the boundary-condition perturbations.

**Fm** – geologic formation.

**FR** – Federal Register.

**GA** – General Atomic, Inc.

**GAC** – Governor's Advisory Committee of New Mexico.

**GARFIELD** – A code in the Property Assignment Module used to evaluate transmissivity fields in the 1991 PA calculations; used generalized kriging, which is a type of interpolation that takes account of known or assumed statistical properties of the field that is being interpolated.

**GENII-S** – A computer code used to simulate radionuclide transport in the biosphere and resultant radiation doses from internal and external exposure of the radionuclides in the air, water, or soil.

**GENMESH** – The principal software in the Mesh Generation Module that produces a right-handed, Cartesian, rectangular, one-, two-, or three-dimensional finite-element or finite-difference mesh.

**GENNET** – Software in the Mesh Generation Module that constructs simple one-, two-, and three-dimensional networks using two-node elements from a geometry specification input file.

**GENOBS** – A code within the Property Assignment Module used to evaluate transmissivity fields in the 1991 PA calculations; generated a set of linear impulse functions for selected segments along the boundary of the mesh.

**GRAPH** – Software for making simple x-y plots.

**HLW** – high level waste; see definition.

**HSWA** – Hazardous and Solid Waste Amendments of 1984 (Pub. L. 98-616) (see also RCRA).

**IAEA** – International Atomic Energy Agency located in Vienna, Austria. Formed in 1956 "to accelerate and enlarge the contribution of atomic energy to peace, health and prosperity throughout the world."

**ICRP** – International Commission on Radiological Protection, established in 1928 by Second International Congress of Radiology. Maintains special relationship with International Society of Radiology, but also has official relationships with World Health Organization and IAEA.

**ICSET** – Software in the Property Assignment Module that sets initial conditions, i.e., sets analysis array variables (history, global, nodal, and/or element variable values) in a CAMDAT file at the first time step.

**IDB** – Integrated Data Base compiled by Oak Ridge.

**INEL** – Idaho National Engineering Laboratory; see definition.

**INGRES®** – The relational data base management software that stores and retrieves model parameters necessary for the PA analysis.

**LANL** – Los Alamos National Laboratory; see definition.

**LLW** – low level waste; see definition.

**MATSET** – Software in the Property Assignment Module that sets material names to specified regions (e.g., defined by GENMESH or GENNET), sets material property values, and sets attribute values into a performance-assessment computational database, CAMDAT, file by extracting data from the SDB.
MB – marker bed; see definition.

MRS – monitored retrievable storage facility for spent fuel from commercial power reactors, proposed in 1982 in NWPA and 1987 in NWPAAA (see also RSSF).

NAS – National Academy of Sciences, is a private, nonprofit, self-perpetuating society of distinguished scholars engaged in scientific and engineering research. The Academy was chartered by Congress in 1863 with the mandate to advise the federal government on scientific and technical matters.

NEA – Nuclear Energy Agency, was established in 1958 to promote cooperation among participating countries in furthering the development of nuclear power as a safe, environmentally acceptable, and economic energy source. It is currently a division of the Organisation for Economic Co-operation and Development (OECD).

NEPA – National Environmental Policy Act of 1969, Public Law No. 91-190, 83 Stat. 852; federal law that sets environmental policy by requiring an environmental impact statement on all major federal projects.


NTS– Nevada Test Site; see definition.

NUC PLOT – Software in the Compliance Module that depicts the contribution [in activity or percentage] of each radionuclide to the EPA summed normalized release, R, as a tukey box plot.


NWPA AA – Nuclear Waste Policy Amendments Act of 1987; amendments to the Nuclear Waste Policy Act of 1982 specifying that only one repository site at Yucca Mountain was to be characterized by the DOE and placing renewed emphasis on the monitored retrievable storage option.

OECD – Organisation for Economic Co-Operation and Development, an international organization formed in 1961 and based in Paris, whose members comprise the principal industrial powers of the world. The CEC takes part in the work of OECD.

ORNL – Oak Ridge National Laboratory; see definition.

OTA – Office of Technology Assessment, U.S. Congress.

PA – performance assessment; see definition.

PANEL – The code in the Repository Module that implements the mixing cell mathematical model to evaluate the dissolution of radionuclides from the TRU waste into brine within the disposal-room.

PCCSRC – A code in the Statistical Module that evaluates variable importance at each time step by reporting the partial correlation coefficients (PCCs) and standardized regression coefficients (SRCs) on either the data or the ranks of the data.

PDF – probability density function; see definition.

PERM2PCC – Software to translate output from CCDFPERM for use by PCCSRC or STEPWISE.

POSTBRAG – Translator software for placing data from BRAGFLO into a CAMDAT file format.

POSTLHS – Software to translate output from LHS to a CAMDAT file format.

POSTSECOTP – Translator software for placing data from SECOTP2D into a CAMDAT file format.

PRA – probabilistic risk assessment; see definition.

PREBRAG – Translator software for extracting data from a CAMDAT file to generate input for BRAGFLO.

PREGENII – PA translator software that statistically characterizes radionuclide concentrations so that they are compatible with input required by GENII-S.
PRELHS – PA translator software used to extract data from the secondary data base to prepare input for LHS.

PRESECOTP2D – Translator software for extracting data from a CAMDAT file to generate input for SECOTP2D.

QA – quality assurance; see definition.

RCRA – Resource Conservation and Recovery Act of 1976 (Public Law 94-580) and, as used herein, subsequent amendments (e.g., HSWA, Hazardous and Solid Waste Amendments of 1984, Public Law 98-616). RCRA establishes a procedure to track and control hazardous wastes from time of generation to disposal. Regulations in 40 CFR Parts 260-281 implement RCRA with respect to hazardous waste and hazardous waste treatment.

RELATE – Software in the Support Module that is used to interpolate pertinent parameters from one mesh to another mesh (e.g., from the regional mesh to the local mesh).

RFP - Rocky Flats Plant; see definition.

RH-TRU waste – remotely handled TRansUranic waste; see definition.

RSSF – retrievable surface storage facility proposed in 1972 by the AEC (see also MRS).

SA – Stipulated Agreement between State of New Mexico and the DOE.

Sandia – see SNL.


SDB – secondary data base; see definition.

SECOFL2D – A code within the Groundwater Flow Module that is a fully implicit, finite difference solution of the partial differential equation based on heads. The groundwater-flow code also automates the calculation of and interaction between models of the regional and local domains.

SECOTP2D – A transport code within the Contaminant Transport Module that simulates single- or multiple-component radionuclide transport in fractured or porous aquifers. The code uses total-variation-diminishing (TVD) schemes to model the advective part of the transport equation.

SI – “Systeme Internationale d’Unites,” an international standard of measurement that is used by the scientific and engineering community.

SNF – spent nuclear fuel; see definition.

SNL – Sandia National Laboratories; see definition.

SPDV – site and preliminary design validation phase performed by Bechtel National.

SRC – standardized regression coefficient in the statistical regression model.

SRP – Savannah River Plant, see definition.

SSDMS II – Sandia Sorption Data Management System Version 2 developed to store and retrieve sorption data on chemicals.

STAFF2D – A code within the Contaminant Transport Module that calculates radionuclide transport in fractured or porous aquifers. One of several PA model-groundwater-flow codes, used in concert with various support modules that can be linked in a serial procedure using the CAMCONexec driver to analyze the WIPP disposal system.

STEPWISE – A code in the Statistical Module that evaluates variable importance by developing regression models between the input variable and the observed response using a forward, backward, or stepwise regression procedure on the rank or raw data.

SUMMARIZE – Software that accesses multiple CAMDAT files and places specified values in one file in tabular form.

SUTRA – Saturated-unsaturated TRAnsport code. A code in the Groundwater Flow Module that models saturated and unsaturated porous media liquid flow and contaminant transport using a finite-
element solution technique. SUTRANUC is a modified version of SUTRA that includes transport and decay of radionuclides.


SWRIC – Southwest Research and Information Center.

TRACKER – A code within the Support Module that tracks a neutrally buoyant particle in a fluid velocity field.

TRU – TRansUranic, all elements of the periodic table having atomic numbers greater than 92.

T,R,U,P,A,C,T – cask TRansUranic Package Transpoter; the transportation container for trucking TRU waste to the WIPP; TRUPACT II (current design) has space for two seven-pack units of 55 gallon waste drums or two standard waste boxes.

UNDERDOG – Underground Nuclear Depository Evaluation, Reduction, and Detailed Output Generator developed for data reduction (i.e., reducing raw data [e.g., voltage readings] to meaningful engineering units [e.g., temperature]).

UNSWIFT – Converts material property data from an input file for SWIFT II into a CAMDAT file format.


VOC – Volatile Organic Compounds, such as solvents used for cleaning.

WIPP – Waste Isolation Pilot Plant; a full-scale research and development repository for transuranic wastes near Carlsbad, NM; authorized in 1979 (Pub. L. 96-164) for the management, storage, and eventual disposal of waste generated by DOE defense programs that is contaminated with transuranic radionuclides and some RCRA hazardous chemicals.


WISDAAM – WIPP In Situ Data Acquisition, Analysis, and Management system developed to group tasks associated with processing experimental data.

WP – waste parcel; see definition.

WPIO – WIPP Project Integration Office, formed in 1989, forerunner of CAO.

WPO – WIPP Project office, forerunner of CAO.

WTWBIR – WIPP Transuranic Waste Baseline Inventory Report compiled by National TRU Program Office of the DOE, Carlsbad, NM.

10 CFR 60 – Code of Federal Regulations, Title 10, Part 60, Licensing Requirements for Land Disposal of Radioactive Waste. This NRC regulation does not apply to the WIPP, but contains terms and concepts frequently used by the scientific community when discussing nuclear waste management.


40 CFR 268 – Code of Federal Regulations, Title 40, Part 268, Land Disposal Restrictions. A portion of the regulations implementing RCRA. This part restricts the land disposal of all hazardous wastes before strict treatment standards are met or a no-migration variance petition is approved.
Definitions

accessible environment — "... (1) the atmosphere, (2) land surfaces, (3) surface water, (4) oceans, and (5) all of the lithosphere that is beyond the controlled area." (40 CFR 191.12[k]); the overall performance of the disposal system is calculated at the contact of disposal with accessible environment.

actinide — The series of elements beginning with actinium, atomic number 89, and continuing through lawrencium, atomic number 103; all are radioactive.

activation — The process of making a material radioactive by bombardment with neutrons, protons, or other nuclear radiation (also called induced radioactivity).

activity — See radioactivity.

aleatoric parameters — Parameters in the parameter space of the conceptual model for which sufficient knowledge is unobtainable such that they are treated as chance occurrences of features, events, and processes. These parameters may be conveniently used to form scenarios related to chance.

alpha particle (α) — A type of radiation; positively charged particle (identical to a helium nucleus—two protons and two neutrons) ejected spontaneously from the nuclei of some radionuclides.

alpha-bearing waste — See transuranic waste.

alternative conceptual models — Multiple working sets of hypotheses and assumptions of a system that are all scientifically acceptable (i.e., consistent with the purpose of the model, logically complementary to one another, in agreement with existing facts and observed data, and able to be tested).

alternative models — Alternatives in model form that may exist at each stage of model development. Alternatives at the first stage of model development (alternative conceptual models) are often of the most concern.

ameriium (Am) — A TRU radionuclide having an atomic number of 95, containing 95 electrons and 95 protons. $^{241}\text{Am}$ (half-life of 432.7 yr) results from the decay of $^{241}\text{Pu}$ (half-life of 14.4 yr). Waste initially containing $^{241}\text{Pu}$ will therefore eventually contain $^{241}\text{Am}$ for several decades as the $^{241}\text{Pu}$ decays.

analysis — Analysis is the rational investigation of a natural or artificial phenomenon to discover principles that underlie the phenomenon. More formally, analysis is the five-step process of (1) defining (developing hypothesis and planning), (2) investigating, (3) validating, (4) reviewing, and (5) documenting the study of a system. This rational study often involves "teasing" the system "apart," i.e., dividing the whole system into simpler components to gain understanding. However, it may also involve synthesis, i.e., the bringing together of diverse facts to comprehend the whole system. Consequently, analysis is at the heart of the method of scientific discovery and explanation. (See engineering analysis.)

anhydrite — A mineral consisting of anhydrous calcium sulfate ($\text{CaSO}_4$). It is gypsum without water, and is denser, harder, and less soluble.

anoxic — Without oxygen.

applied model — The analyst's application of the generic computational model to a particular system, using appropriate values for dimensions of the system components, parameters, and boundary and initial conditions. In a waste management, the system is a waste disposal site, and so this model is also referred to as a site-specific model.

Argonne National Laboratory (ANL) — A national laboratory in Argonne, IL; some TRU waste destined for the WIPP is stored on site.

Assurance Requirements — Qualitative requirements in Subpart B of 40 CFR 191 (§191.14) that specify actions and procedures to increase confidence that the probabilistic release limits in the Containment Requirements (§191.13) will be met.

backfill — Material used to fill the shafts, access drifts, and other excavated openings. Special types of backfill include concrete and bentonite clay plugs for sealing (seals) and possibly any backfill around the waste parcel (backfill-buffer).
**backfill-buffer** – The earthen backfill between the waste parcel and host rock; because some emplacement designs envision using the backfill material to moderate (or buffer) the release of contaminants to the host rock (e.g., bentonite clay in a granite repository), this backfill is also referred to as “backfill-buffer.” The term "backfill-buffer" is used in this report even when the crushed-salt backfill around the waste parcel is discussed, although it does not technically provide a moderating function. The term "buffer" is also frequently found in the literature but is not used here to avoid confusion with the many other uses of the term (e.g., in chemistry, a solution containing a weak acid and conjugate base that resists changes in pH).

**barrier** – As defined in 40 CFR 191, a barrier "means any material or structure that prevents or substantially delays movement of water or radionuclides toward the accessible environment. For example, a barrier may be a geologic structure, a canister, a waste form with physical and chemical characteristics that significantly decrease the mobility of radionuclides, or a material placed over and around water, provided that the material or structure substantially delays movement of water or radionuclides" (Section 191.12).

**becquerel** – SI unit of radioactivity equal to one transformation per second (see also curie).

**Bell Canyon Formation** – A sequence of rock strata that form the topmost formation of the Delaware Mountain Group. The Bell Canyon Formation lies below the Castile Formation.

**bentonite** – A common term applied to clay containing montmorillonite (smectite) as the predominate mineral.

**beta particle (β)** – A type of radiation; a charged (positive or negative) particle emitted from the nuclei of some radionuclides during radioactive decay. A negatively charged beta particle is identical to an electron; a positively charged beta particle is a positron.

**biosphere** – Portion of the earth and atmosphere occupied by living organisms.

**borehole** – A hole drilled from the surface for purposes of geologic or hydrologic testing, or to explore for resources. Sometimes referred to as a drillhole.

**brine reservoir** – Pressurized brine of unknown origin but of limited extent contained in fractured anhydrite within the Castile Formation (also frequently referred to as a brine pocket). Although a portion of the WIPP waste panels are assumed to have brine pockets beneath them, the pockets are only of concern for human intrusion scenarios where exploratory boreholes penetrate a waste panel and then continue down to the Castile Formation.

**buffer** – See backfill-buffer.

**californium (Cf)** – A TRU element having an atomic number 98 (the number of protons in the nucleus). An alpha emitter (half-life of 2.64 yr), 252Cf also spontaneously fissions, thus making it desirable as a neutron source. 252Cf is created by neutron bombardment of 244Cm targets. Oak Ridge is the only production agency for Cf. As a result, Oak Ridge is the only major generator of TRU waste showing finite quantities of this element.

**Castile Formation** – A formation of evaporite rocks (interbedded halite and anhydrite) of Permian age that immediately underlies the Salado Formation.

**cavings** – Particulates brought to the ground surface in the drilling fluid of a rotary drill from erosion of the borehole wall by the circulating drilling fluid.

".CDB" files – computational data base files. All .CDB files have the same format, and any number of codes can write to a .CDB file. The intermediate results of all computer codes pass through the same evolving .CDB file for each Monte Carlo simulation.

**code** – Software, but usually implying scientific/engineering software that groups together several different computational models.

**complementary cumulative distribution function (CCDF)** – One minus the cumulative distribution function (CDF). It is the graphical representation of the probability (P) of any consequence value R exceeding a specified consequence value \( P(R > R) \). For the Containment Requirements in 40 CFR 191, the consequence value R is the sum of the radionuclide releases (normalized by the EPA release limits) accumulated over 10,000 years.
computational model – The solution and implementation of the mathematical model. The solution may be either analytical, numerical, or empirical (where an empirical solution uses observed data directly by means of lookup tables and/or interpolation on statistical relationships). Conceivably, the implementation may be evaluated either by hand or on a computer. However, because the latter is more frequent, computational model is often synonymous with computer model. The computational model is generic until system-specific data are used. The computational models are the heart of the PA analysis and selected and/or designed by PA analysts to simulate the features, events, and processes of the WIPP disposal system.

computational scenario – A member of a class or subset of the parameter space that is obtained by further subdividing the summary scenario subspace Sj.

conceptual model – The set of hypotheses and assumptions that postulates the description and behavior of a system. To be scientifically acceptable, the set of hypotheses must be (1) consistent with the purpose of the model, (2) logically consistent with one another, (3) in agreement with existing information and observed data, and (4) able to be tested (i.e., capable of being falsified by the collection of more observed data). At a minimum, these hypotheses and assumptions describe the following about the system, including whether time dependent: (1) the simplified physical arrangement of system components, (2) the initial and boundary condition types, and (3) the nature of the relevant chemical, physical, cultural, or biological phenomena.

consequence – Result or effect on the disposal system from the consequence model. Conceptual and mathematical models are used to estimate consequences of feature events and/or processes.

consequence model – A "complete" (or "total system") consequence model, C, for the WIPP disposal system predicts a "consequence," C[x, S(x)], for each value of the scenario, Sj, and each value of the model parameter space x.

contact-handled transuranic (CH-TRU) waste – Packaged TRU waste whose external surface dose rate does not exceed 200 mrem per hour (see also dose).

Containment Requirements – Requirements in Subpart B of 40 CFR 191 (§191.13) that set probabilistic limits on cumulative releases of radionuclides beyond the "controlled area" (defined in the regulation as a surface location that encompasses no more than 100 km² and extends horizontally no more than a 5-km radius from the outer boundary of a radioactive-waste disposal system, plus the underlying subsurface [§191.12(g)]) for 10,000 years.

controlled area – As defined in 40 CFR 191, Subpart B, "(1) a surface location, to be identified by passive institutional controls, that encompasses no more than 100 km² and extends horizontally no more than 5-km in any direction from the outer boundary of the original location of the radioactive wastes in a disposal system; and (2) the subsurface underlying such a surface location" (Section 191.12).

criticality (nuclear) – A self-sustaining nuclear chain reaction from sufficient mass of a fissile material.

Culebra Dolomite – The lower of two dolomite strata of the Rustler Formation that ranges in thickness from 3 to 14 m (10 to 46 ft) in the regional modeling domain; the strata contains a brine aquifer that could provide a pathway for lateral transport of radionuclides to the accessible environment.

cumulative distribution function (CDF) – The integral of a probability density function (PDF) over those values of a random variable that are less than or equal to a specified value, R. It represents the probability that an outcome of R or less will occur.

curie – A curie is the unit describing the intensity of radioactivity of a material sample. A curie equals 3.7 x 10¹⁰ nuclear transformations per second or 3.7 x 10¹⁰ becquerel.

curium (Cm) – A TRU element having an atomic number of 96 (the number of protons in the nucleus). An alpha emitter (half-life of 18.1 yr), ²⁴⁴Cm is used for neutron bombardment of targets for the production of ²⁵²Cf at Oak Ridge. In spite of its half-life being less than 20 years, Oak Ridge considers and handles ²⁴⁴Cm as a TRU element. Some TRU waste at both Oak Ridge and Savannah River contains ²⁴⁴Cm.

cuttings – See drill cuttings.
data – Information that is purposely collected, organized, and used in preparing values for parameters of computational models in an analysis or used as the basis of a decision. As used here, data is a subset of general information.

decision parameters – Also known as value parameters; represent various alternatives that are of high interest to decision makers.

defense waste – Nuclear waste derived mostly from the manufacture of nuclear weapons, weapons-related research programs, the operation of naval propulsion reactors, and the decontamination of production facilities.

Delaware Basin – The part of the Permian Basin in southeastern New Mexico and adjacent parts of Texas where a sea deposited large thicknesses of evaporites some 200 million years ago. It is partially surrounded by the Capitan Reef.

deterministic simulations – Modeling simulations that use an exact mathematical relationship with one to one corresponding between a set of fixed dependent parameters for features, events, and processes and the independent results.

Dewey Lake Red Beds – A formation of the Permian Period that overlies the Rustler Formation and is composed of reddish brown marine mudstones and siltstones interbedded with fine grained sandstone.

disposal – Emplacement of waste in a manner that assures isolation from the biosphere for the foreseeable future with no intent of retrieval and that requires deliberate action to regain access to the waste. For example, disposal of wastes in a mined geologic repository occurs when all of the shafts to the repository area are backfilled and sealed.

disposal system – Any combination of engineered and natural barriers that isolate spent nuclear fuel or radioactive waste after disposal (40 CFR 191.12(a)). The natural barriers extend to the accessible environment.

disturbed (human-intrusion) performance – Performance of the disposal system when human intrusion—e.g., through inadvertent drilling for oil or gas—penetrates the system, creating pathways for radionuclide release.

dose – The quantity of radiation absorbed accounting for biologic effect, measured in sieverts (Sv) or rem.

drift or access drift – Approximately horizontal underground excavated passageway from the shaft(s) to the mined panels and room(s).

drill cuttings – Particulates brought to the surface in the drilling fluid of a rotary drill either from directly cutting through a material with the drill bit or from erosion of the borehole wall by the circulating drilling fluid.

dual permeability mathematical model – A discrete hierarchical model consisting of two continuum, a fracture system and matrix system, that are fully coupled in properties such as pressures of modeled phases, temperatures, and velocities.

dual porosity mathematical model – A special case of the dual permeability mathematical model where the permeability of the matrix is assumed to be zero, such that fluid flow can occur only within the fractures of the two continuaums. Only diffusion, not flow advection, can occur in the matrix and is orthogonal to the fractures. This mathematical model is implemented in STAFF2D and SECOTD2D.

E1 – An event used to develop scenarios: intrusion of a borehole through a disposal panel into a pressurized brine reservoir in the Castile Formation, or a simplified notation for a scenario in which event E1 occurs and other events do not (TS', E1, E2').

E1E2 – A scenario: intrusion of a borehole through a disposal panel into a pressurized brine reservoir in the Castile Formation (E1) and another intrusion of a borehole into the same panel (E2), without the occurrence of other events. Simplified notation for scenario TS', E1, E2, E3'.

E2 – An event: intrusion of a borehole into a disposal panel, or a simplified notation for a scenario in which event E2 occurs and other events do not (TS', E1', E2).
Eh – The redox potential; a measure of the oxidizing or reducing tendency of a solution and defined by
the Nernst equation for a half-reaction written as a reduction reaction in comparison to the standard
hydrogen reaction, \( E_{\text{H}} = E^\circ_{\text{H}} + \frac{RT}{nF} \ln \left( \frac{[\text{oxidized species}]}{[\text{reduced species}]} \right) \).

engineered barrier – Human-designed (engineered) barriers of the waste disposal system. This
definition, which is used herein and in 40 CFR 191, includes shafts, boreholes, and their seals. Note
that the 10 CFR 60 definition is narrower and omits shafts, boreholes and their seals in its definition.

engineering analysis – An engineering analysis is similar to a general scientific analysis except that
engineering analysis (1) has formal constraints on purposes (specifications) rather than the limits of
human curiosity, (2) has formal constraints on resources (time and money) rather than the limits of
human energy, (3) uses fairly accepted methods rather than novel approaches, and (4) seeks to clarify
rather than to discover new knowledge (i.e., the study is likely to further understanding of a system
through the application of already discovered knowledge). The term "engineering analysis" applies to
the WIPP disposal system provided one understands the formal constraint on the analysis purpose,
which is an analysis that is intended to investigate the entire system for the primary purpose of
determining compliance with environmental regulations. (See analysis.)

EPA limiting line – The set of lines in space of complementary cumulative distribution function (CCDF)
that connect the two limiting points specified in the Containment Requirements (Section 13) of 40
CFR 191. According to the guidance of Appendix C of 40 CFR 191, the EPA can consider a disposal
system to be in compliance if the CCDF (predicted by the appropriate probability and consequence
models) meets or is less than the two limiting points.

EPA release limits – The normalizing factors for various radionuclides listed in Table 1 of Appendix A
of the EPA regulation, 40 CFR 191.

epipenetic parameters – Parameters related to precision of knowledge in the parameter space of the
conceptual model for which some information has been obtained.

evaporate – A sedimentary rock composed primarily of minerals produced by precipitation from a
solution that has become concentrated by the evaporation of a solvent, especially salts deposited from
a restricted or enclosed body of sea water or from the water of a salt lake. In addition to halite
(\( NaCl \)), these salts include potassium, calcium, and magnesium chlorides and sulfates.

event – A natural or anthropogenic phenomenon that occurs either instantaneously or over a small
portion of the time frame of interest.

event tree – The result of an inductive probabilistic technique that starts with hypothesizing the
occurrence of basic initiating events and proceeds through their logical propagation to a change in
(and possible disruption of) the system (e.g., a nuclear disposal system).

feature – An object or condition of the disposal system that influences release of contaminants.

gamma ray (\( \gamma \)) – A type of electromagnetic radiation of high energy and short wavelength that originates
from within the nucleus of the atom. Gamma radiation can accompany some alpha and beta
emissions in radioactive decay and always accompanies fission of nuclei.

gas production – Three gas generation processes are expected to be factors in the degradation of TRU
wastes in the WIPP repository. The generation of gaseous species is expected to occur through
chemical (i.e., corrosion), microbial, and radiolytic processes.

general environment – Used in 40 CFR 191, Subpart A, as the "total terrestrial, atmospheric, and aquatic
environments outside sites within which any activity, operation, or process associated with the
management and storage of ... radioactive waste is conducted" (Section 191.02).

geologic barrier – A barrier within the geologic portion of the disposal system (see also barrier).

geologic repository – A system intended to be used for disposal of radioactive waste in excavated
geologic media. A geologic repository includes (1) the operations area, including both surface and
subsurface area, where waste handling occurs, and (2) the geologic setting, i.e., the geologic,
hydrologic, and geochemical systems that isolate radioactive waste (10 CFR 60).
**Groundwater Protection Requirements** – Requirements in Subpart C of 40 CFR 191 that set limits on radioactive contamination of certain sources of groundwater within or near the controlled area for 10,000 years after disposal.

**half-life, radioactive** – The time required for half the atoms of a radioactive substance to decay (see also radioactivity).

**halite** – Crystalline sodium chloride, also known as common rock salt.

**handling container** – The container placed around the waste form for handling prior to disposal preparation or disposal itself. At the WIPP, a handling container is the sole container for storage and disposal.

**Hanford** – Hanford Reservation, Hanford Engineering Development Laboratory, and Pacific Northwest Laboratory, Richland, WA. Site N-reactor for plutonium production and numerous storage tanks for radioactive waste. A large volume of TRU waste is destined for the WIPP.

**hazardous waste** – Those wastes that are designated hazardous by the EPA (or state) regulations through the RCRA.

**head** – The hydraulic head of the fluid potential (Φ) of the system divided by the acceleration of gravity (g); the hydraulic head (h) is the sum of the elevation of the point (z) in the fluid system (elevation head) and the pressure head \( \left( \frac{P}{\rho g} \right) \) (pressure divided by the fluid density and g); \( h = \frac{P}{\rho g} + z \).

**heavy metal** – All uranium, plutonium, and thorium placed into a human-engineered nuclear reactor.

**high level (radioactive) waste (HLW)** – "...the highly radioactive material [fission products and some actinides] resulting from the reprocessing of spent nuclear fuel, including liquid waste produced directly in reprocessing and any solid material derived from such liquid waste that contains fission products in sufficient concentrations ..." (NWPA, 1982, §2[12]). Although not used in this manner in this report, general articles regarding radioactive waste use the term high level waste to imply any combination of spent nuclear fuel and HLW (and sometimes transuranic [TRU] waste) that requires disposal in a deep, geologic repository. 10 CFR 60, which was promulgated by the NRC prior to NWPA, also includes spent nuclear fuel in its definition of high level waste.

**Holocene Age** – The more recent of the two epochs of the Quaternary geologic period, extending from the end of the Pleistocene to the present.

**hydraulic conductivity (K)** – The constant of proportionality in Darcy's law of flow through porous media.

**Idaho National Engineering Laboratory (INEL)** – A multiprogram laboratory in Idaho Falls, Idaho, furnishing engineering services and products on primarily nuclear energy and related technologies. The Idaho Chemical Processing Plant (ICPP) at the Idaho site processes highly enriched uranium fuel from spent nuclear fuel stored at the site. In addition to receiving spent nuclear fuel from throughout the DOE defense complex, it stores a large volume TRU waste from Rocky Flats destined for WIPP. Prior to 1970, it buried this TRU waste, but now stores it on the surface.

**implementing agency** – The NRC for facilities licensed by the NRC, the EPA for those implementation responsibilities given to the EPA by the Waste Isolation Pilot Plant Land Withdrawal Act, and the Department of Energy for any other disposal facility and for implementation responsibilities for the WIPP not given to the EPA.

**index parameters** – Parameters that represent choices for various model forms.

**Individual Protection Requirements** – Requirements in Subpart B of 40 CFR 191 (§191.15) that set limits on radiation doses to members of the public in the accessible environment (the environment beyond the controlled area [§191.12(k)]) for 10,000 years of undisturbed performance.

**information** – A collection of cognitive or intellectual material. Information includes both observational data and communicated knowledge derived by inference and interpretation.
isomorphism - A one-to-one correspondence through algebraic manipulation between the elements of two mathematical spaces such that the result of a mathematical operation in one space corresponds to analogous operation on the corresponding elements of the other space.

isotope - A species of atom characterized by the number of protons and the number of neutrons in its nucleus. In most instances, an element can exist as any of several isotopes, differing in the number of neutrons, but not the number of protons, in their nuclei. Isotopes can be either stable isotopes or radioactive isotopes (also called radioisotopes or radionuclides).

Latin hypercube sampling (LHS) - A Monte Carlo sampling technique that divides the cumulative distribution function into intervals of equal probability and then samples from each interval to ensure coverage of the full range of each variable with fewer samples.

Lawrence Livermore National Laboratory (LLNL) - A multiprogram laboratory in Livermore, CA, conducting research and development on all facets of nuclear weapon design and basic research in a variety of areas. Some TRU waste stored on site is destined for the WIPP.

Los Alamos National Laboratory (LANL) - A multiprogram laboratory in Los Alamos, NM, conducting research and development on all facets of nuclear weapon design and basic research in a variety of areas. A large volume TRU waste stored on site is destined for the WIPP.

low level waste (LLW) - All radioactive waste other than spent nuclear fuel, high level waste, transuranic waste, and mill tailings. (Mill tailings are the residue from the physical and chemical processing of uranium ore to obtain uranium.) In the United States, LLW is divided into three categories: A, B, and C. Category A has the lowest activity, and Category C has the highest. Some countries create a category called "Intermediate Level Waste (ILW)" by grouping together the United States Category C LLW, which requires shielding during handling, and transuranic waste.

marker bed - A unit of strata within a formation or a member of a formation that can be mapped in a particular area of interest.

mathematical model - The mathematical representation of a conceptual model. That is, the algebraic, differential, or integral equations that predict quantities of interest of a system and any constitutive equations of the physical material that appropriately approximate system phenomena in a specified domain of the conceptual model. Mathematical models can be categorized as either deterministic or stochastic models.

MB139 - An anhydrite marker bed and one of about 45 interbed units within the Salado Formation. It is about 1-m thick and about 1-m below the floor of the repository.

mesh - A subdivision of the domain of some mathematical model into cells, blocks, or elements for purposes of numerical solution.

metric tons of heavy metal (MTHM) - metric tons (1000 kg) of heavy metal (all isotopes of uranium, plutonium, and thorium) before placed into a reactor; the measurement is for initial mass.

mixed waste - waste that contains both radioactive and hazardous components as defined by the Atomic Energy Act and the RCRA in 40 CFR Parts 263, 265, 268, and 270.

model constants - Precisely known values for the intended purposes of the analysis.

model form uncertainty - Uncertainty in the most appropriate model form for a system. The uncertainty results from sparse observed data and lack of information able to corroborate or refute alternative models. Developing alternative models is a way to explicitly acknowledge model form uncertainty; however, in some cases it may be appropriate to combine the alternative models into a megamodel and represent the model form uncertainty as uncertainty in an index parameter.

model-control parameters - Parameters used to control the numerical solution of the mathematical model.

model-domain parameters - Parameters that reflect the overall size and appropriate temporal and spatial mesh used in discretizing a problem for numerical solution of the mathematical model.

module - A grouping or category of codes in the CAMCON system; the module name describes the primary function provided in the performance assessment.
Monte Carlo method - A technique that obtains a probabilistic approximation to the solution of a problem by using statistical sampling techniques and usually computer simulation. For the WIPP PA, the method is used to evaluate the distribution of the consequence results and thereby approximate the uncertainty in the results. Specifically, the Monte Carlo method of random sampling is used to integrate the multidimensional differential equations expressing the expectation of the results (i.e., to evaluate the distribution of the consequence results and thereby approximate the uncertainty in the results).

montmorillonite - A soft clayey mineral that is a hydrous aluminum silicate with considerable capacity for exchanging part of the aluminum for magnesium and bases.

Mound Laboratory - A laboratory located in Miamisburg, OH; some TRU waste destined for the WIPP is stored on site.

natural barrier – see geologic barrier.

neutron - An elementary particle that has approximately the same mass as the proton but lacks electric charge, and is a constituent of all nuclei having mass number greater than 1.

Nevada Test Site (NTS) – Located in Nevada to field test nuclear components and weapons. Some TRU waste that is destined for the WIPP is stored at this site.

No-Migration Variance Petition (NMVP) – Section 3004 of RCRA allows the EPA to grant a variance from the land disposal restrictions when a determination can be made that, to a reasonable degree of certainty, there will be no migration of hazardous constituents from the disposal unit for as long as the waste remains hazardous. Specific requirements for making this demonstration are found in 40 CFR 268.6, and the EPA has published a draft guidance document to assist petitioners in preparing a variance request.

nuclear fuel – Fuel containing sufficient fissionable material (material able to split after the sorption or capture of a neutron) to maintain critical conditions in a nuclear reactor.

Oak Ridge National Laboratory (ORNL) – Y-12 Plant, Oak Ridge Reservation, Oak Ridge, TN. A large volume of TRU waste in storage is destined for the WIPP.

panel – A grouping of pillars and rooms.

parameter uncertainty – Uncertainty in the most appropriate parameter value for a computational model. The uncertainty results from sparse observed data and lack of information able to corroborate or refute alternative parameter values. Developing distributions of the parameter values is a way to explicitly acknowledge parameter uncertainty and is a part of probability modeling.

parameters – The underlying elements \( \{x = x_1, \ldots, x_n, \ldots, x_{nv}\} \) of a computational model. As \( x \) changes, so does the model result. The individual parameters, \( x_n \), may be vectors, tensors, higher order quantities, or even functions, but are usually scalar quantities. Furthermore, the individual parameters are usually coefficients of the mathematical model, but they may also relate to scenario uncertainty or model form uncertainty.

percolation – The movement of liquid (usually water) through unsaturated or saturated solid and rock. This flux is directly controlled by the permeability of the medium.

performance assessment (PA) – The process of assessing whether a system meets a set of performance criteria. For the WIPP PA, the process is a stochastic simulation. The system is a deep geologic repository disposal system (in salt) for DOE TRU waste. The performance criteria are various long-term environmental metrics in U.S. government regulations (not short-term operational safety issues).

permeability \( (k) \) – A measurement of the ability of a rock or soil to transmit fluid under hydraulic gradient. It is the hydraulic conductivity divided by the fluid unit weight \( (\gamma) \), density times acceleration due to gravity \( (\gamma g) \) times the fluid dynamic viscosity \( (\mu) \); \( k = \mu / \gamma g \).

Permian Basin – A region in the south-central United States, where during the Permian period (248 to 286 million years ago), there were many shallow sub-basins in which vast beds of marine evaporities were deposited.

Permian Period – The last of the seven periods (~248 to ~286 million years ago) of the Paleozoic Era.
**pH** - A measure of the proton activity of a solution and equal to the negative logarithm of concentration of hydrogen ions in a solution, $\text{pH} = -\log(c_{H^+})$.

**pillar** - A block of rock left intact to support the strata overlying the underground excavations.

**Pleistocene Age** - The earlier of two epochs of the Quaternary geologic period, characterized by the alternative appearance and recession of northern glaciation and the appearance of the progenitors of humans; climatic changes during this period are used as an analog in estimating future climatic extremes for the WIPP.

**plutonium (Pu)** - A radionuclide having an atomic number of 94. Pu isotopes exist in some TRU waste at all 10 of the major DOE storage facilities. The significant isotopes that may exist in measurable quantities at these facilities are $^{238}$Pu through $^{242}$Pu. Each isotope is an alpha emitter; the respective half-lives are: $^{238}t_{1/2} = 87.7 \text{ yr}$; $^{239}t_{1/2} = 24,000 \text{ yr}$; $^{240}t_{1/2} = 6563 \text{ yr}$; $^{241}t_{1/2} = 14.4 \text{ yr}$; $^{242}t_{1/2} = 376,000 \text{ yr}$. Because of its high activity, $^{239}$Pu can contribute significantly to the thermal loading on some TRU waste. $^{241}$Pu decays, primarily by beta emission, to $^{241}$Am.

**Poisson distribution** - A discrete analytic probability distribution function (PDF) that adequately describes many random processes that involve events taking place over time.

**polyhalite** - An evaporite mineral: $K_2MgCa_2(SO_4)_4 \cdot 2H_2O$, a hard, poorly soluble mineral.

**potash** – Specifically $K_2CO_3$. Also loosely used for many potassium compounds, especially as used in agriculture or industry.

**primary data base** – The data base storing the raw measured or interpreted data that is under the control of the experimentalist.

**probabilistic risk assessment (PRA)** – The process of assessing, through a stochastic simulation, the risks from a system. In theory, a PRA is identical to a performance assessment (PA) in the United States. In practice, the two differ because a PRA usually connotes (a) a system composed solely of human-engineered components, and (b) performance criteria that include risk to health over a short time (e.g., human lifetime) relative to geologic time. A PA usually connotes a system composed of both natural and human-engineered components over geologic time. Because the time frame is different, many phenomena for a PRA can be termed events (short-term phenomena); because the components are all human engineered, measured failure rates of components are often available. The modeling tools in a PRA can include elaborate event and fault trees and can substitute empirical data for mechanistic models. For a PA, the event trees are simpler, fault trees are not used, and mechanistic models are used directly.

**probability density function (PDF)** – If an event depends on a random variable, $x$, and $P(x)$ is its PDF, then $P(x)dx$ represents the probability that the event will occur for values of the random variable between $x$ and $x + dx$. The integral of the PDF from 0 to $R$ represents the probability of occurrence for values of $x$ less than or equal to $R$. The integral of the PDF from 0 to 1 is unity.

**process** – A physical natural or anthropogenic phenomenon that occurs continuously or over a significant portion of the time frame of interest, in other words, a "long-term" phenomenon.

**quality assurance (QA)** – All those planned and systemic actions necessary to provide adequate confidence that a structure, system, or component will perform satisfactorily in service. Quality assurance for a product is ensuring that the product does what it is supposed to do to meet the specifications of the customer. The customer expectation, as related to a performance assessment, is that the analysis results present an adequate view of the WIPP performance based on currently available data and information.

**radioactive decay** – A process whereby the nucleus of an atom spontaneously emits excess energy by emitting particles (alpha, beta, or neutrons).

**radioactivity** – The spontaneous emission of alpha or beta particles and/or gamma rays, or emission of x-rays following capture of an orbiting electron from the nucleus of an unstable isotope. Measured as disintegration (decay) of radionuclie per unit time (e.g., 1 disintegration per second is 1 becquerel (Bq); $3.7 \times 10^{10}$ disintegrations per second is one curie ($Ci$)).

**radionuclide** – An isotope having an unstable nucleus and thus subject to radioactive decay.
recharge – Movement of water (usually precipitation) at the surface into soil and rock through infiltration and then percolation flow of liquid through soil and rock to an aquifer to replenish it.

rem – Acronym for roentgen equivalent man; a unit of dosage to measure amount of damage to tissue from ionizing radiation (see sievert and dose).

remotely handled transuranic (RH-TRU) waste – Packaged TRU waste whose external surface dose rate exceeds 200 mrem per hour, but not greater than 1000 rem per hour (see also dose).

repository – The portion of a waste disposal facility that includes the waste panels, access drifts, and access shafts. The term "repository" does not include either the aboveground facilities or the undisturbed host rock. (Note that this term differs from the definition in 10 CFR 60 for "geologic repository," which is described as the disposal system and the current surface facilities.)

risk – Risk is the measure of some unwanted outcome from an activity or use of technology. Risk is commonly quantified as the product of the probability of occurrence of an event and a measure of the consequence of that event. Because analysts prefer to see the elements of this product as well as the product itself, PDFs, CDFs, and CCDFs are commonly used to represent risk.

Rocky Flats Plant (RFP) - plant in Golden, CO, that originally fabricated and assembled fission triggers in nuclear weapons. A large volume of TRU waste was sent to the Idaho Lab, but a large volume is still stored on site.

room – An excavated cavity underground for disposal of waste; in the WIPP, a room is 16-m wide and 4-m high.

Rustler Formation - A sequence of upper Permian age clastic and evaporite sedimentary rocks that contains two dolomite beds, and overlies the Salado Formation. The dolomite bed of primary interest is called the Culebra Member of the Rustler Formation.

safe (disposal system) – The acceptable risk to a society posed by an activity or use of technology.

Salado Formation – A bedded salt deposit composed primarily of halite that is the host medium for the WIPP repository.

salt – In this report, salt refers to evaporite deposits that are predominantly sodium chloride (NaCl). Mineralogic names such as halite (NaCl), sylvite (KCl), gypsum (CaSO•H2O), and anhydrite (CaSO4) are used when referring to specific evaporite minerals. The term evaporite includes all of the above minerals; evaporites are formed by the evaporation of a saline solution such as sea water.

Sandia National Laboratories (SNL) – A multiprogram laboratory located in Albuquerque, NM, and Livermore, CA. SNL is operated and managed for the DOE by the Sandia Corporation. From 1949 until October 1993, Sandia Corporation was a wholly owned subsidiary of AT&T. Sandia Corporation is currently a wholly owned subsidiary of Lockheed-Martin Corp.

Savannah River Plant (SRP) – Laboratory Production Reactors Defense Waste Processing Facility, located southeast of Augusta, Georgia. A large volume of TRU waste produced and stored on site is destined for the WIPP.

scenario – The subset of all features, events, and processes considered for incorporating in the conceptual model of the disposal system. Once a mathematical model of the disposal system has been developed, the term scenario can be more precisely defined in relationship to the parameter space of the mathematical model, i.e., a scenario is a subset of the parameter space defined as a compound statement, \( A(\mathbf{x}) \), that is built by linking with the conjunction "and" any series of simple statements about values taken by elements of the parameter space, \( \mathbf{x} \), and/or the set of consequences, \( R \).

scenario development – The identification and selection of features, events, and processes, as well as the incorporation of those components into the conceptual model. The inclusion of conceptual model development acknowledges the close relationship between modeling and scenario generation and the need to have close communication between individuals performing these two tasks.

scenario identification – A necessary step in the construction of any model of a natural or engineered system in which the physical, chemical, and anthropogenic phenomena that might play a significant role in determining the performance of the system are identified.
**scenario screening** – A necessary step in the construction of any model of a natural or engineered system in which a subset of the phenomena identified through scenario identification is selected for incorporation into a mathematical model of the system.

**scenario uncertainty** – Uncertainty in the most appropriate scenarios for a system. The uncertainty results from omission of discrete, short-term, natural, or anthropogenic phenomena (events), continuous natural or anthropogenic phenomena (processes), and objects and conditions (features) of a system (completeness errors) and the imperfect aggregation of histories of a system (aggregation errors).

**scientific/engineering software** – Software that models a physical process, often by the numerical solution of mathematical equations. Software that is used to establish the spatial variation of modeling parameters is also scientific/engineering software. A significant distinction of scientific/engineering software from other software used in performance assessment is that validating the software is often subjective, difficult, and sometimes impossible.

**seals** – Portions of the backfill emplaced at several locations within the shafts and drifts that would be specially prepared from preconsolidated salt with concrete plugs; would serve to protect the ordinary backfill from fluids (gases or liquids). These plugs would likely hasten backfill consolidation and increase the likelihood that salt backfill would rapidly (<100 yr) assume properties near to those of the surrounding host rock.

**secondary data base (SDB)** – Data base of interpreted data from the Primary Data Base for use as parameters for the PA simulation models. The information is stored in tabular format within a relational data base system, under the control of the PA Department.

**seiche** – An oscillation of the surface of a lake or landlocked sea that varies in period from a few minutes to several hours.

**sensitivity analysis** – An analytic or numerical technique for examining the effects of parameters being varied in a model; specifically, an analysis of the effects that parameter changes have on model predictions.

**shaft** – An approximately vertical or steeply inclined passageway from the ground surface to the underground level of the disposal region.

**sievert (Sv)** – SI unit of dosage from ionizing radiation (see dose). 1 Sv = 100 rem.

**single history (χ)** – χ is a single 10,000-yr WIPP history beginning at the time of decommissioning, i.e., one future disposal-system condition of interest. A single history consists of a defined sequence of features, events, and processes that could lead to radionuclide release to the accessible environment during a prescribed time period. The single-history space is isomorphic to the parameter space, D.

**site** – As used in this report, the "site" is the general location of the controlled area (the disposal system, including the land surface directly above it). The term "site" also includes any important features surrounding the controlled area (e.g., "site characterization"). Except for the latter addition, this report's definition of site is most similar to the regulatory definition in 10 CFR 60.2: "the location of the controlled area." It is roughly equivalent to the regulatory definition of "site" in 40 CFR 191.02, provided "effective control" is loosely defined (e.g., as simply land use or ownership records): "an area contained within the boundary of a location under the effective control of persons possessing or using radioactive waste that are involved in any activity, operation, or process covered by this Subpart."

**site-specific model** – See applied model.

**software** – A set of computer operations specified in any language that can be translated unambiguously into machine language. Types of software include computer codes and operating system procedural files.

**source term** – The kinds and amounts of radionuclides that make up the source of a potential release of radioactivity. For the performance assessment, the source term model calculates the sum of the quantities of the important radionuclides in the WIPP inventory that will be mobilized for possible transport to the accessible environment, and the rates at which these radionuclides will be mobilized.
spallings – Material that surround the eroded boreholes that may be broken away by the action of waste-generated gases escaping to the lower-pressure borehole; not included in the 1990, 1991, or 1992 PA calculations.

spent nuclear fuel (SNF) or spent fuel – "... fuel that has been withdrawn from a nuclear reactor following irradiation, the constituent elements of which have not been separated by reprocessing" (NWPA, 1982). Spent fuel can include intact and failed fuel assemblies, consolidated fuel rods, non-fuel components that are a part of a fuel assembly (such as neutron sources, instrumentation, and fuel channels). Although spent nuclear fuel has fissionable $^{235}$U, it contains too many radionuclides (primarily short-lived) that adsorb neutrons from the fission process for it to be usefully left in the reactor. Because of spent nuclear fuel's high value, some countries choose to recycle it (recycling becomes more attractive after the short-lived fission products have decayed away). It is also designated separately from other high-level and transuranic wastes in the U.S. Environmental Protection Agency's standard on disposal of radioactive wastes, 40 CFR 191.

stakeholder – A person, group, or agency who is not a customer, but who nevertheless has a keen interest in a product or service, such as the WIPP, and the recognized right to impact the process.

stochastic simulations – Modeling simulations that involve uncertain parameters for the features, events, and process of the system and thus produce a distribution and/or measures of the distribution of results (see also deterministic simulations).

summary scenario – A retained scenario from the set of plausible histories of the disposal system. The summary scenario is the result of the scenario screening procedure and is a subdivision of the scenario space, which is isomorphic with the parameter space.

thorium (Th) – A radionuclide having an atomic number of 90. Although not TRU, $^{232}$Th is an alpha emitter (half-life is 14 billion years) and exists in finite amounts in some TRU waste at Hanford, Idaho Lab, and Oak Ridge. Thorium is naturally occurring and contributes to background radiation at some sites (e.g., Idaho Lab).

transmissivity – The rate at which water, driven by a unit hydraulic gradient, is transmitted through a unit depth of aquifer. It is the hydraulic conductivity of the aquifer times its depth.

transuranic (TRU) waste – Transuranic waste is contaminated with transuranic radionuclides (atomic number greater than 92) emitting a radiation and having a half-life greater than 20 years and an activity greater than 100 nCi per gram of waste. Transuranic waste is also termed Alpha-Bearing Waste in some countries.

tsunami – A long wavelength surface gravity sea wave produced by submarine earth movement or volcanic eruption.

uncertain parameter – An imprecisely known parameter, one that cannot be assigned a single, universally accepted value.

uncertainty analysis – An analytic or numerical technique to evaluate how important the uncertainties of a parameter are (i.e., how likely it is to vary) in explaining uncertainty in the predictions. For example, the results of a model may be very sensitive to varying a parameter, but if the parameter's value is precisely known, the parameter is not important to producing any uncertainty in the prediction.

uncertainty propagation – Methods for propagating the uncertainty in parameters of a model, through the model, to calculate the uncertainty in the predictions. Uncertainty propagation is an important aspect of stochastic simulation.

underground facility – The underground structure including openings and backfill materials, but excluding shafts, boreholes, and their seals (10 CFR 60.2).

undisturbed (base-case) performance – Performance of the disposal system, including consideration of uncertainties in predicted behavior, if the disposal system is "... not disrupted by human intrusion or the occurrence of unlikely natural events." (40 CFR 191.12)

uranium (U) – A naturally slightly radioactive element with the atomic number of 92 (number of protons in the nucleus) and an atomic weight of approximately 238. The two principal naturally occurring isotopes are the fissionable $^{235}$U (0.7 percent of natural uranium and half life of $\sim7 \times 10^8$ yr) and
validation — The process of making valid by confirming, corroborating, substantiating, or supporting, where valid means of good authority, well founded, sound and to the point, and applicable to the subject or circumstances against which few objections can be fairly brought.

validation of an (applied) model — The process of validating through sufficient testing (subjective) using system-specific observed data that a conceptual model and the corresponding mathematical and computational models explain a system with sufficient accuracy (subjective), consistent with the purpose of the model. In other words, model validation is the process of confirming that the applied model is solving the appropriate idealization of the system (correct applied model produced). Model validation is an ongoing process.

verification of a (computational) model — The process of verifying that a computational model appropriately solves and implements the mathematical model. In other words, model verification is the process of illustrating that the mathematical model is being solved appropriately (computational model correctly produced). Often the computational model is implemented as a code; thus, verification of the computational model is closely connected to verification of software. Once a computational model is verified, the assumptions of the conceptual model underlying the mathematical and computational model (the applied model) should be validated using system-specific data.

verification of software — The process of illustrating through sufficient (subjective) testing that the software satisfactorily performs its stated capabilities (subjective) and providing a point of reference for future modifications. The extent to which the software can be tested is determined by its complexity.

waste form — The physical and chemical form of the waste after any specific treatment (none for the WIPP) just prior to being placed in the handling container.

waste package or waste emplacement package (WEP) — According to 10 CFR 60.2, the waste package is "the waste form and any containers, shielding, packing, and other absorbent materials immediately surrounding an individual waste container." Thus, the waste package contains all components that enclose the waste form out to the host rock. The waste package is defined as a unit as a convenience for subsystem modelers; also 10 CFR 60.113(b) places release limits on this unit.

waste parcel (WP) — The waste form, any internal backfill (none for the WIPP), handling container, and any overpack disposal containers (none for the WIPP). This definition describes a unit that can be handled; it does not include backfill immediately surrounding the waste panel.
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